

Development of the Upper Air Simulator (UAS) for the Calibration of Radiosondes

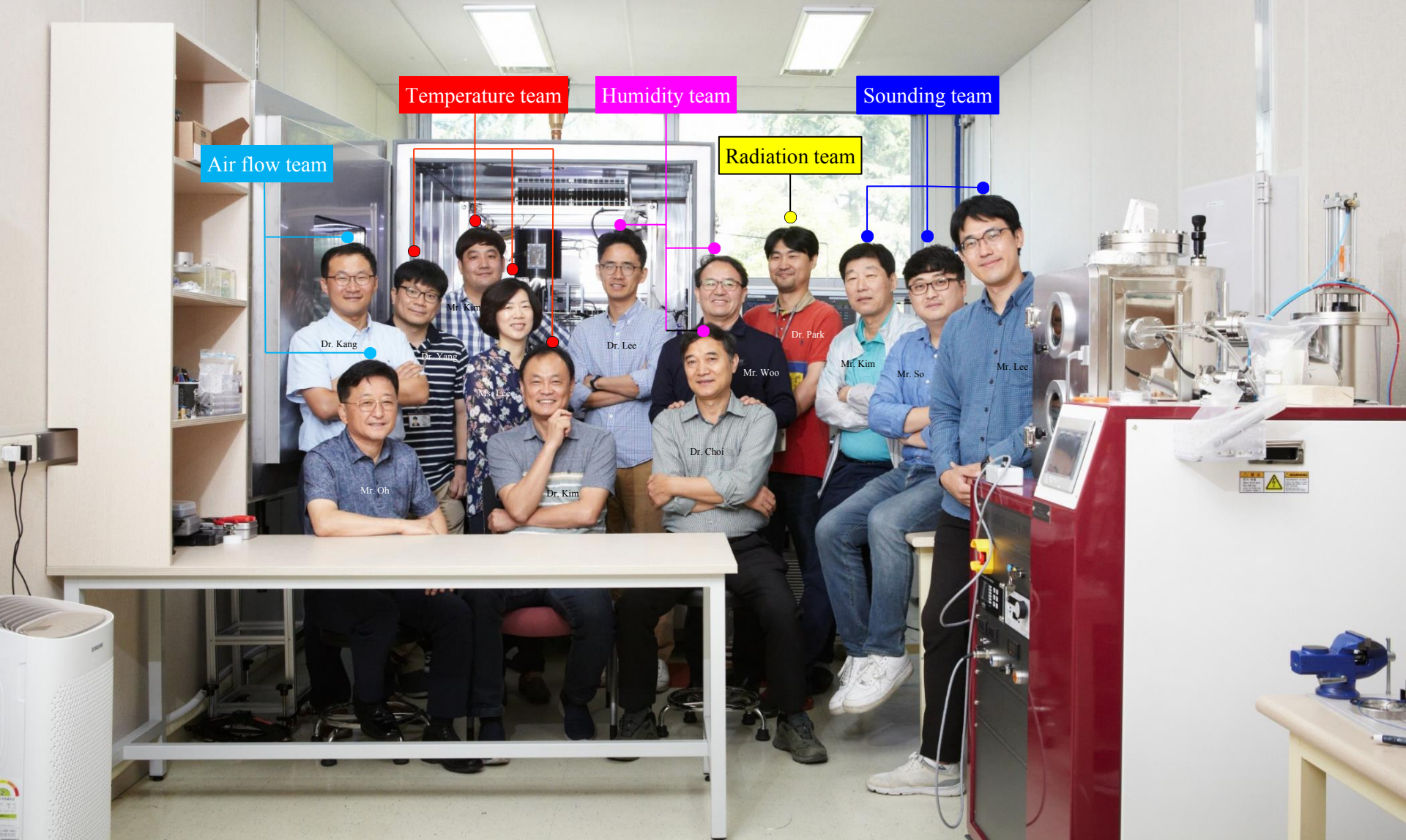
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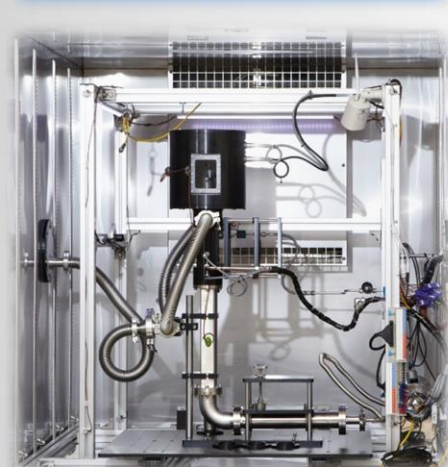
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II Design of Upper Air Simulator (UAS)

III Performances of UAS

IV Calibration of DTR and RS41

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Introduction

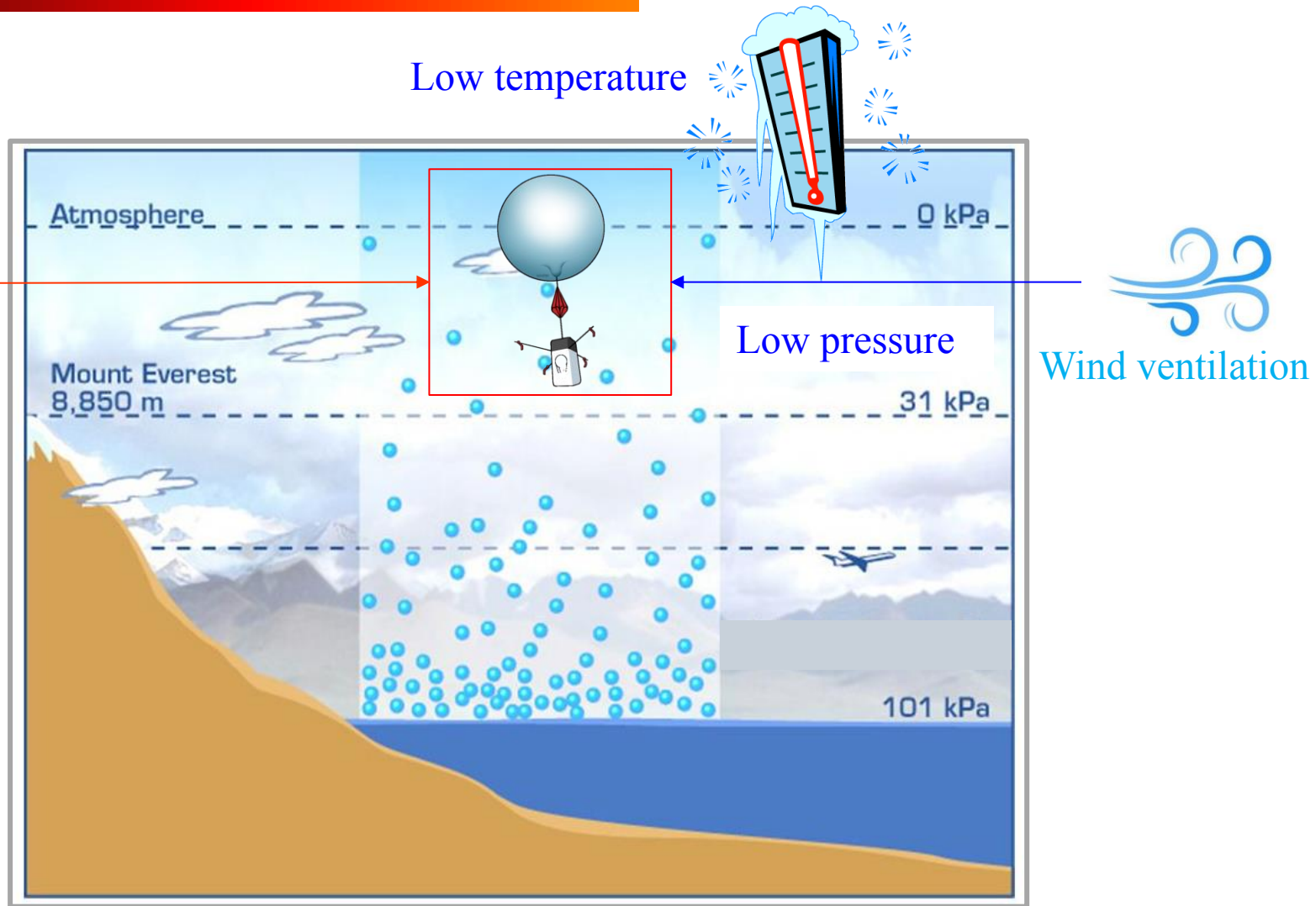
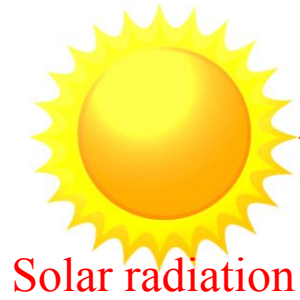


Radiosonde

- Crucially important instruments for **upper-air measurements** by WMO
 - ◆ Battery-powered telemetry instrument
 - ◆ Carried into atmosphere by a weather balloon
 - ◆ to measure **temperature, humidity**, pressure, altitude, geographical position, wind speed and direction, cosmic ray, etc
 - ◆ Operated at a radio frequency of 403 MHz ~ 1680 MHz
- **Calibration with high accuracy required.**



Radiosondes in upper air



Calibration of radiosonde

- In common, calibration is done at ground laboratory.
 - ◆ It cannot reflect the upper air conditions.
 - ◆ Radiation effects are the most important parameter.
 - It causes heating in daytime and cooling at nighttime.
 - Low-pressure and low-temperature increases solar heating effects.
 - Air ventilation decreases solar heating effects.
 - ◆ There is no combined system which can control all parameters together.
- For the precise calibration of radiosonde, upper air simulation system is required.

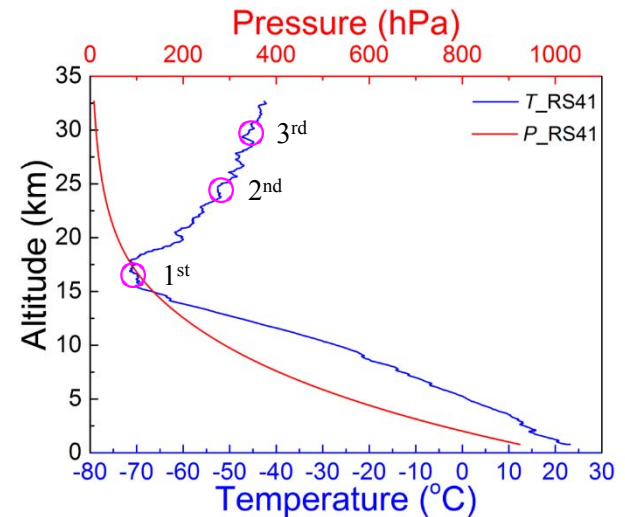
In this work

□ Upper air simulator (UAS) for radiosonde calibration is designed and constructed.

- ◆ Temperature from $-70\text{ }^{\circ}\text{C}$ to ambient
- ◆ Pressure range from 10 hPa to 1000 hPa
- ◆ Solar radiation to $1\ 500\ \text{W}/\text{m}^2$
- ◆ Wind ventilation up to 5 m/s
- ◆ Dew point from $-40\text{ }^{\circ}\text{Cdp}$ to $25\text{ }^{\circ}\text{Cdp}$

□ Temperature sensors of KRISS DTR and Vaisala RS41 tested at 3 points

- ◆ Ventilation about 5 m/s and irradiance about $1000\ \text{W}/\text{m}^2$
- ◆ 1st at about 15 km ($-70\text{ }^{\circ}\text{C}$, 100 hPa)
- ◆ 2nd at about 25 km ($-50\text{ }^{\circ}\text{C}$, 50 hPa)
- ◆ 3rd at about 30 km ($-40\text{ }^{\circ}\text{C}$, 10 hPa)



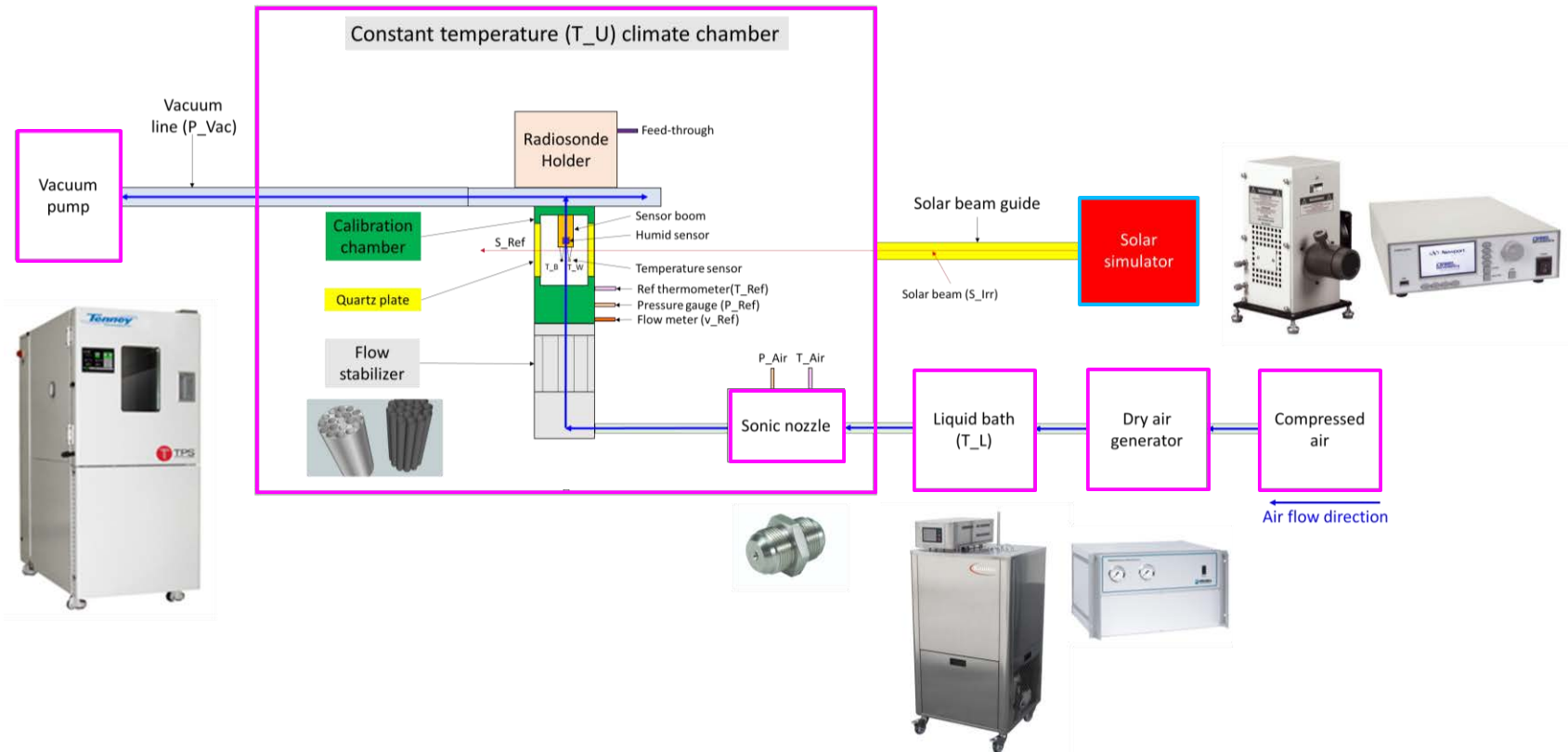
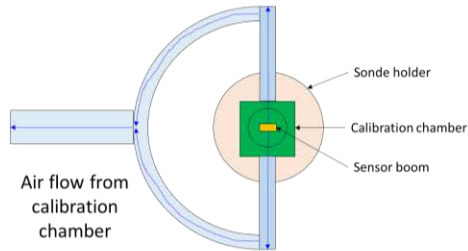
<Temperature profile on Aug. in Korea>



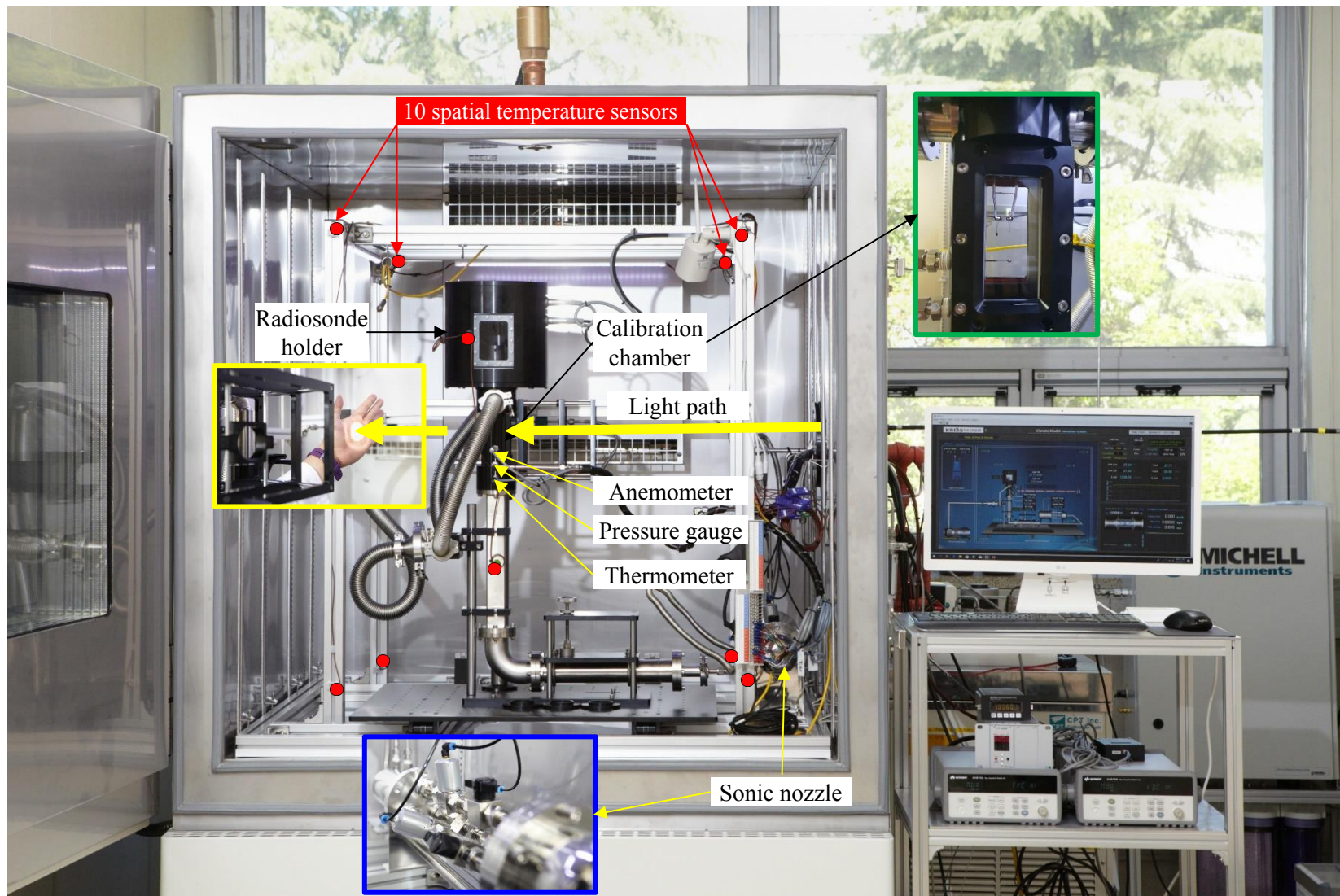
Design of UAS



Schematic design of UAS



Constructed UAS



Data acquisition software by Labview



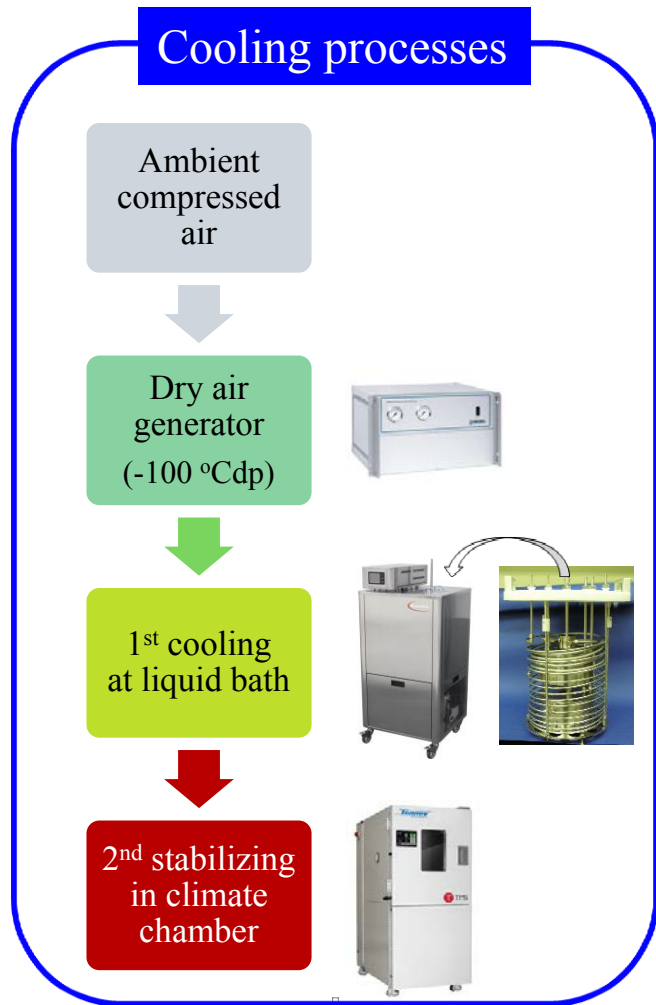


Performance of UAS

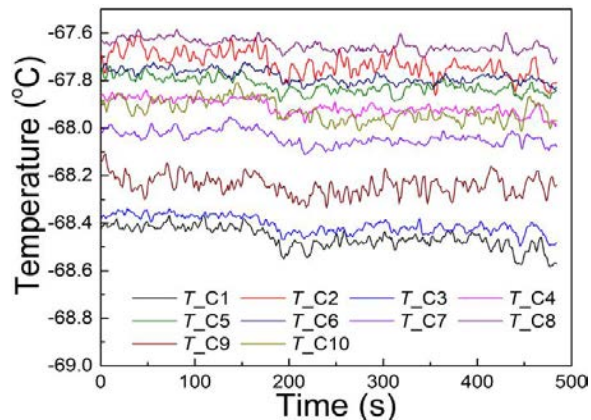


Air Temperature

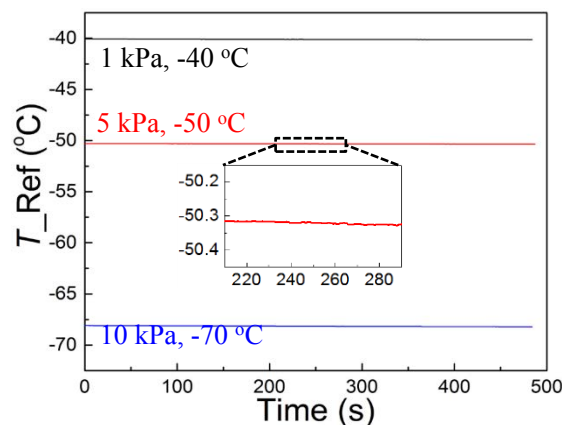
Cooling processes



Temperature stability inside chamber@-70 °C set



- Type E thermocouple
- Stability of ± 0.1 °C
- Gradient of ± 0.4 °C



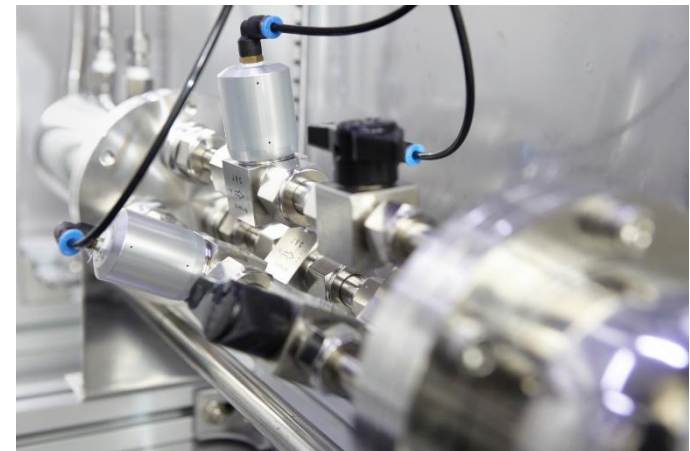
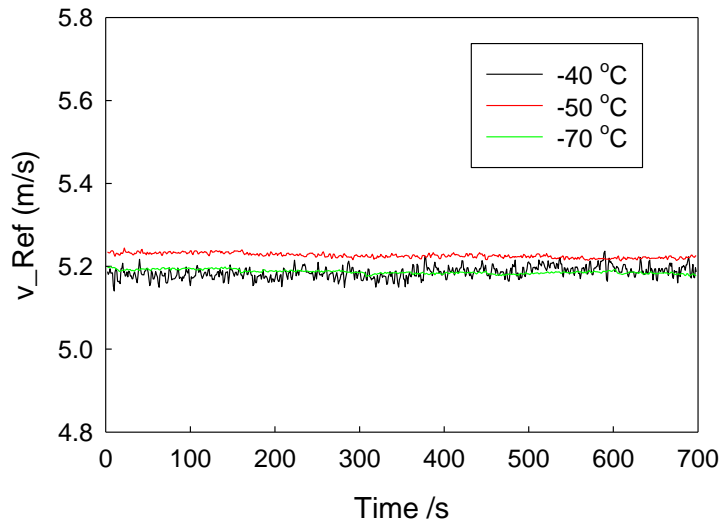
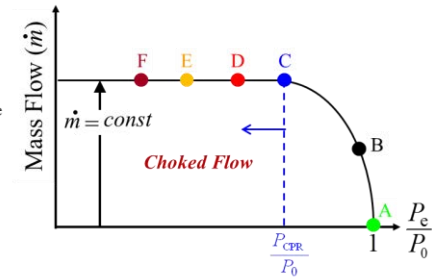
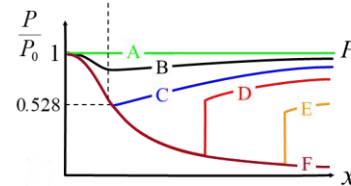
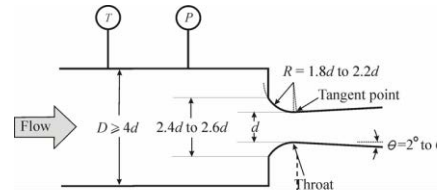
- Reference air temperature
- PT100 thermometer
 - Uncertainty of 50 mK ($k=2$)
 - **Stability of ± 0.01 °C**



Wind ventilation

□ Mass flow control using sonic nozzle

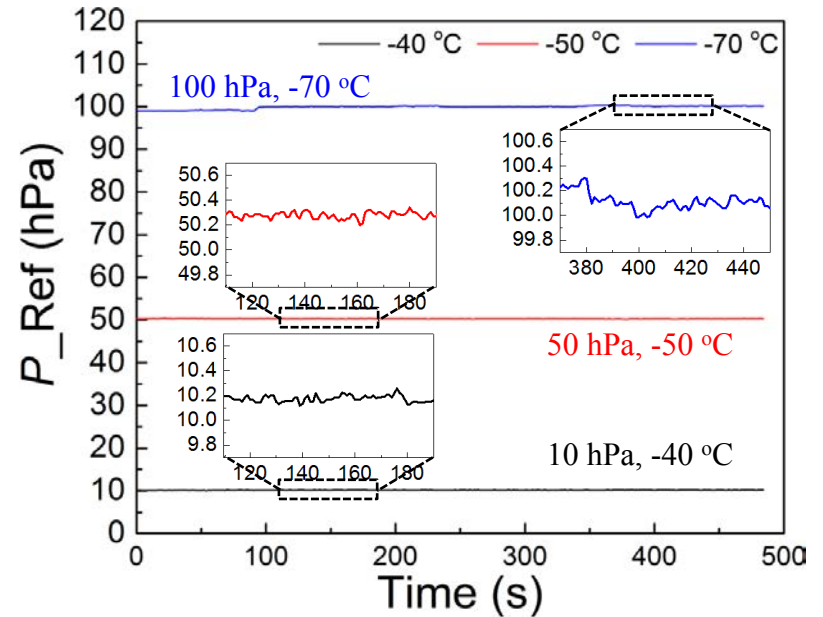
- ◆ Three set of nozzle diameter (d)
 - 0.4 mm for about (10 ~ 50)hPa
 - 1.12 mm for about (50 ~ 100)hPa
 - 3.2 mm for about (100 ~ 1 000)hPa
- ◆ Set accuracy of ± 0.05 m/s
- ◆ **Stability of ± 0.02 m/s**



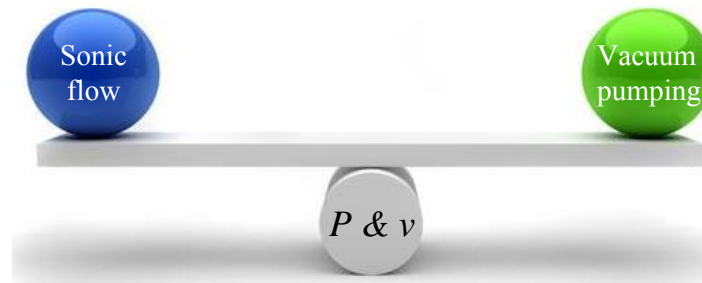
Pressure

□ Vacuum gauge

- ◆ INFICON CDG 020D
- ◆ (10 ~ 1000) torr
- ◆ 1 % of reading accuracy



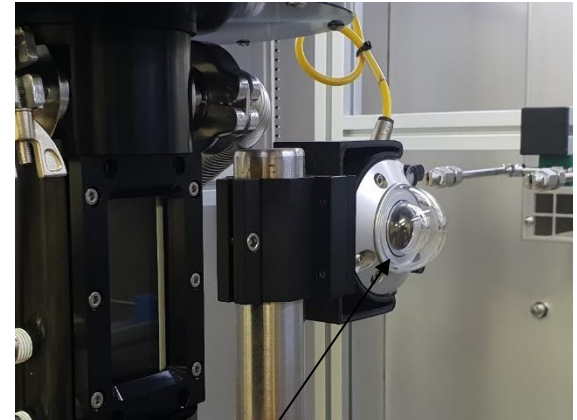
Stability of ± 0.1 hPa



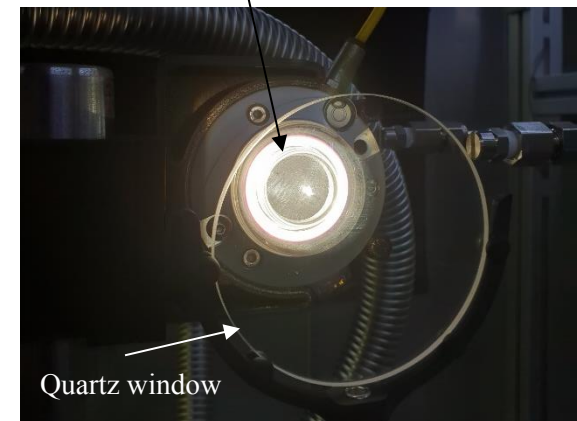
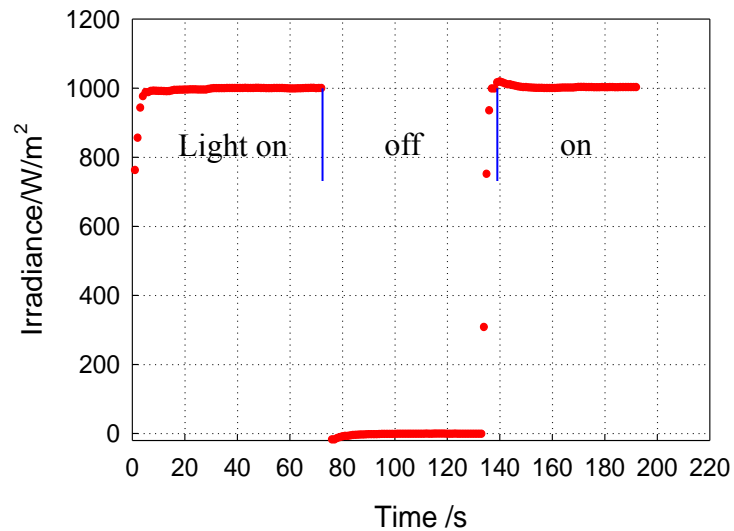
Solar Irradiance

☐ Solar simulator

- ◆ Newport Research Xe Arc Lamp
- ◆ Max. 1000 W with ozone-free Xe
- ◆ Tested at irradiance ($\sim 1000 \text{ W/m}^2$)
- ◆ **Stability of $\pm 1.5 \text{ W/m}^2$**



Reference pyranometer



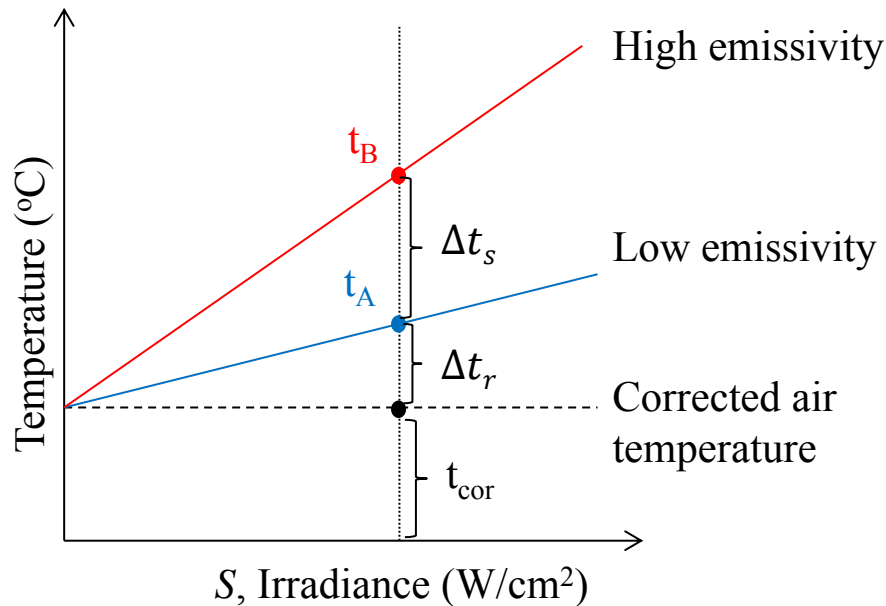
Quartz window



Calibration of DTR and RS41



DTR (Dual Thermistor Radiosonde)



- $t_B = \Delta t_s + \Delta t_r + t_{cor}$
- $t_{cor} = t_B - \Delta t_r - \Delta t_s$
- $t_B, \Delta t_s$: Can be measured during flight
- Δt_r : obtained by calibration

Related Articles

Meteorol. Appl. **23**: 691–697 (2016)
Meteorol. Appl. **25**: 49–55 (2018)
Meteorol. Appl. **25**: 209–216 (2018)
Meteorol. Appl. **25**: 283–291 (2018)
 Patent FI 127041 B
 Patent KR 1742906
 Patent KR 1787189
 Patent US 15/306,697

$$\Delta t_s = S \times f(T, P, v) \rightarrow S$$



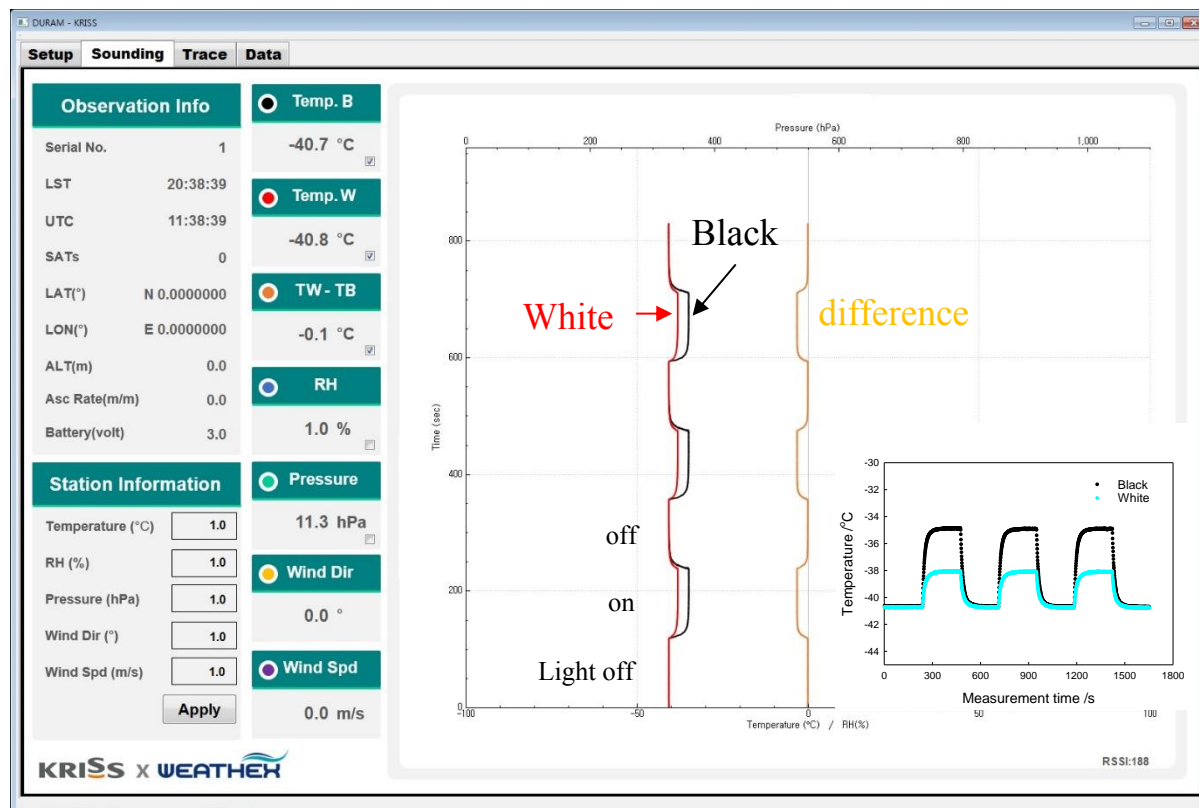
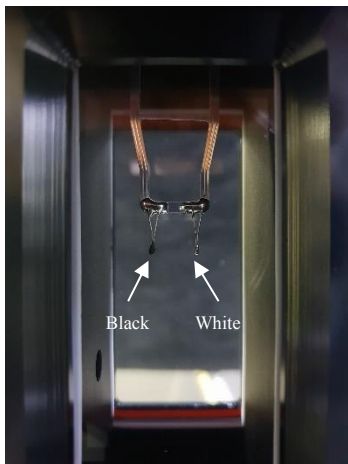
$$\Delta t_{cor} = S \times g(T, P, v) \rightarrow T_{cor}$$

Real time *in-situ* radiation correction technique

Setup of DTR

- DTR (Dual Thermistor Radiosonde) and DURAM sounding system
 - ◆ *In-situ* on sounding solar correction by measuring temperature differences between two thermistors having different emissivity (Black and White)

-40 °C set, 10 hPa, 5 m/s, 1 000 W/m²



Calibration results of DTR

Solar irradiance (S) = 1 000 W/m²

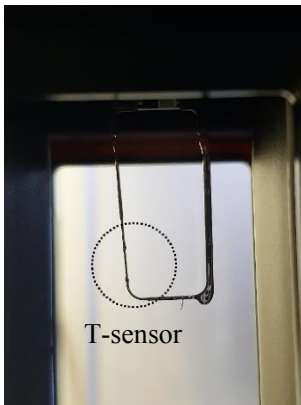
Height /km	Temperature $T_{ref}/^{\circ}\text{C}$	Pressure P/hPa	Air speed $v/\text{m/s}$	$T_{W_Before}/^{\circ}\text{C}$	$T_{W_After}/^{\circ}\text{C}$	$T_{B_Before}/^{\circ}\text{C}$	$T_{B_After}/^{\circ}\text{C}$	$\Delta T_{W_Before}/^{\circ}\text{C}$	$\Delta T_{W_Rad}/^{\circ}\text{C}$	$\Delta T_S/^{\circ}\text{C}$
15	-69.0	101.7	5.19	-70.6 ± 0.1	-69.1 ± 0.1	-70.3 ± 0.2	-66.7 ± 0.2	1.6	1.5	2.4
25	-50.5	50.5	5.22	-51.9 ± 0.1	-49.1 ± 0.1	-51.9 ± 0.1	-45.7 ± 0.1	1.4	2.8	3.4
30	-40.3	10.2	5.18	-40.7 ± 0.1	-38.1 ± 0.1	-40.7 ± 0.1	-34.9 ± 0.1	0.4	2.6	3.2

(ΔT (correction value) = reference temperature – measured temperature)

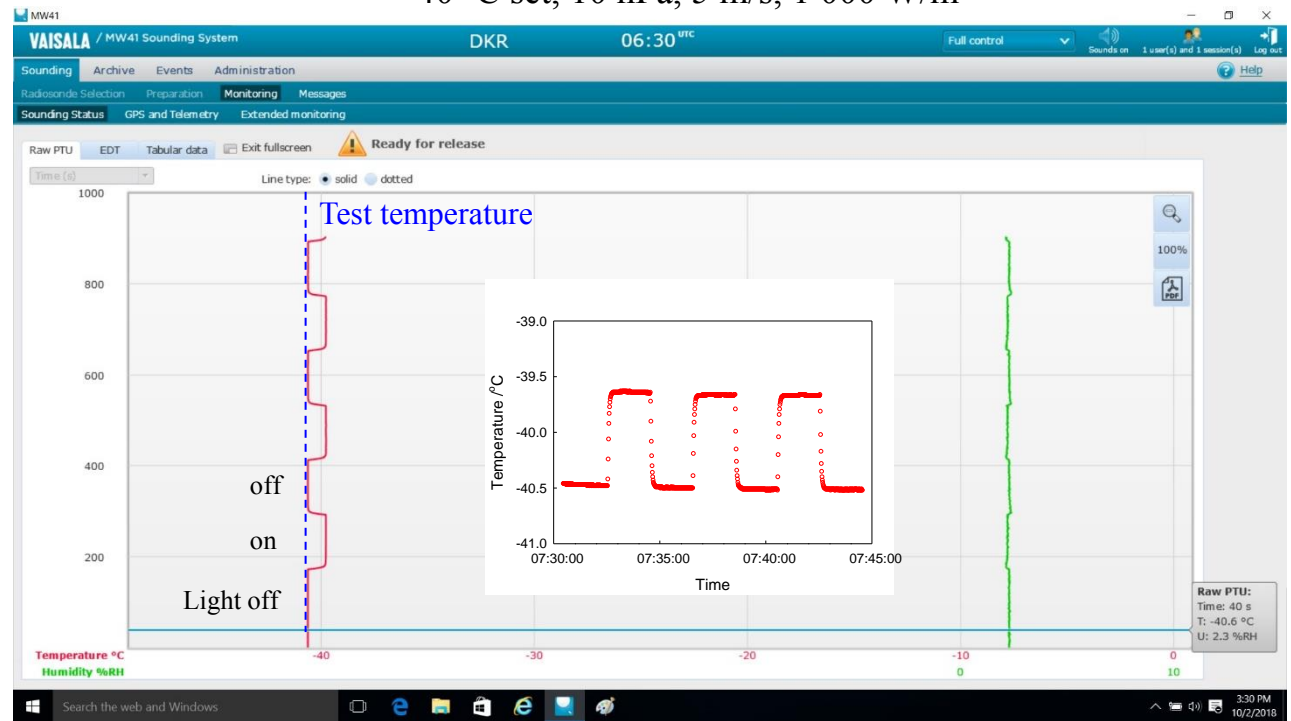
- DTR shows a large temperature rise by solar heating.
- Temperature differences between two thermistors are about 2 ~ 3 °C depending on air condition.
- From the relationship ΔT_S and other parameters (T, P, v, S), we can get the in-situ solar correction formula.

Setup of RS41

- Vaisala RS41 and MW41 sounding system
 - ◆ Well-known radiosonde with PT1000 Ω resistive temperature sensor



-40 °C set, 10 hPa, 5 m/s, 1 000 W/m²



Calibration results of RS41

Solar irradiance(S) = 1 000 W/m²

Height /km	Temperature $T_{ref}/^{\circ}C$	Pressure P/hPa	Air speed $v/m/s$	$T_{RS41_Before}/^{\circ}C$	$T_{RS41_After}/^{\circ}C$	$\Delta T_{Before}/^{\circ}C$	$\Delta T_{rad}/^{\circ}C$	$\Delta T_{cal}/^{\circ}C$
15	-68.5	99.2	5.18	-68.5 ± 0.1	-68.1 ± 0.1	0.0	0.4	0.4
25	-50.4	50.8	5.16	-50.4 ± 0.1	-49.5 ± 0.1	0.0	0.9	0.9
30	-40.5	10.2	5.19	-40.5 ± 0.1	-39.7 ± 0.1	0.0	0.8	0.8

(ΔT (correction value) = reference temperature – measured temperature)

- ❑ Temperature accuracy of RS41 is as good as same to the reference temperature.
- ❑ It is less affected by solar heating than thermistors.
- ❑ At higher altitude, solar correction value increases by about 2 times.



Summary



Success in UAS development

- We have developed the **upper air simulator** for the calibration of radiosondes.
 - ◆ Air temperature, humidity, pressure, wind ventilation and solar irradiance can be precisely controlled simultaneously.
 - ◆ **Sonic nozzle technique** to mimic upper air ventilation is the our best uniqueness.
- **Calibrations of DTR and Vaisala RS41** have been performed in remote mode.
 - ◆ Simulation of upper air at -70 °C (15 km, 100 hPa), -50 °C (25 km, 50 hPa) and -40 °C (30 km, 10 hPa) with ventilation speed of 5 m/s and solar irradiance of 1000 W/m²
 - ◆ Solar correction values with altitude are obtained with high measurement accuracy.
- Any radiosondes in market can be calibrated at various air conditions.
- Collaborations with other institutes or suppliers are always welcome.



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Further works

- ❑ Improvement of control accuracy of UAS including wind velocity profile measurements, rotation of sensor and control of incident beam area
- ❑ Calculation of calibration uncertainty and development of calibration procedures
- ❑ Improvement of measurement accuracy of DTR
- ❑ Development of accurate *in-situ* real time solar correction formula using DTR
- ❑ Sounding tests of DTR with formula

Thank you for your attention

And

Thank my team!

