



Koninklijk Nederlands  
Meteorologisch Instituut  
*Ministerie van Verkeer en Waterstaat*

Operational use of high  
resolution observations for  
very short term numerical  
weather forecasting

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Sibbo vd Veen (KNMI)  
Magnus Lindskog (SMHI)  
Martin Stengel (DWD)



# Very short term numerical weather forecasting

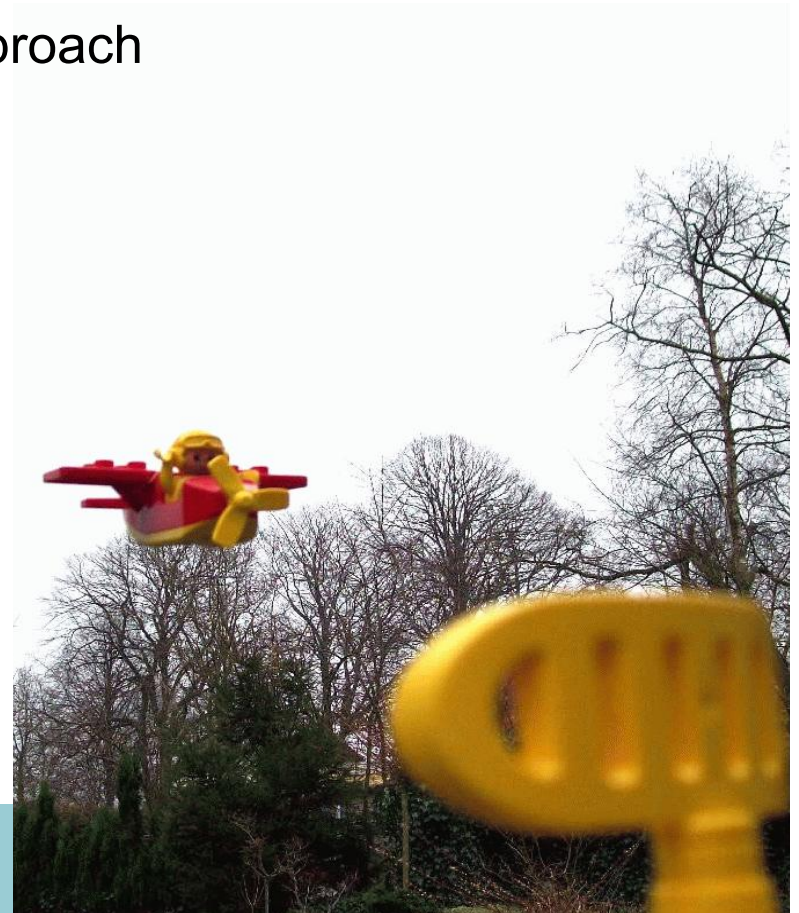


Project initiated by:

Amsterdam Schiphol Airport and Air Traffic Control, The Netherlands

Research to support Continuous Descent Approach

- Environment (fuel/noise)
- Efficiency Amsterdam Schiphol Airport
- Prototype “Expected touchdown time”
  - > Meteorological Input
    - » Mode-S
    - » NWP Model
  - > Improved prediction
    - » Landing time estimates
    - » Wind forecast

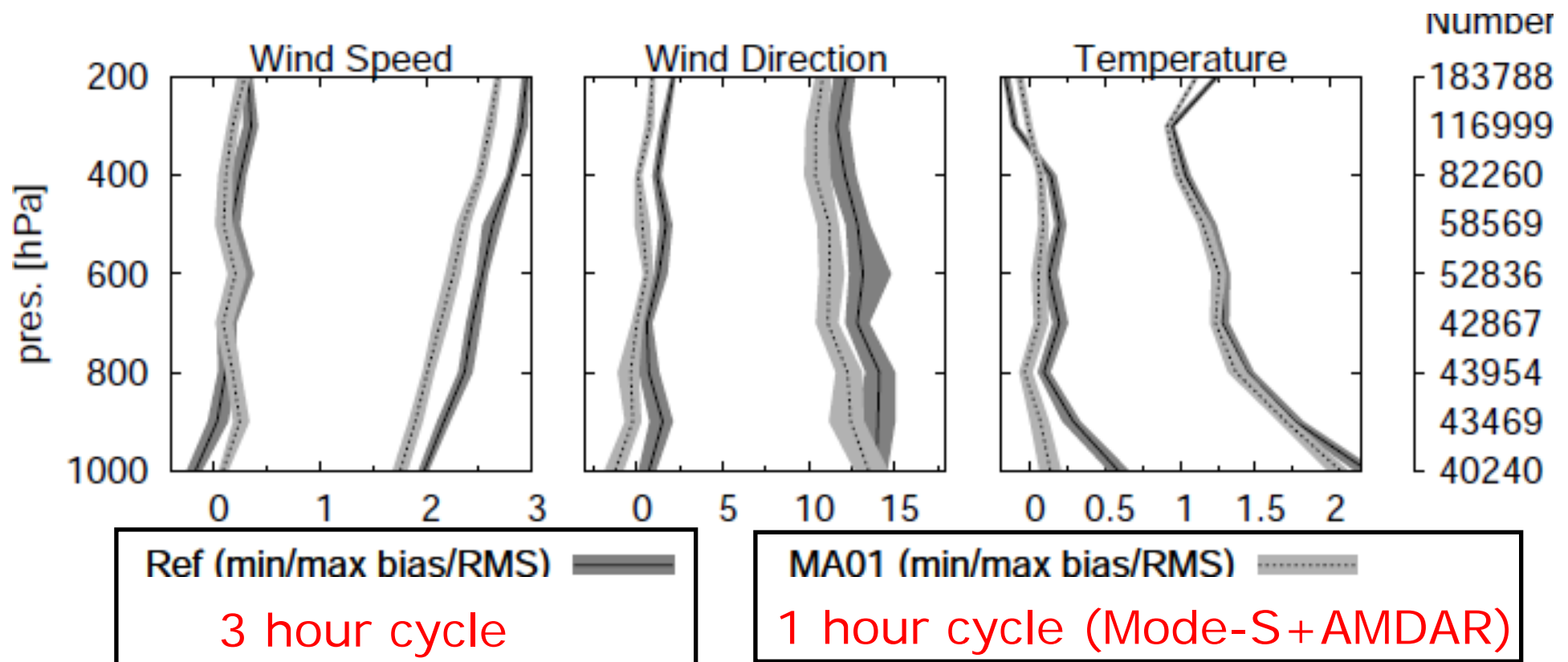


# Real-time Forecast skill



At observation time compared with available forecast

5% reduction in wind speed RMS



# Mode-S EHS observations (Enhanced Surveillance)

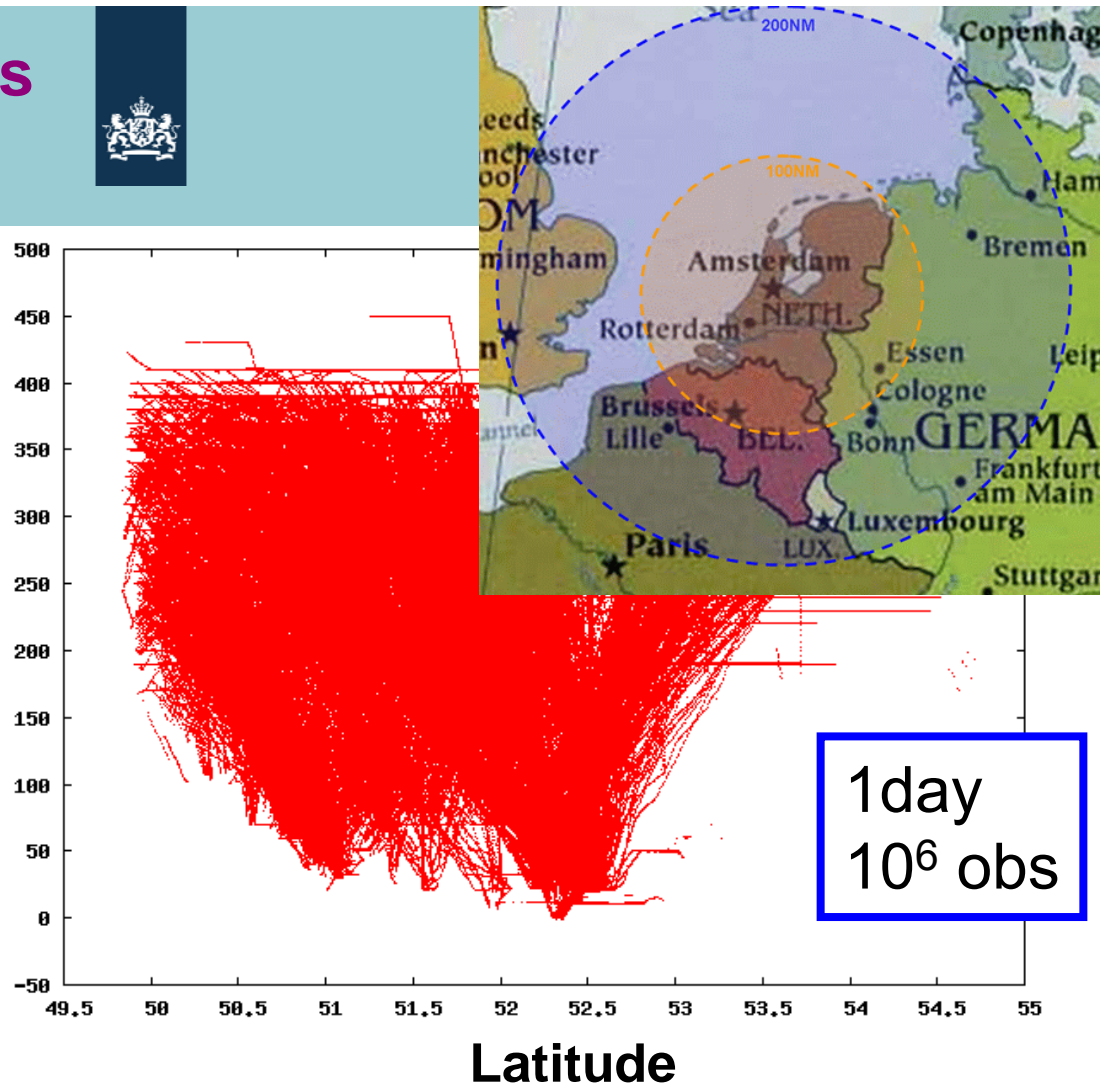
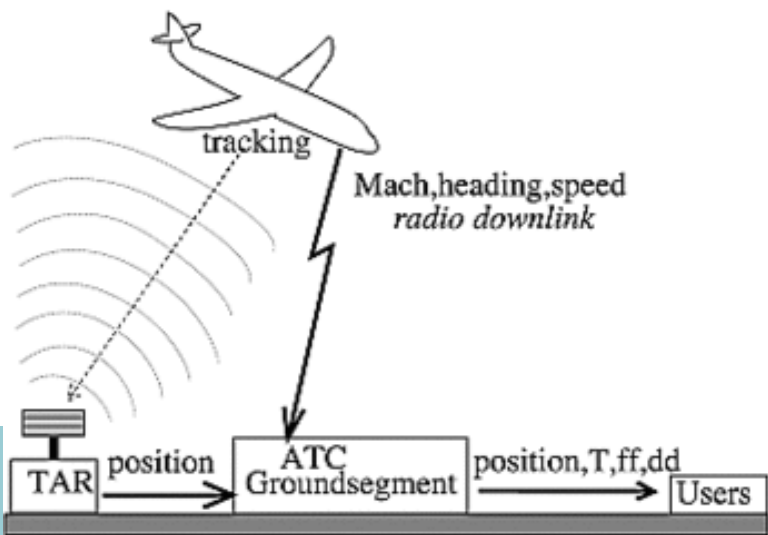


ATC-Radar interrogates all aircraft

Aircraft replies with:

- Identity
- Flightlevel
- Airspeed/direction
- Mach number

All aircraft/every 4.2 seconds



Wind observation similar to AMDAR  
Temperature slightly worse.  
After calibration and correction

# Numerical Weather Prediction Models

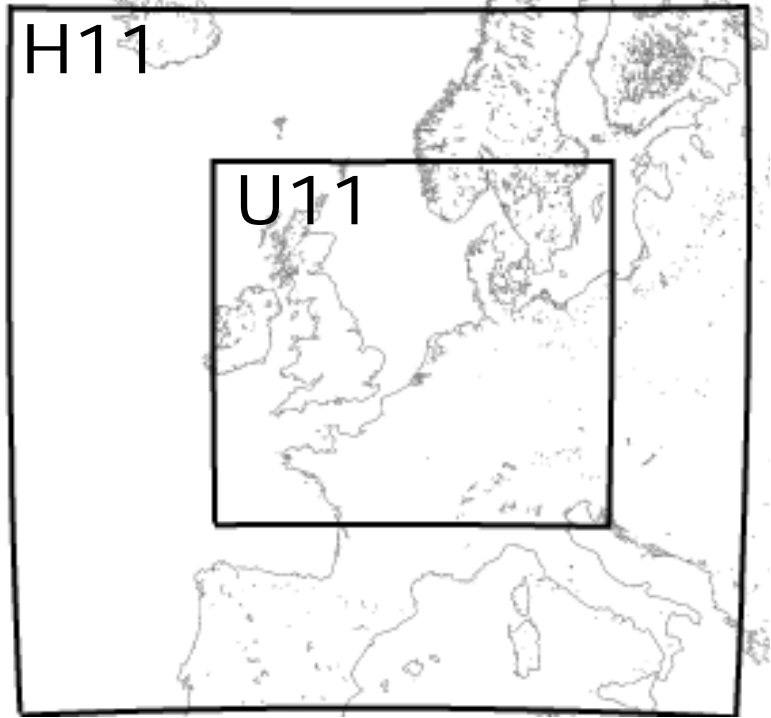


## HIRLAM

- 11 km Resolution (U11)
- Observation cut-off time : 10 minutes
- 9 hours forecast
- Hourly 3DVAR Assimilation: **p,u,v,T,q**
- Operational (U11)
  - > Synoptic (land, ship, buoy)
  - > AMDAR/Mode-S
  - > Groundbased GNSS
  - > Radar radial winds (NL)
- Simultaneous test (pre-operational)
  - > MSG clouds/ceilometer (initialization)
  - > MSG Seviri (ch 6.2,7.3,13.4)
  - > AMSU-A

p  
u,v,T  
≈ q  
≈ u/v  
≈ q,T  
≈ q,T  
≈ q,T

Operational (H11)  
3 hour 3DVAR  
cycle: Synoptic  
(land, ship, buoy)  
radiosonde AMDAR



# Assimilation of GNSS and radar radial winds



## Radar radial winds

Lowest elevations have an unambiguous velocity of 24 m/s

Dealiasing using higher elevations

Thinning to 20x20 km boxes

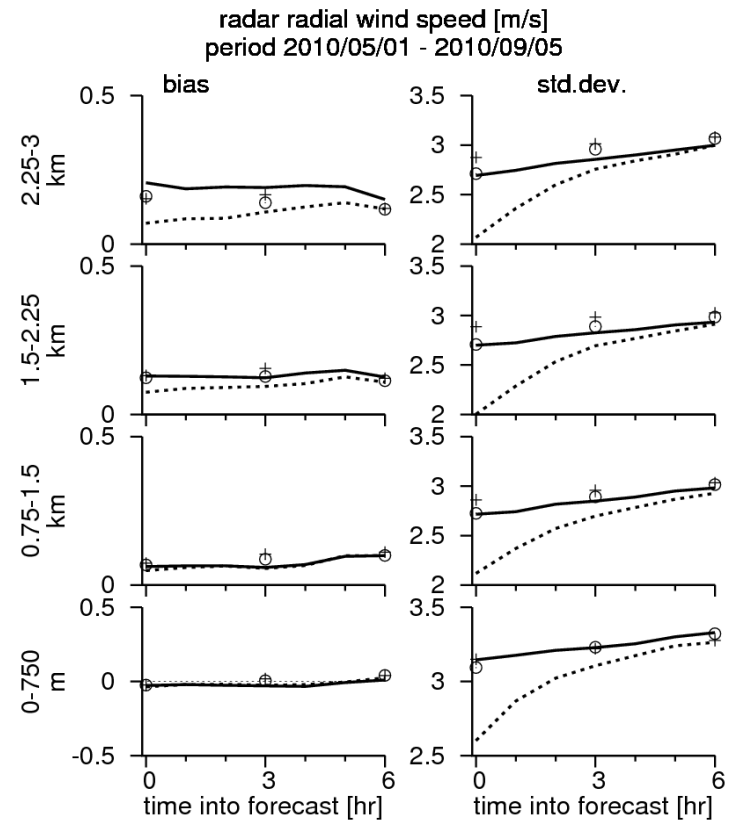
QC checks

## GNSS ZTD observations

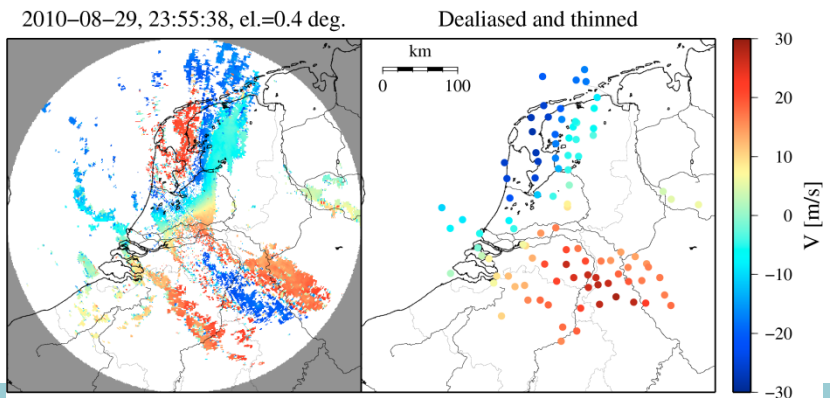
Processing of within 5 minutes after observation time



- ▲ Kadaster (the Netherlands)
- ★ Ordnance Survey (Great Britain)
- ▽ NTRIP (BKG, Germany)



H11 + U11+GNSS —  
H11+GNSS ○ U11+GNSS+RAD ·····



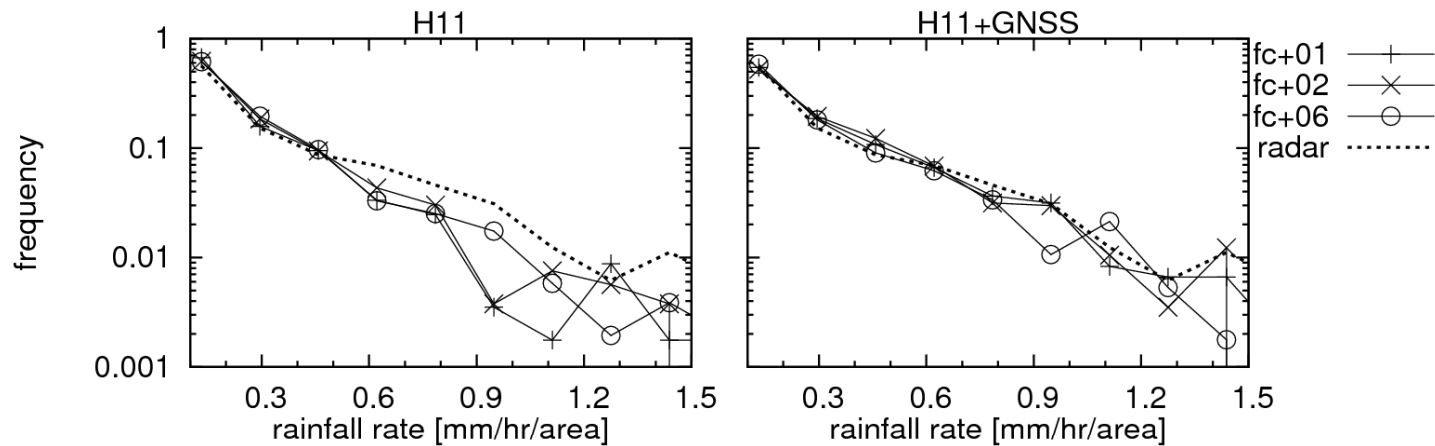
DeHaan, QJRMS, 2012 revised

# Assimilation of GNSS and radar radial winds

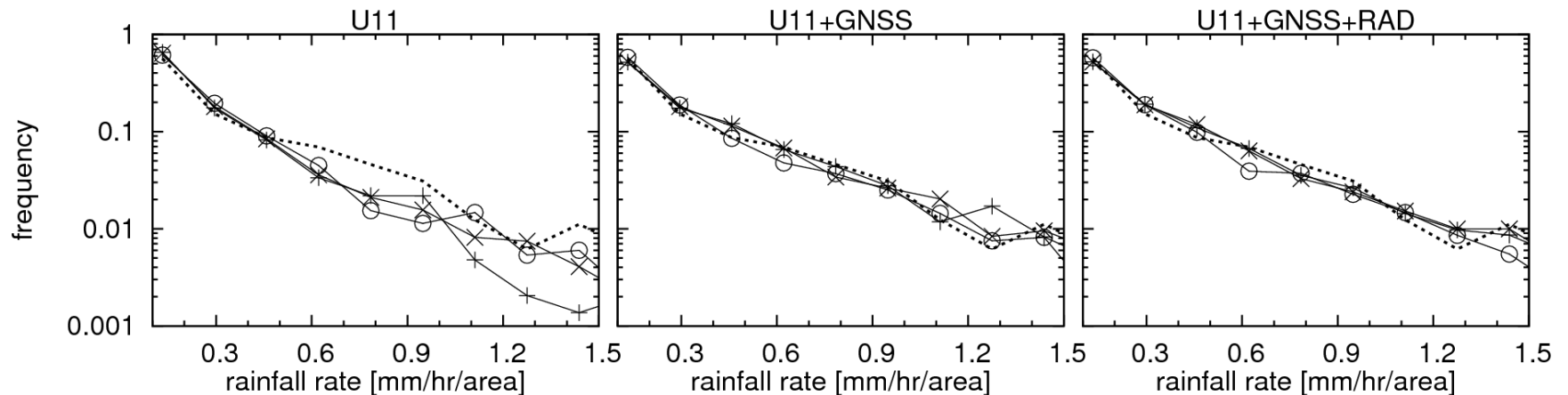


Hourly Rainfall Frequency Distribution (2010/05/01 - 2010/09/05)

3 hour cycle



1 hour cycle



# Mixing cloud information in hourly update

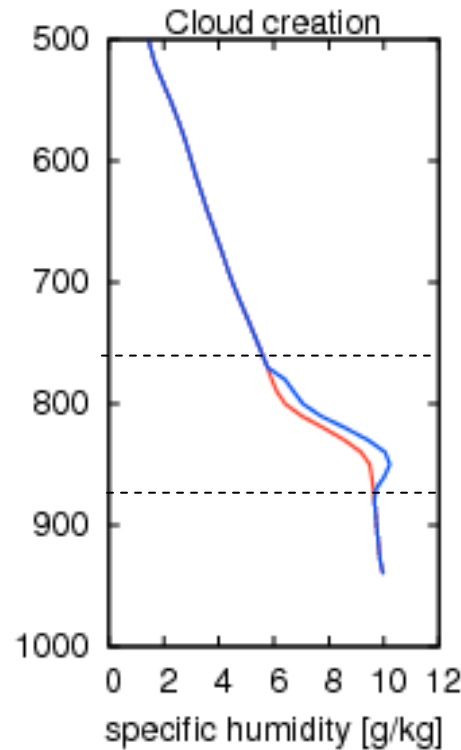


Temperature and specific humidity adjustment  
after digital filtering step

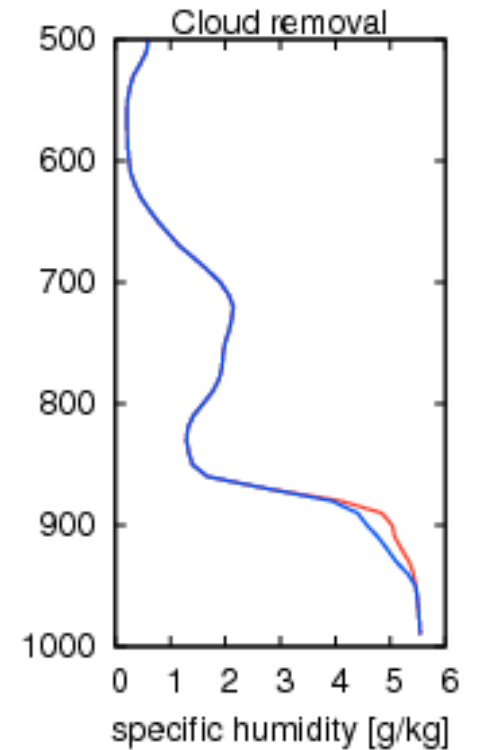
Input:

From the NWPSAF

- Cloud Cover
- Cloud Top  
Temperature
- SYNOP Cloud base  
height



Initial profile —



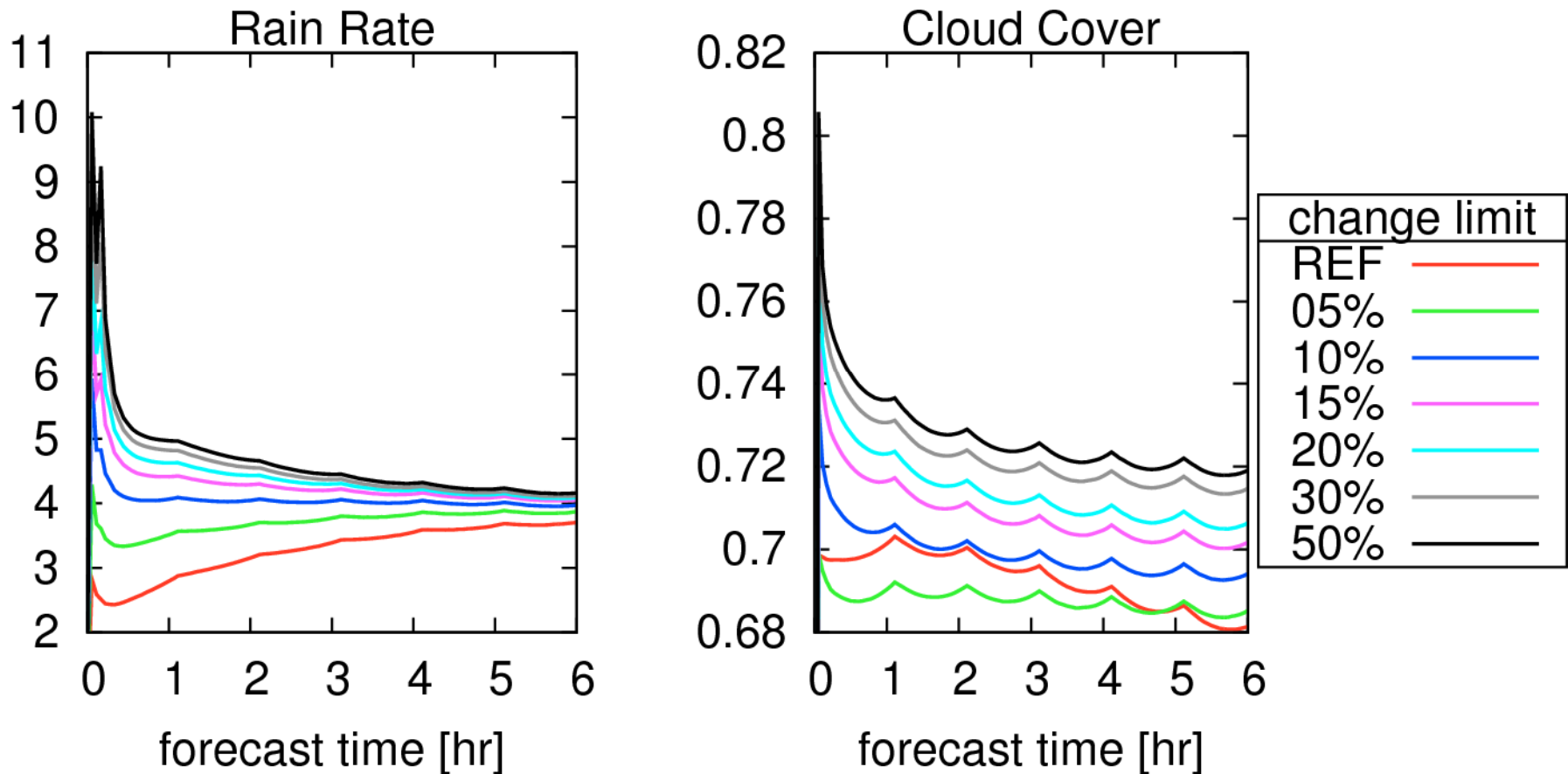
Adjusted profile —



# Effect of initialization on spinup



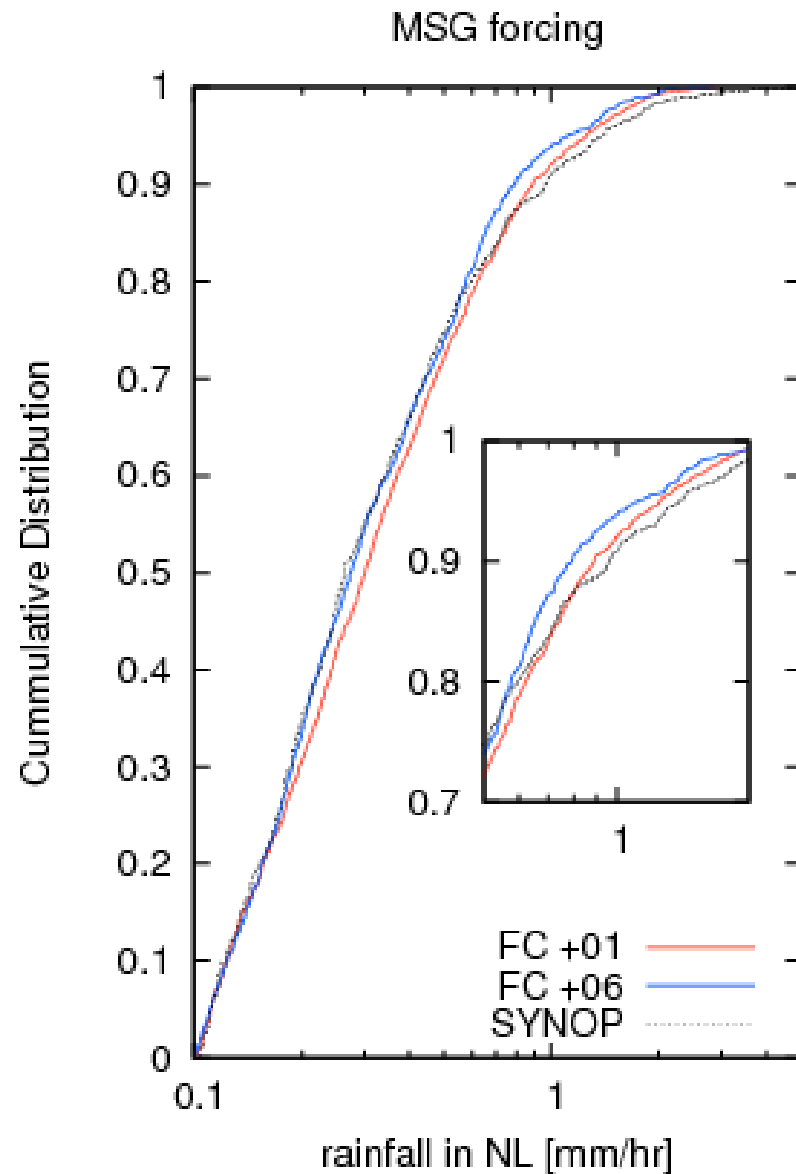
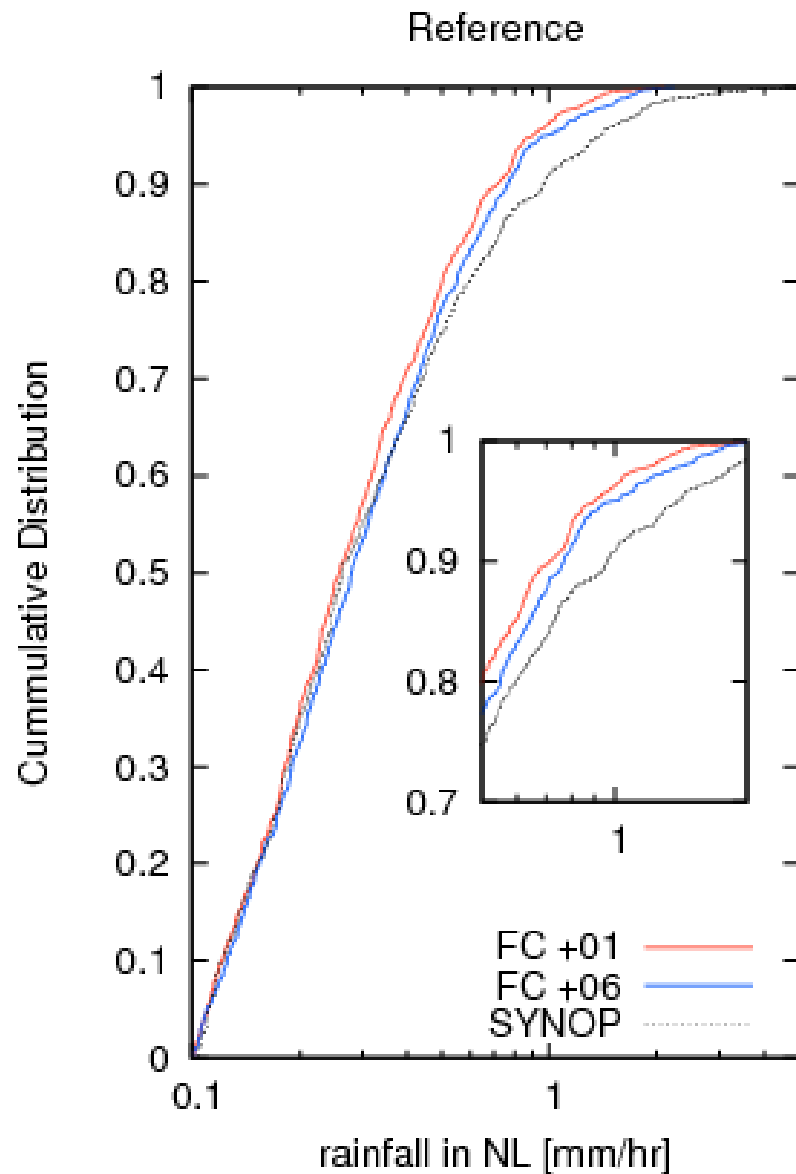
Tests with different change limits in change of  $q$   
6 days: 144 runs



**Maximum change in  $q$  is set to 10%**

deHaan and vdVeen, in preparation

# Impact on rainfall rate May 2011 – December 2011



# MSG/Seviri/ATOVS assimilation



AMSU-A

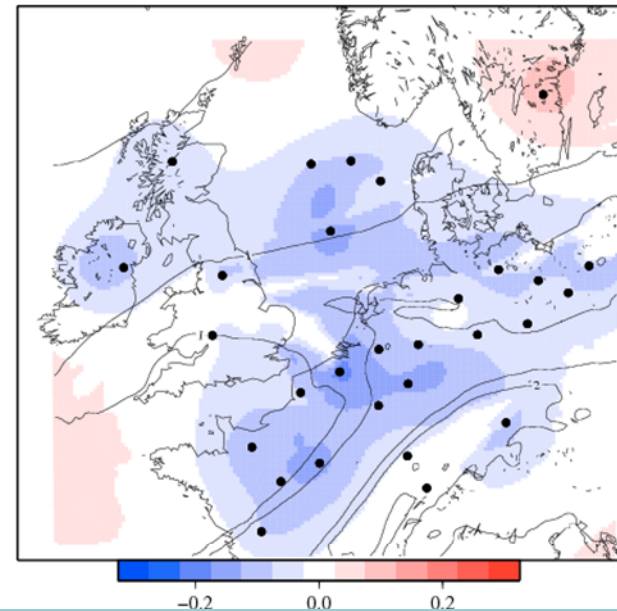


Period : 13 April 2012 – 12 May 2012

Pre-operational

- Use late/delayed observation
  - › Obs-cutoff time : 1h05m
  - › Radiosondes
  - › AMSU-A
- Real-time assimilation of
  - › Mode-S/AMDAR
  - › SYNOP pressure
  - › Radar radial velocities
  - › MSG initialization
  - › SEVIRI radiances (Stengel, QJRMS, 2009)

SEVIRI radiances



# Impact results



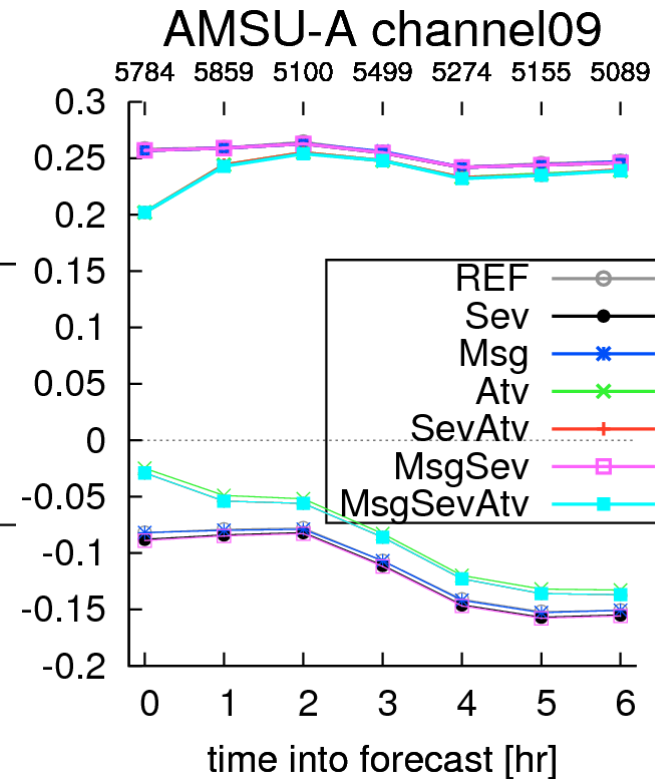
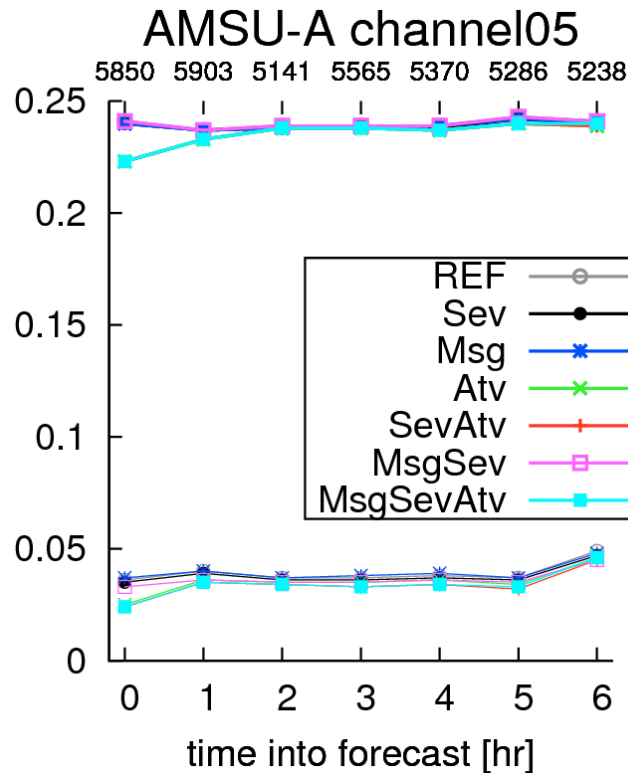
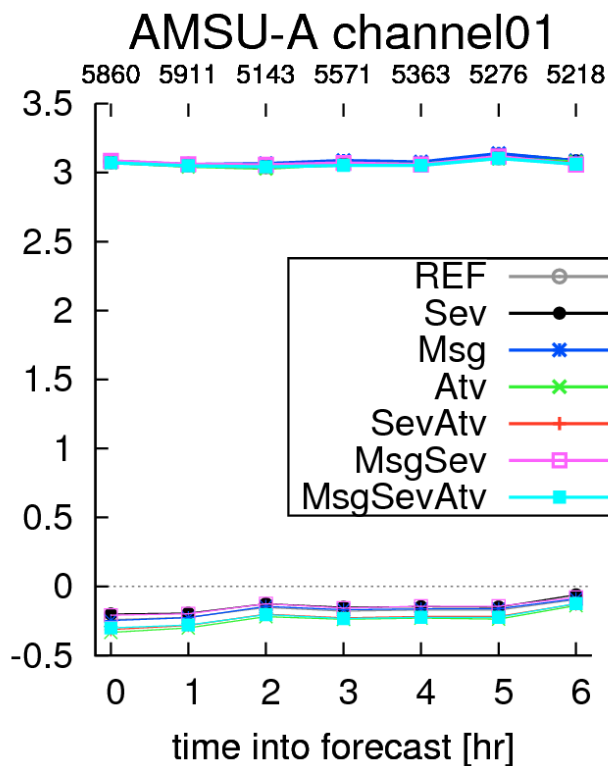
Comparing the AMSU-A observations against forecasts. (Polar orbit = irregular)

Standard bias corrections as derived for operational HIRLAM

Channels 01-04 show no signal

Channels 05-10 show better scores:

- Reduction in standard deviation in the first hour of the forecast
- Bias is present and may change with forecast time!





# Summary



- Hourly HIRLAM beneficial for ATC/CDA
  - > Improved wind forecasts for real-time usage
- Use of GNSS observations essential for humidity/rainfall forecast
- Use of radar radial winds improves the wind forecast (locally)
- MSG initialization
  - > improves cloud cover forecast even up to 6 hour
  - > Positive effects observed for rainfall rate
- Recycle of HIRLAM to use “delayed” observations
  - > Radiosondes
  - > AMSU-A
  - > Bias corrections for AMSU-A and SEVIRI seems necessary
- More observations from surrounding countries:
  - > radars (BEL/FRA/GER/UK)
  - > Mode-S observations



# Assimilation of radar radial winds



- Data in HDF5 format
- Using dealiasing from high elevation
  - large ambiguity (48m/s and 25m/s)
- Thinning to 20x20km boxes
  - median
  - number + standard deviation check

