

# CCTV based Video Analytics for Managing and Forecasting Impact of Weather

Hanseok Ko

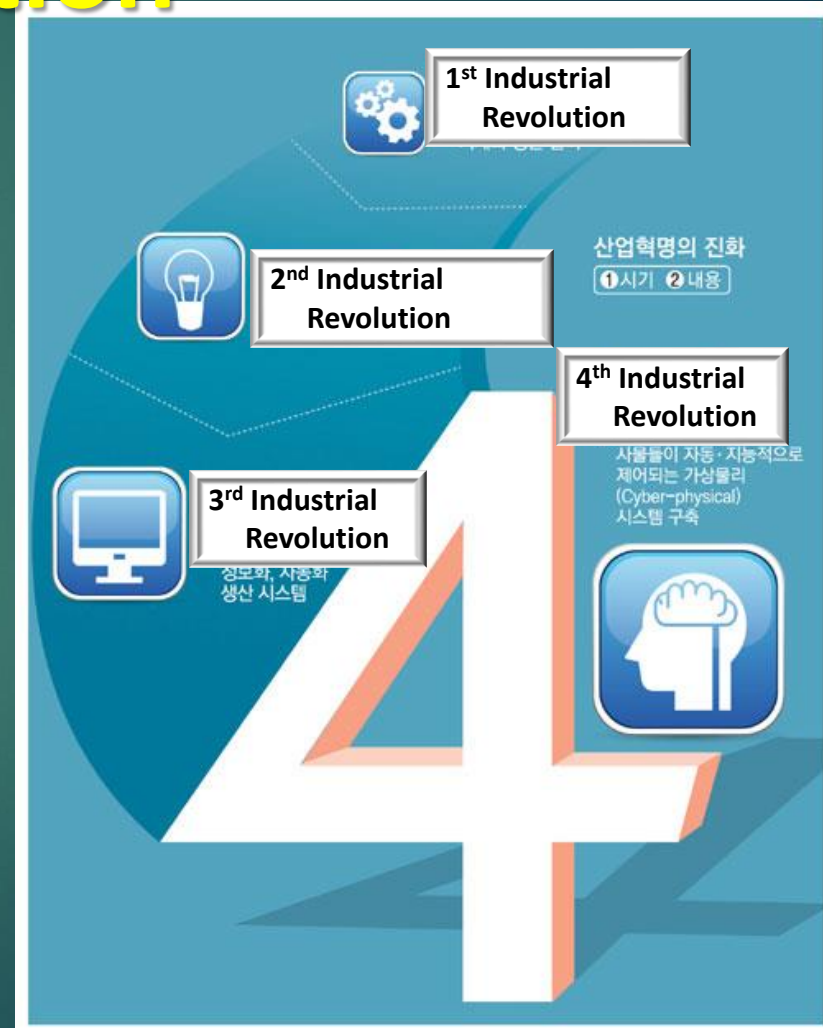
School of Electrical Engineering  
Big Data & AI Institute  
Korea University, Seoul

## 4<sup>th</sup> Industrial Revolution

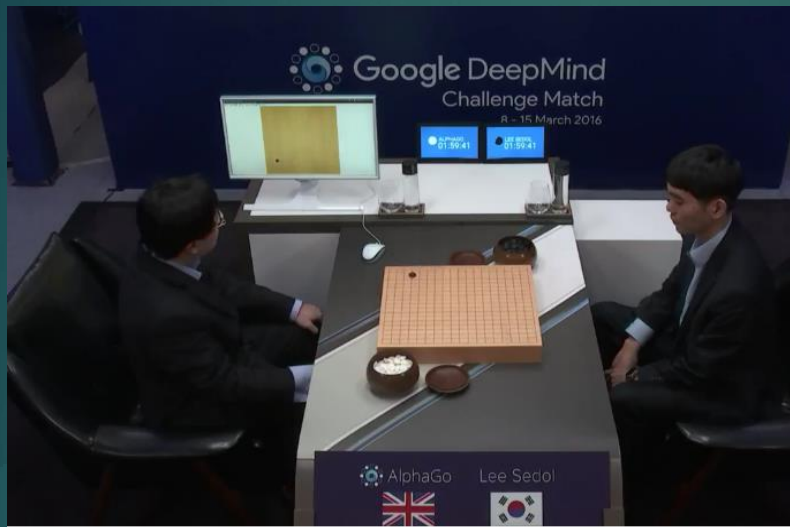
- AI
- Big Data Analytics



Chat-bot, Diagnostic, Weather Prediction



# Machine that can think like human



Alpha-Go vs. Sedoll LEE

4 vs. 1

2016.03

Deep Learning applications



Speech recognition  
(Jia Lei)



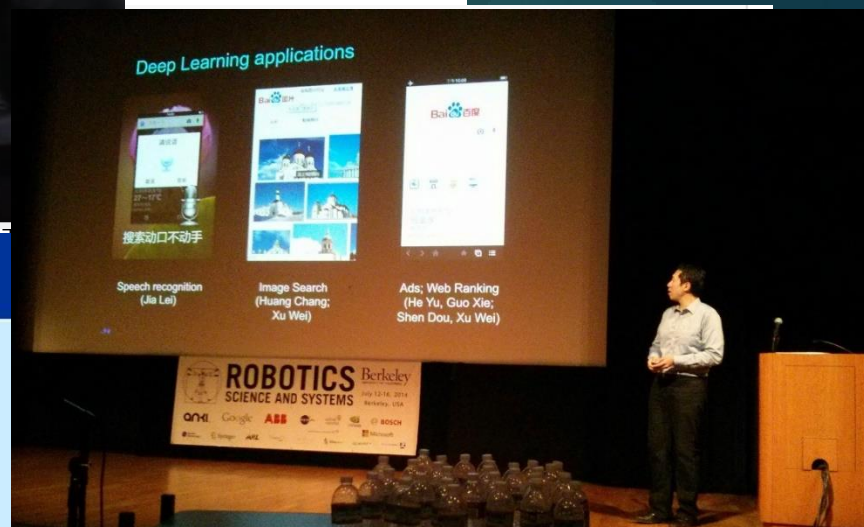
Image Search  
(Huang Chang;  
Xu Wei)



Ads; Web Ranking  
(He Yu, Guo Xie;  
Shen Dou, Xu Wei)



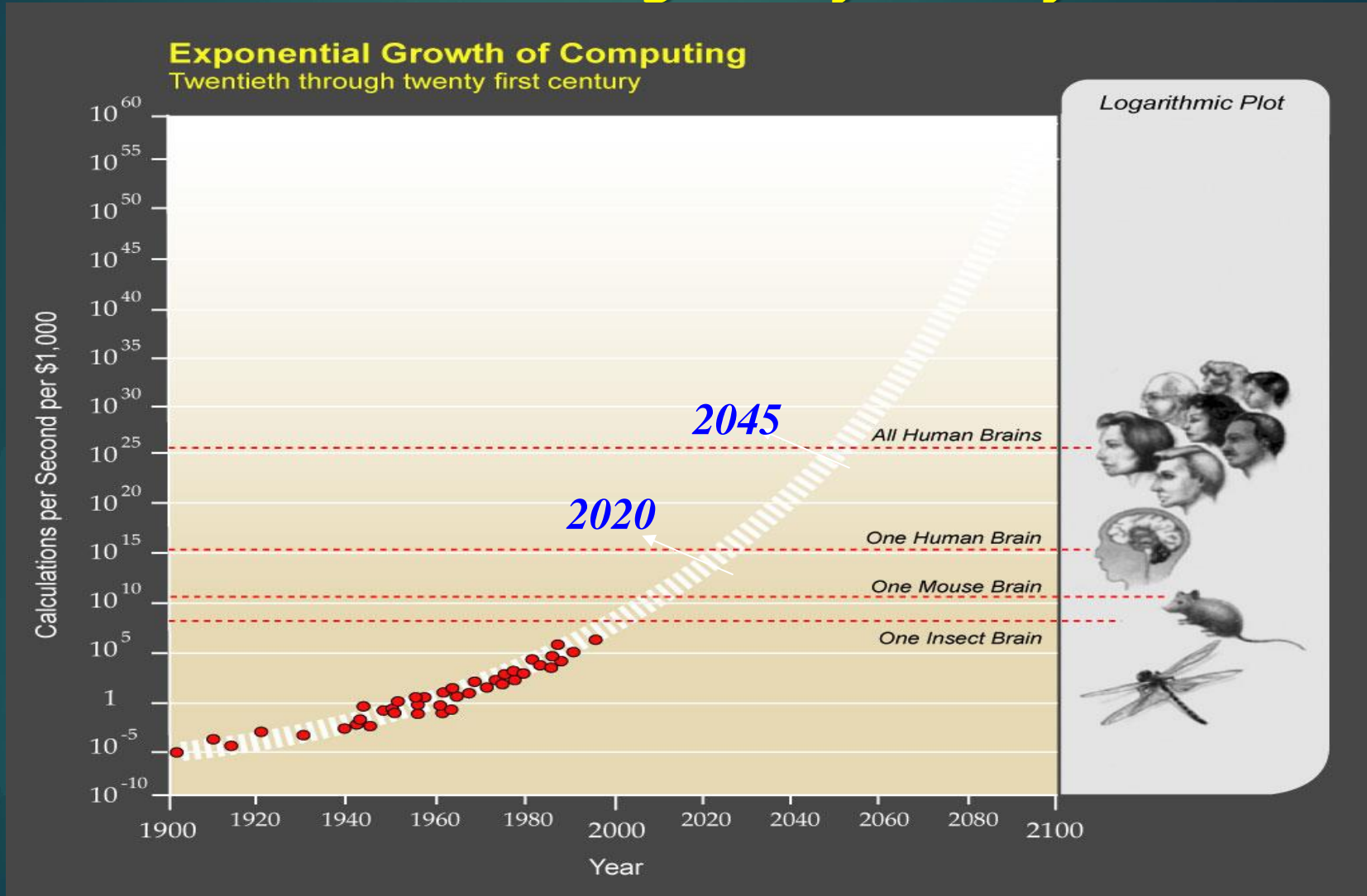
Computer program convinced humans as  
a 13-year-old boy to pass the Turing Test  
2014



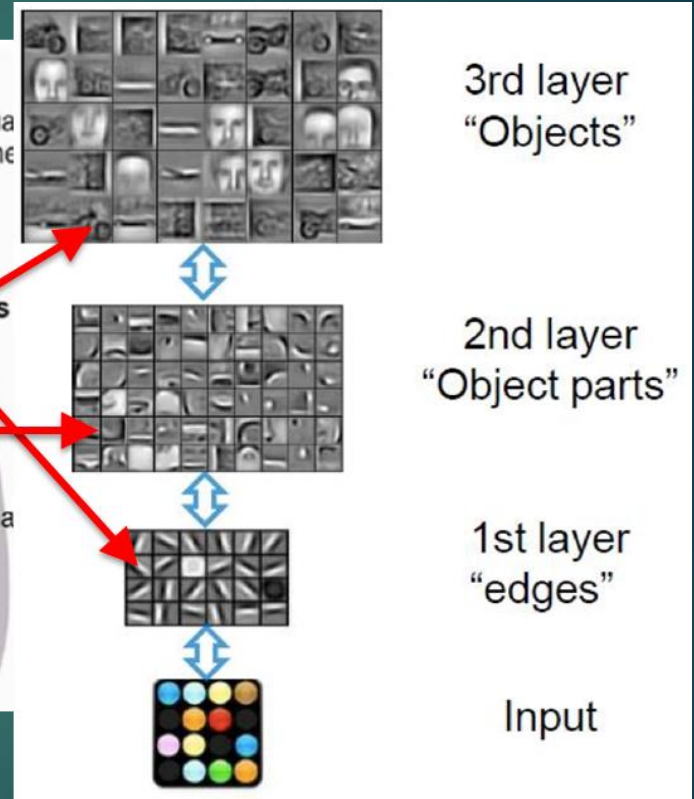
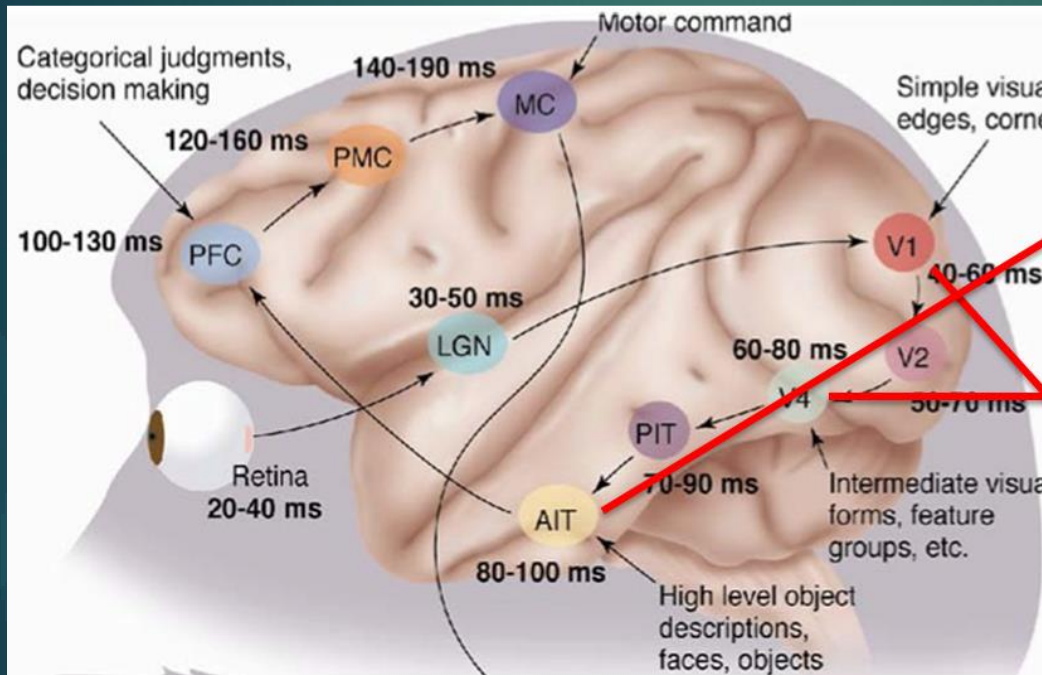
Baidu Deep Learning  
 $10^{15}$  connections (synapses)  
neural connection system  
2015

# Accelerating Intelligence :

## "Singularity" – Ray Kurzweill



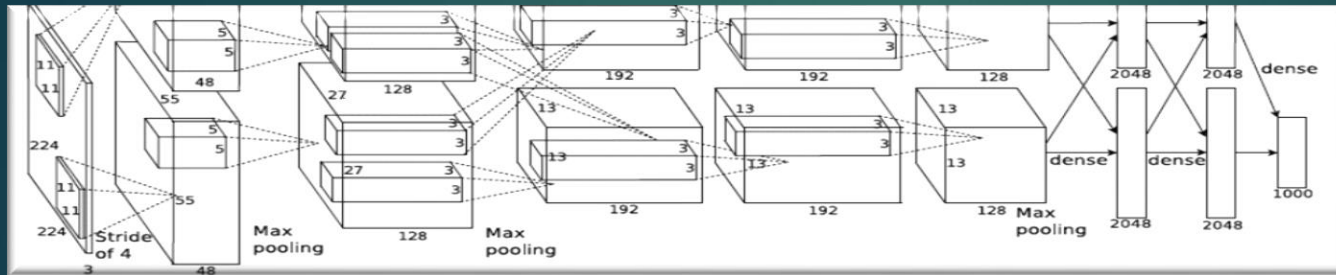
# Deep Neural Networks: human cognition?



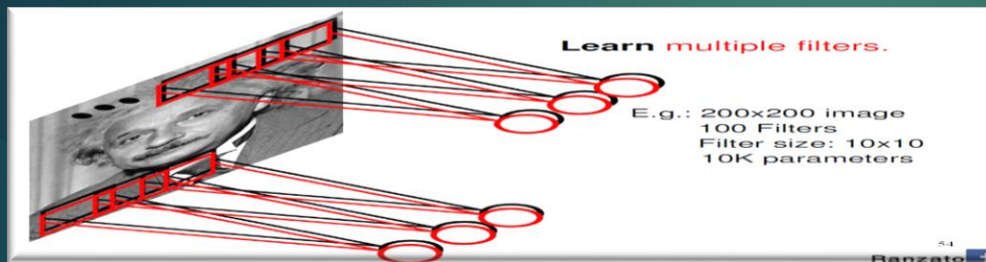
인간 학습 모델  
**Human Learning Process**

**Deep Learning**

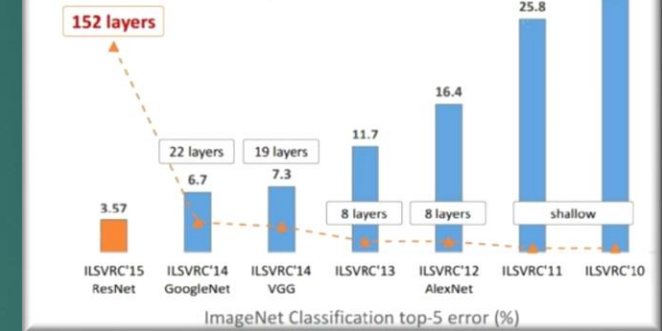
# Deep Neural Networks



Alexnet



Revolution of Depth



Inception Networks (GoogleNet)

# AI / Machine Learning based Vision /Speech Understanding



: Speech interfaced conversational robot

Speech  
enhancement  
/ noise  
reduction

Speaker  
identification  
(speech/face)

Speech  
recognition  
based on Deep  
learning

Natural  
language  
processing

# Big data Video Analysis

## ▶ Visual scene analysis

- ▶ Visual Motion: HOG, HOF, SIFT, Dense trajectories
- ▶ Visual Scene: Deep-CNN based object/scene descriptors

## ▶ Acoustic scene analysis

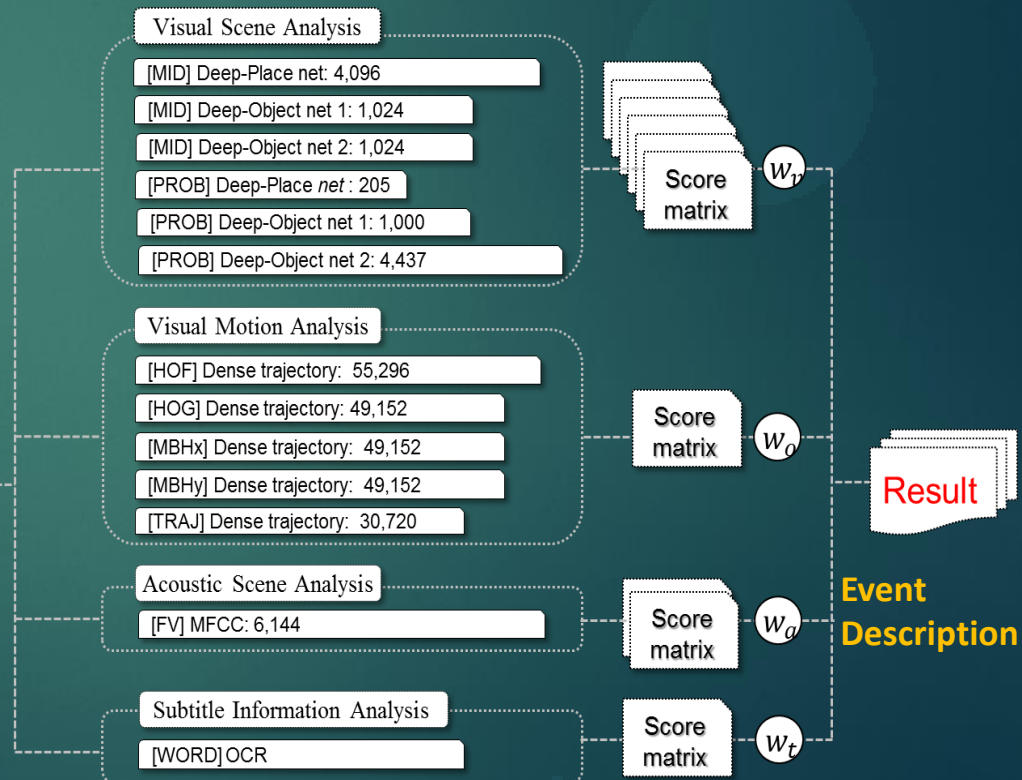
- ▶ Low level: MFCC, TM
- ▶ Semantic Level: TF-IDF based descriptor

## ▶ Speech recognition

## ▶ Optical character recognition



Input

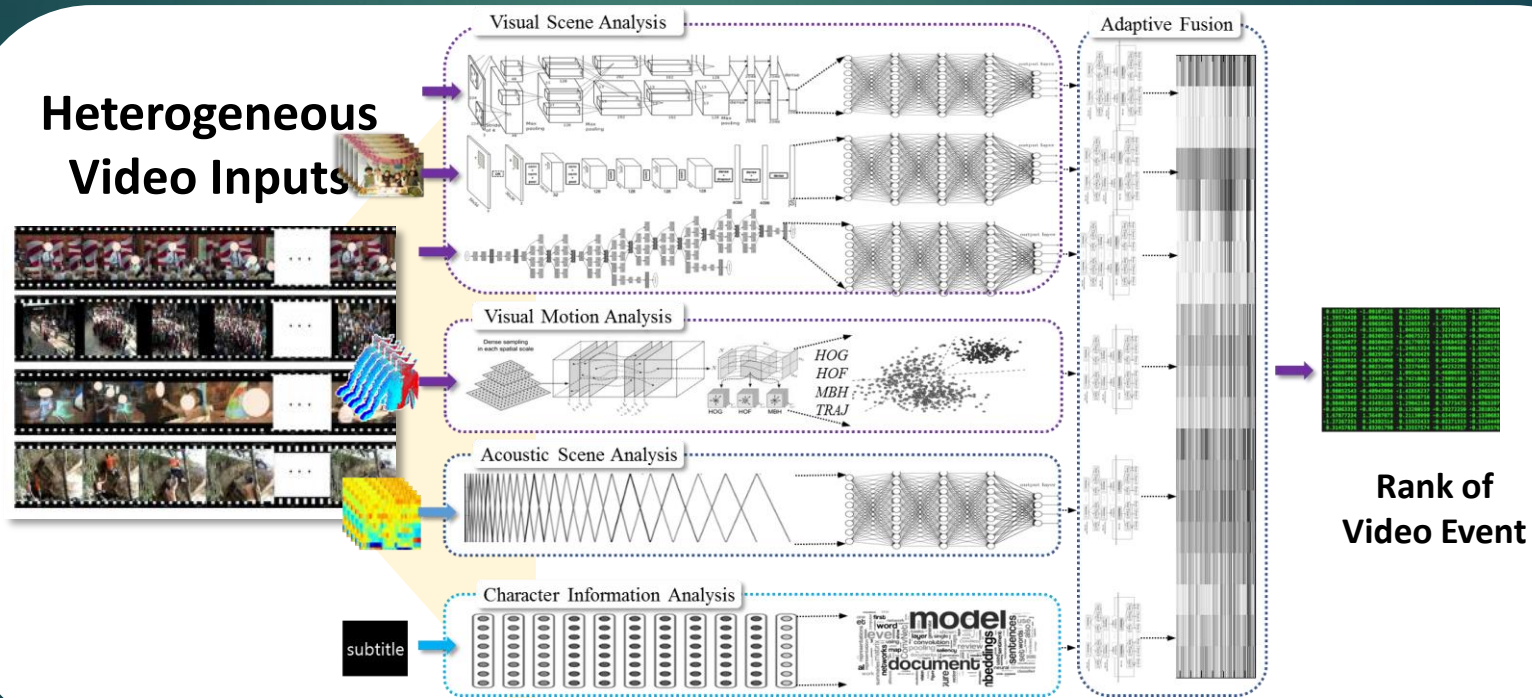




# TRECVID

## – Global Challenge for video analytics

- Event Query Generation (modeling)
  - Deep architecture-based hybrid video event learning
- Event Search (detection)
  - Two-fold information fusion
    - Dynamic Feature Selection Adaptive Metadata Weighting



# TRECVID

## – Global Challenge for video analytics

- **Training / Evaluation database (2016's)**

- **HAVIC (NIST), YFCC100M (Yahoo Corp.)**

- **Heterogeneous Audio Visual Internet Collection (HAVIC) – Default set**

- **User generated video collected from internet (*Youtube*)**

- **Testing set : 100,000 video clips (EvalFull) / 16,000 (EvalSub)**

- **Training set: 10 and 100 video clips for each video event (10EX / 100EX)**

- **Yahoo Flickr Creative Commons 100M**

- **User generated video collected from internet (*Flickr*)**

- **Testing set : 100,000 video clips (EvalFull) / 16,000 (EvalSub)**

Bike trick



Fixing a musical instrument



Town hall meeting



Tailgating



# An example of video event

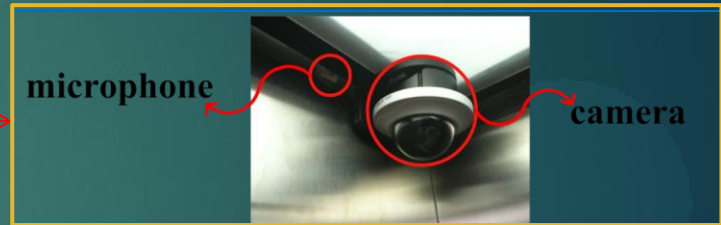
## 1. Land Vehicle Accident event

1. **Definition:** A motorized land vehicle being operated by a human hits or crashes into another vehicle or object.
2. The vehicle initiating the accident must be a motorized land vehicle
3. **Evidential Description:**
  1. **Scene:** outdoors, roads or highways, person, ...
  2. **Objects/People:** motorized land vehicle, car, ...
  3. **Activities:** driving, loss of vehicular control, people observing
  4. **Audio:** vehicle impacting, engine noise, skid, ...



# Surveillance (Human Activity Recognition)

1. Event detection is the basic technology of intelligent surveillance system
2. Heterogeneous sensor fusion is required for effective event detection



Alarm triggered



Intelligent Security System (ISS)



Integrated Security Center



more accurate, more efficient

# Surveillance

## ▶ Feature extraction

- ▶ Interesting point extraction : Dense sampling
- ▶ Point tracking : Optical flow tracking
- ▶ Feature description : HOG (Histogram of Oriented Gradients) , HOF (Histogram of Optical Flow), MBH (Motion Boundary Histogram) , Trajectory
- ▶ CNN



Interesting point tracking

# Surveillance

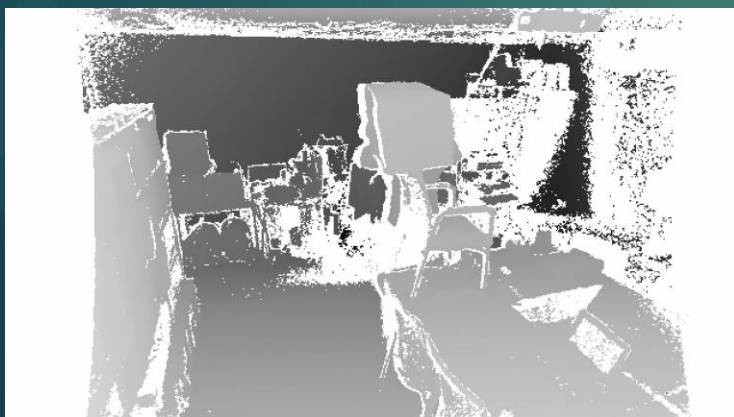
## ► Normal situation



# Surveillance

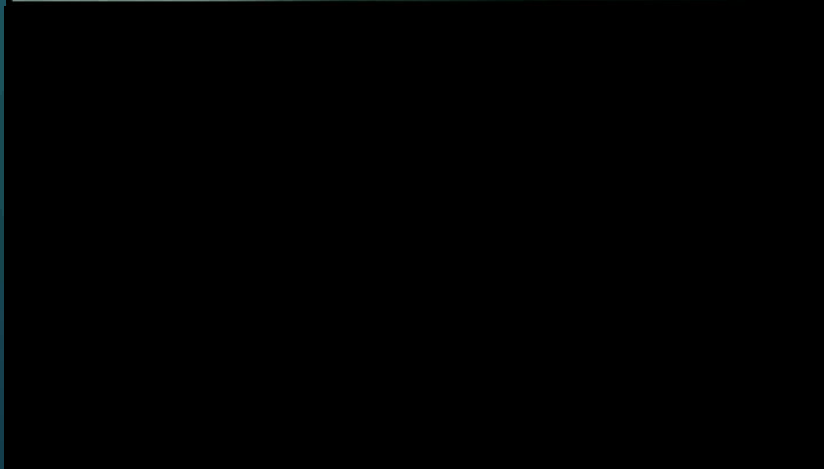
## - Demo

### ▶ Falling objects situation



# Intelligent Transport System

## 5. Demo (Image Enhancement)





# Intelligent Transport System

## 6. Demo (Image Enhancement & IR-CCD Fusion)

Hazy Video



Dehazed Video



IR Video



CCD Video



Fused Video

# Drone for surveillance

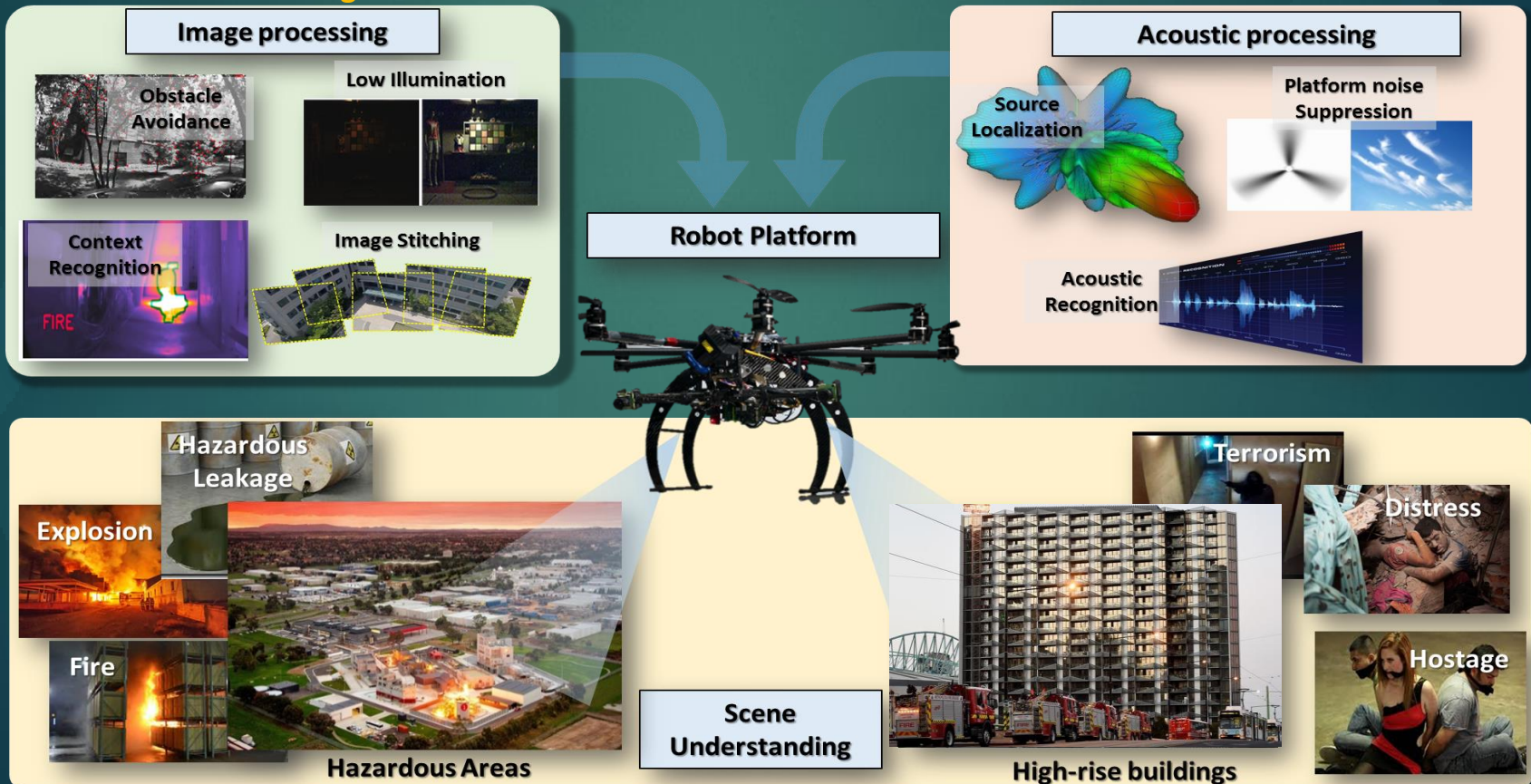
## ▶ Image Processing

- Image Stitching, Obstacle Avoidance, Low Illumination
- People detection / tracking, scene understanding

## ▶ Acoustic Processing

- Platform noise suppression, Source Localization, Acoustic recognition

## ▶ Scene Understanding

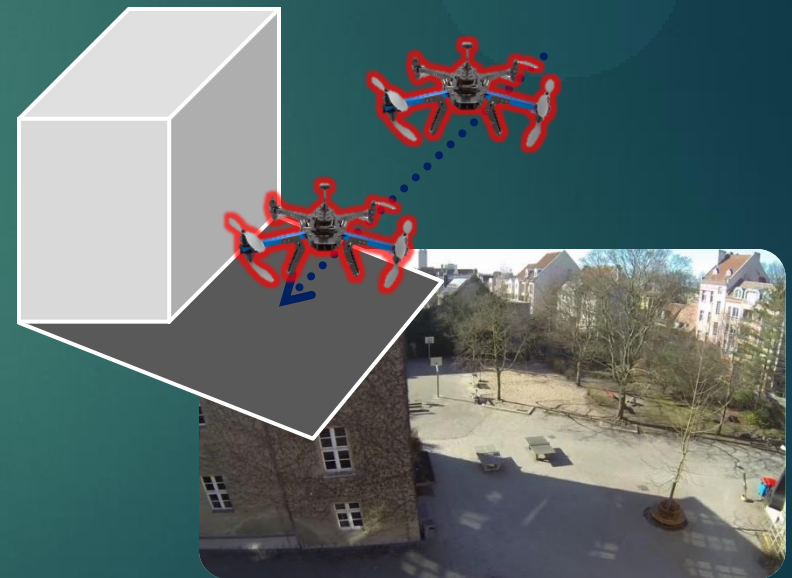
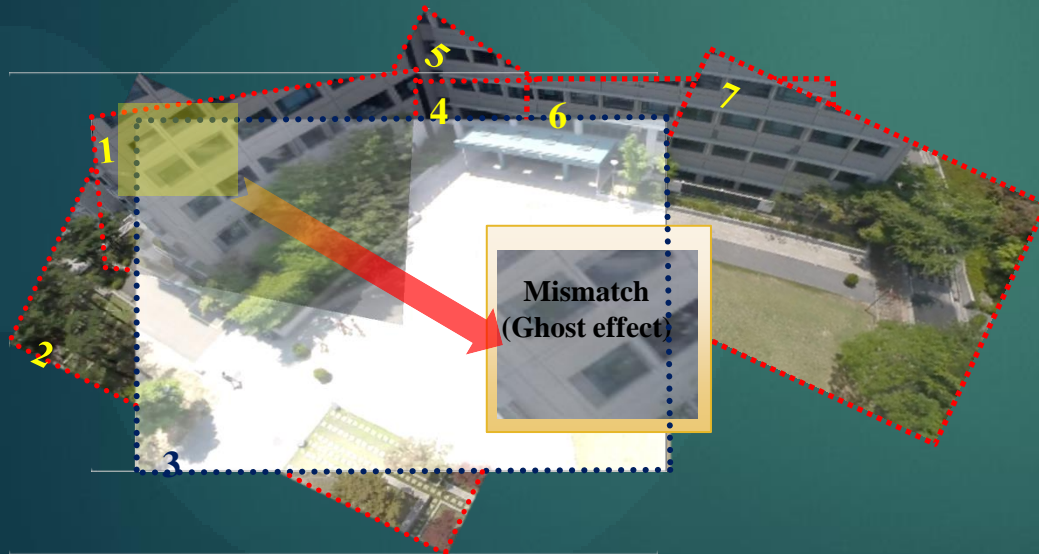


# Drone panoramic view system

## - Challenges

### ► Poor performance in illumination changes

- Image stitching has bad results in illumination changing situations.
- Due to the characteristics of the drones, the illumination changes are more severe.
  - outdoor conditions, many movements, Presence of objects such as buildings, etc.



# Drone panoramic view system

## - Approach

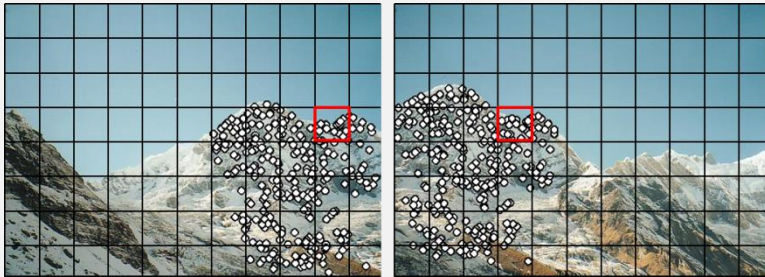
### ► Pre-Selection procedure using chaos-inspired similarity measure (fractal dimension)

- Clustering correspondence points into NxN grid
- choose the outstanding correspondence points without degradation that was caused by illumination change

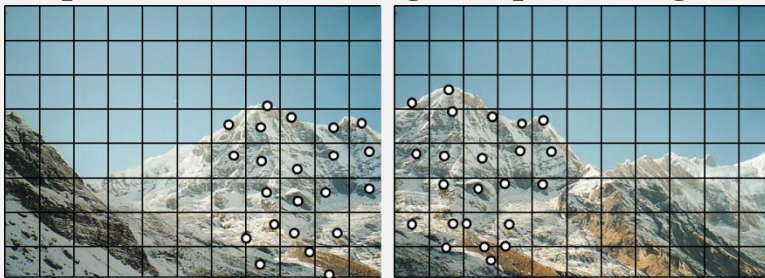
$$CISM(I_A, I_B, s) = \frac{2}{D_B(\overline{\Phi}_{I_A, \Delta I})} - 1$$

where  $\Delta I = I_A - I_B$

#### Step 1: Clustering data point into NxN grid



#### Step 2: Select outstanding data point using CISM



#### Grid from image 1 Grid from image 2

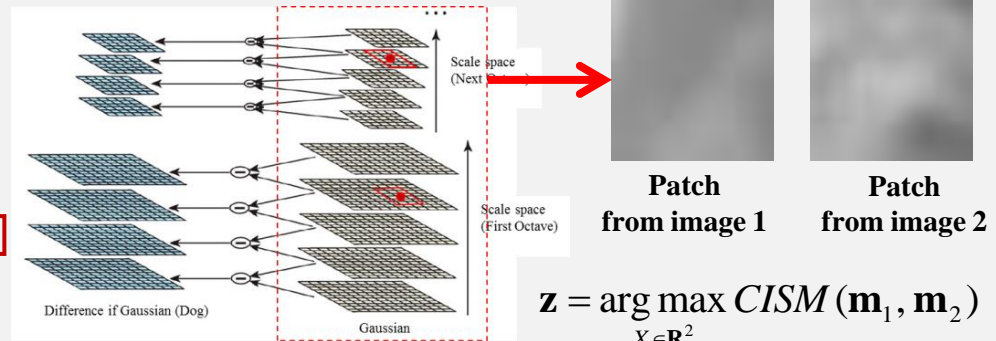
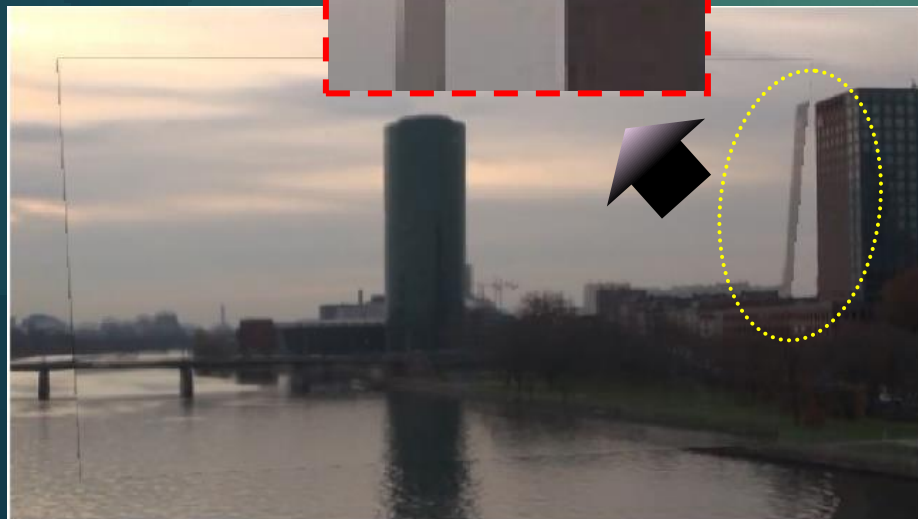
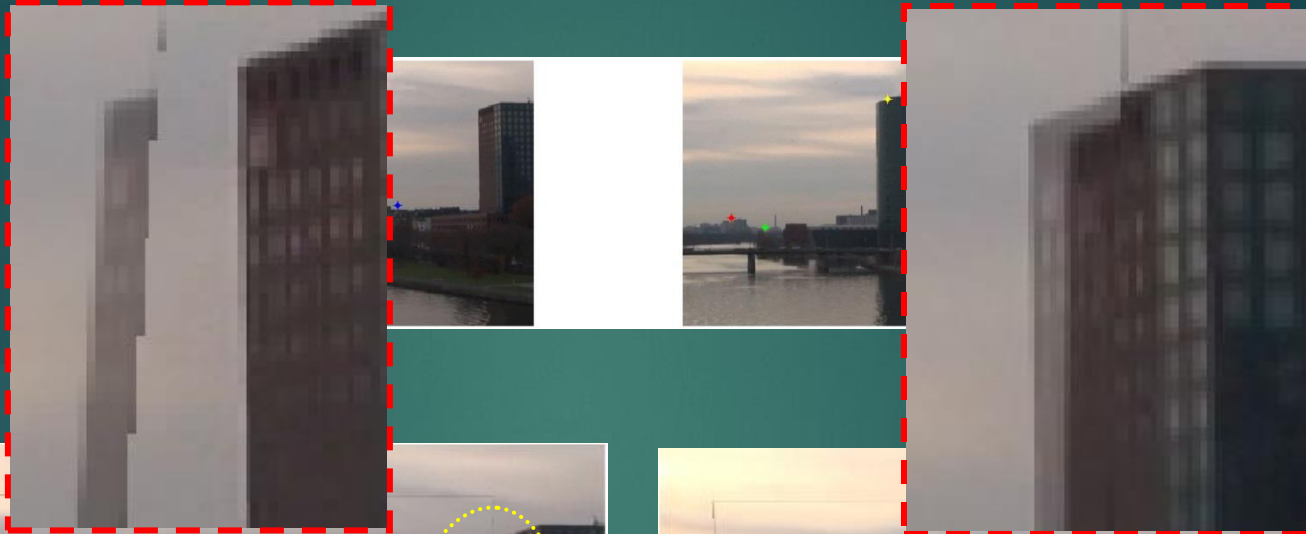


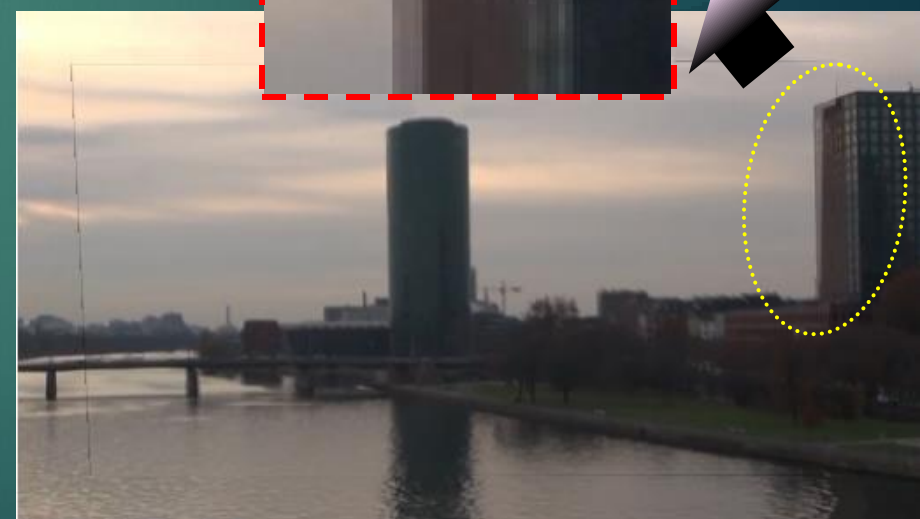
Image patch extraction and select outstanding point in each grid

# Image Stitching from Drone Platform

## ► Real-world Drone Image



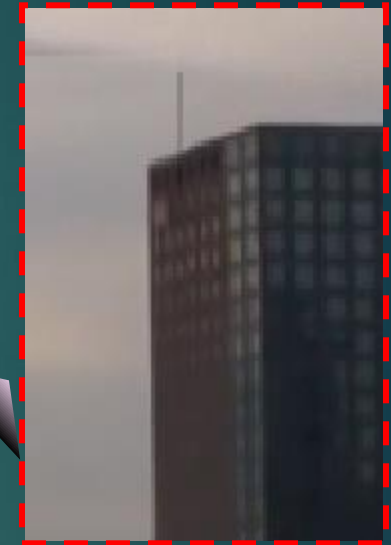
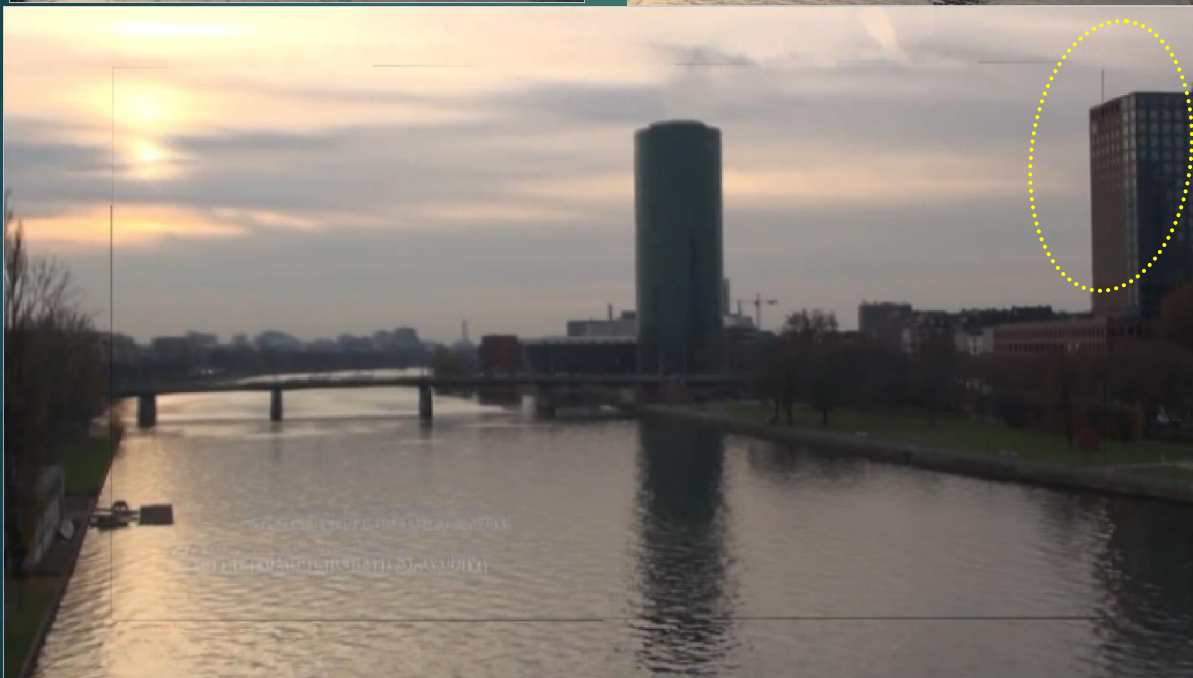
**Conventional SIFT-RANSAC**



**Chaos-RANSAC**

# Image Stitching from Drone Platform

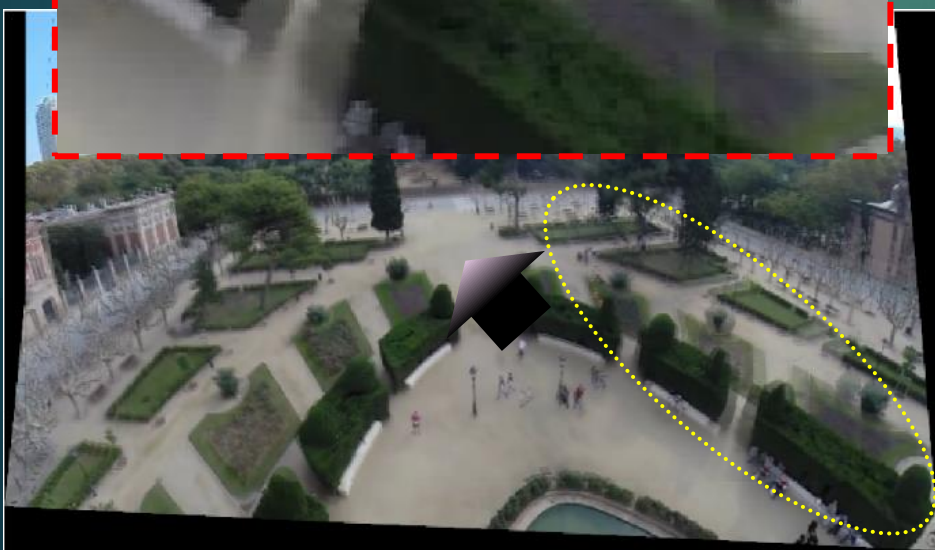
## ▶ Real-world Drone Image



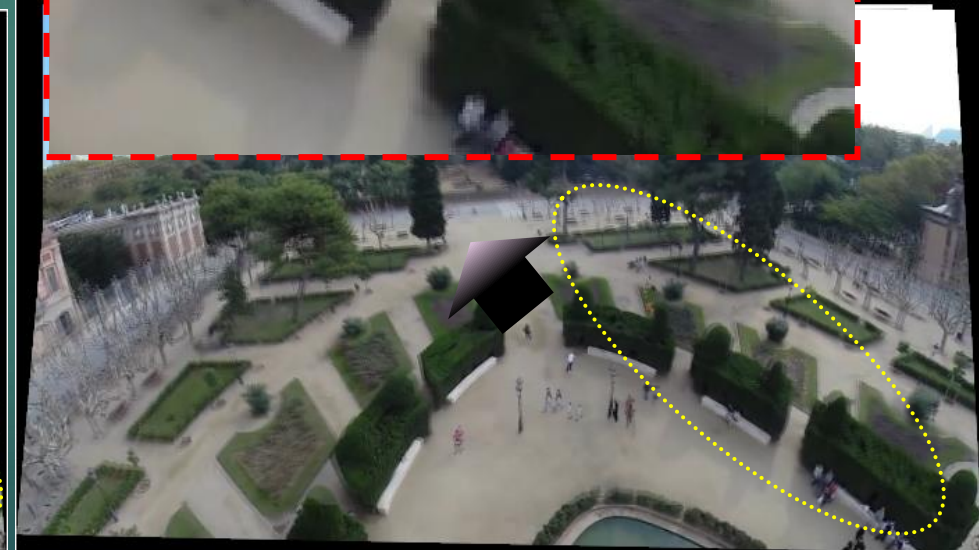
Modified CISM

# Image Stitching from Drone Platform

## ► Real-world Drone Image



Conventional SIFT-RANSAC



Chaos-RANSAC

# Image Stitching from Drone Platform

## ► Real-world Drone Image

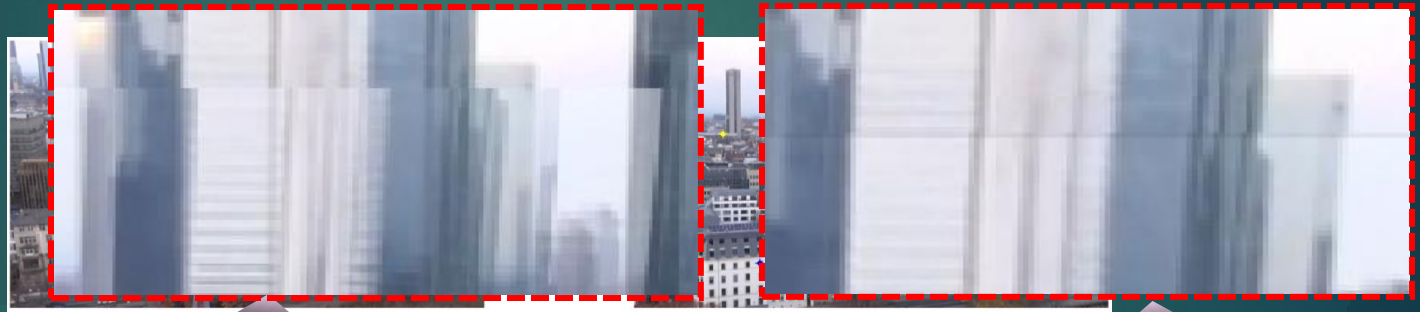


Modified CISM

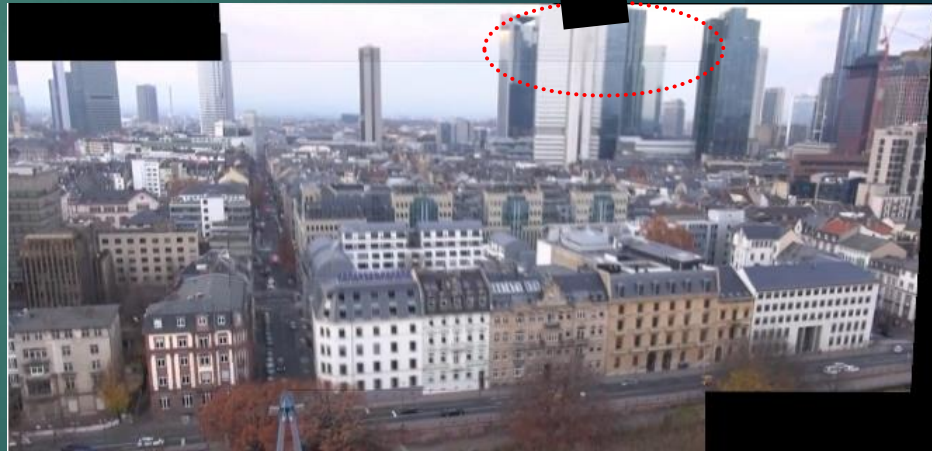


# Image Stitching from Drone Platform

## ► Real-world Drone Image

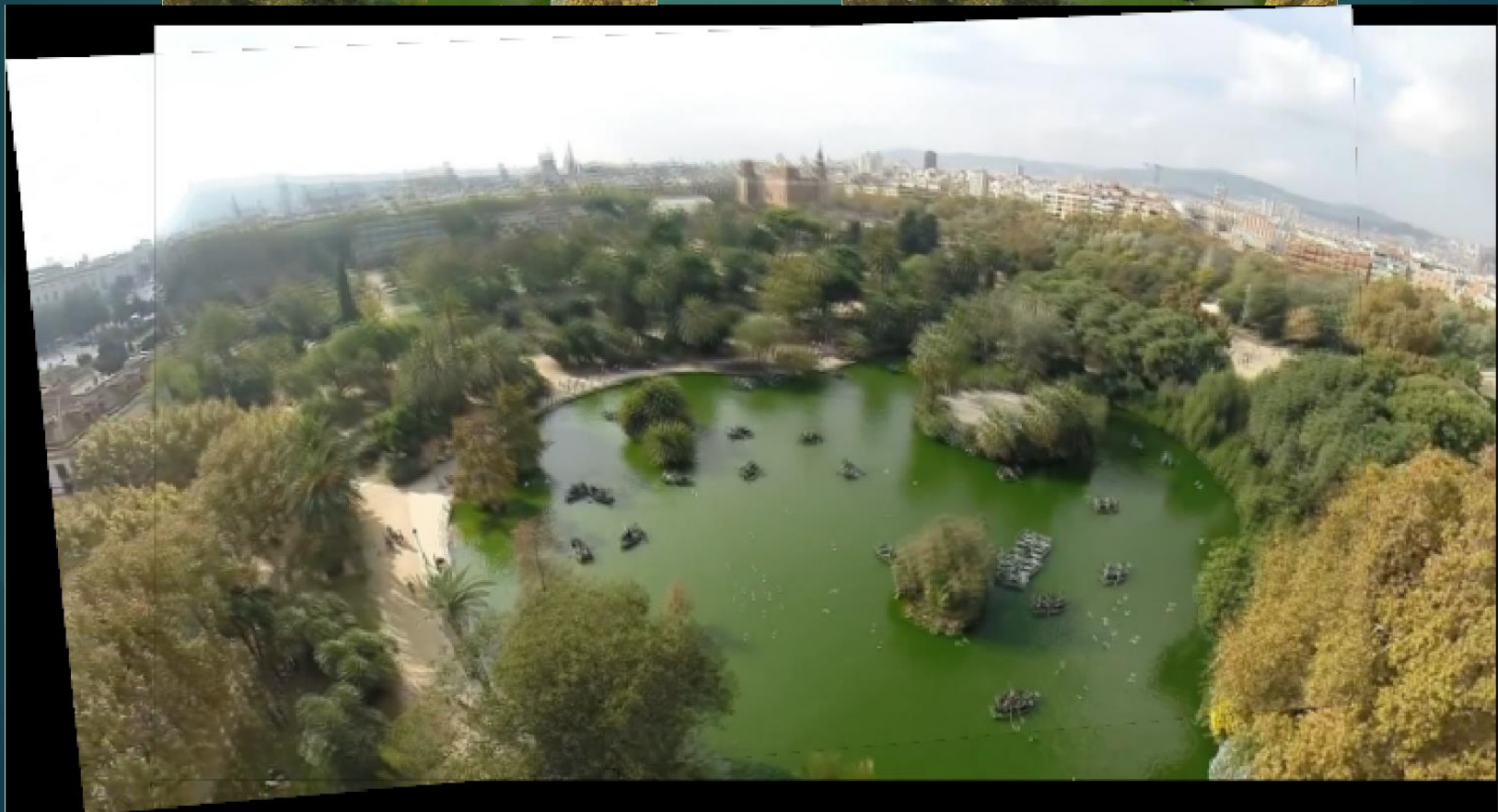


Conventional SIFT-RANSAC



Chaos-RANSAC

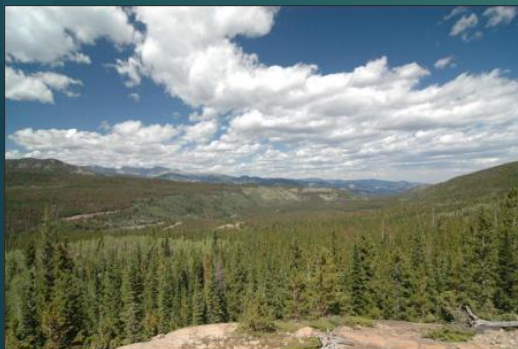
# Image Stitching from Drone Platform



# Image Stitching from Drone Platform



# Image Stitching from Drone Platform



# Delivering Impact of Weather

AI technology based **Video Analytics** and **Image processing** techniques applied to **live CCTV feed** can deliver the impact of weather to citizens and Meteorology Agency **real time** with **timely warnings** and alarms.



## Video Analytics, Image Processing



Video Analytic Server

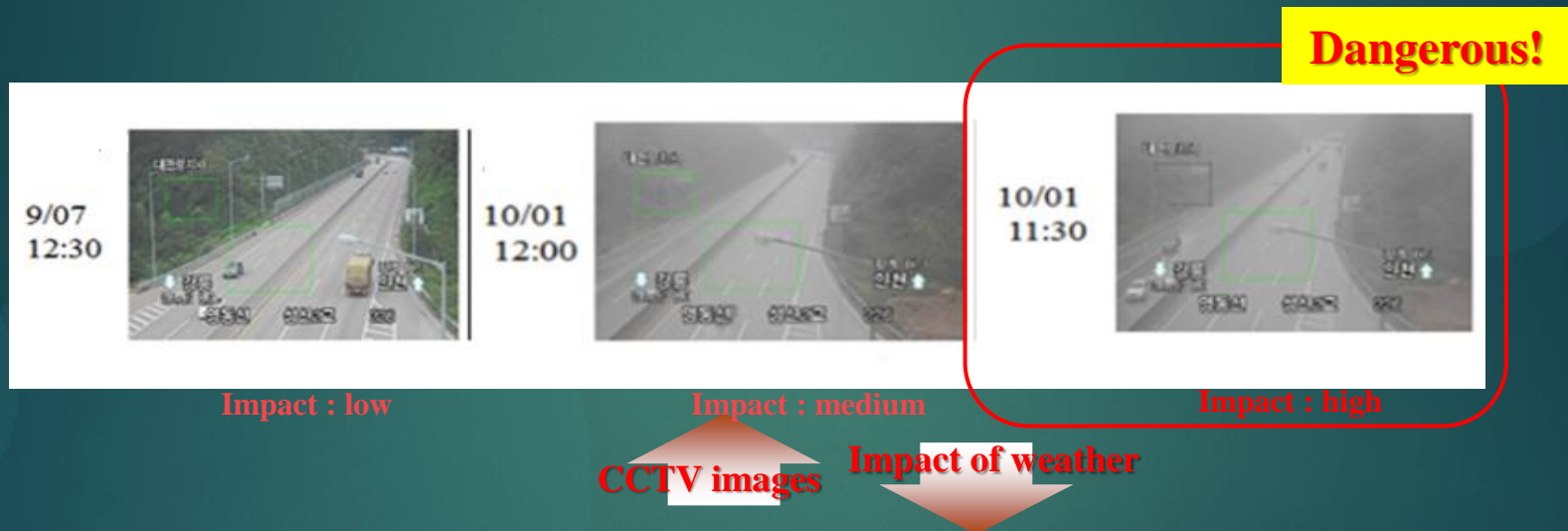


Monitoring Center

Efficiently manage and forecast  
the impact of weather

# Operational Scenarios under various weather environment

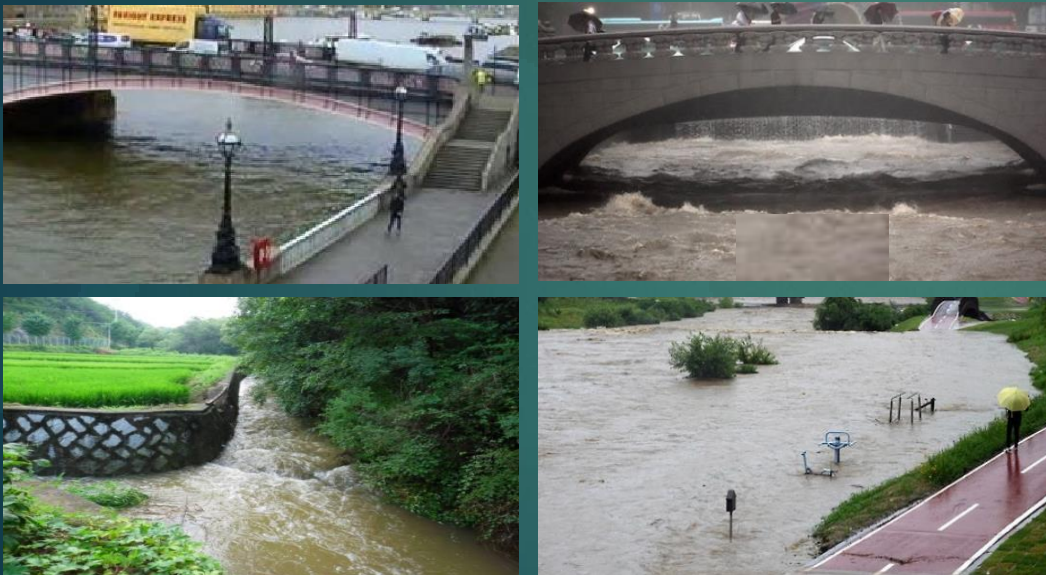
- Impact of weather on highways using **CCTV** streams
  - Managing and forecasting of **fog on highway** can prevent car fatalities (extreme fog, flooding, ice)



# Operational Scenarios under various weather environment

## ➤ Impact of weather on river

- Managing and forecasting **depth of water in a river** can **prevent possible flooding** and provide timely warning to those being endangered.



< CCTV images from rivers >

Image processing  
technique

Rainfall raises  
depth of water in  
river

Video Analytics

Impact of weather on river

# Operational Scenarios under various weather environment

## ➤ Impact of weather on the coast

- Managing and forecasting the **wave height on the coast** can **prevent damages** from tsunamis.



< CCTV images from the coasts >

Image processing  
technique

Wave height

Big data Analytic

Impact of weather on the  
coast



# Operational Scenarios under various weather environment

## ➤ Impact of weather on the street

- Managing and forecasting the **snow or rain on the street**
- Impact of weather can also be estimated by **analyzing the activities of pedestrian or cars**



Amount of rain



Impact of rain



Number of umbrellas



Impact of rain



Amount of snow



Impact of snow



Moving pattern of pedestrians



Impact of condition of road

---

# Approaches

# Fixed CCTV based:

## *people activity monitoring on streets*

- **Weather information from fixed CCTV camera on streets**
  - **Clothing classification:** Indication of temperature
  - **Umbrella detection:** Indication of rain
  - **Mask detection:** Indication of dust storm



< Temperature > ↓



< Temperature > ↑



< Rain >



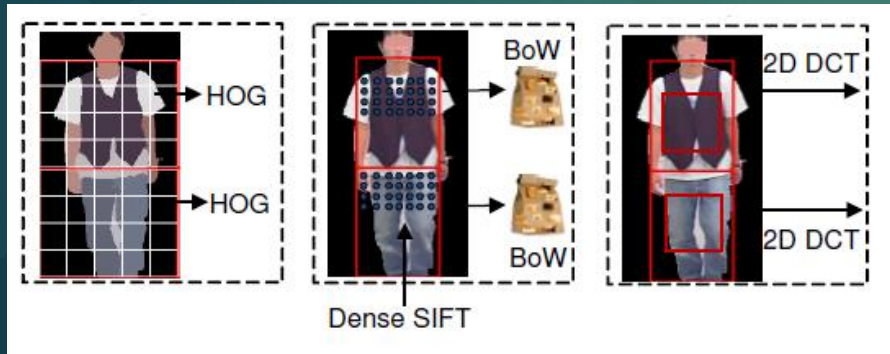
< Dust storm >

# Fixed CCTV based: *people activity monitoring on streets*

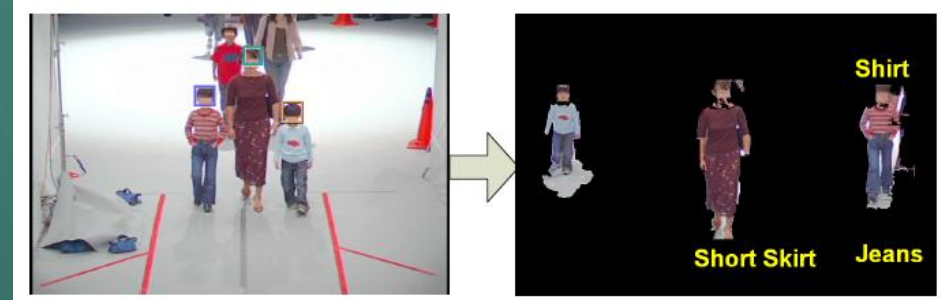
## ➤ Clothing classification & recognition

- Color segmentation method with 3 types of texture features (HOG, BOW, DCT) [1]

**HOG: Histogram of Oriented Gradient**  
**BOW: Bag of-Words**  
**DCT : Discrete Cosine Transform**



< 3 types of texture features >



< Recognition example >

# Fixed CCTV based: *people activity monitoring on streets*

## ➤ Clothing classification (Cont'd)

- Recently, **deep learning model** (named FashionNet) based on CNN has been developed [2]
- It learns clothing features by jointly predicting clothing attributes and landmarks



< Additional landmark locations >



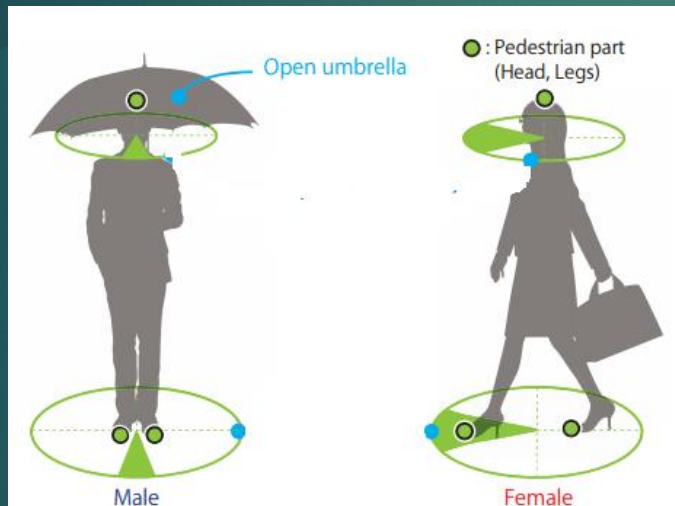
< Partition of clothing feature space >

[2] LIU, Ziwei, et al. “Deepfashion: Powering robust clothes recognition and retrieval with rich annotations”. CVPR, pp. 1096-1104, 2016

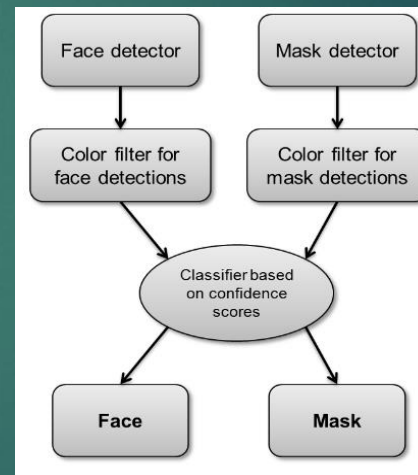
# Fixed CCTV based: *people activity monitoring on streets*

## ➤ Umbrella / Mask detection

- Recognizing the attribute (open umbrella) was proposed in [3]
- Confidence measures was proposed for the mask and maskless face detections [4]



<Recognizing attributes for open umbrella >



< Mask detection example >



[3] FUKUI, Hiroshi, et al. "Robust pedestrian attribute recognition for an unbalanced dataset using mini-batch training with rarity rate". In: Intelligent Vehicles Symposium pp. 322-327, 2016

[4] N.Rodriguez, al Mask and maskless face classification system to detect breach protocols in the operating room. International Conference on Distributed Smart Cameras. ACM, pp. 207-208, 2015

# Fixed CCTV based: *augmented weather surveillance*

## ➤ Extreme Weather Detection and Alarm



<Normal Weather>

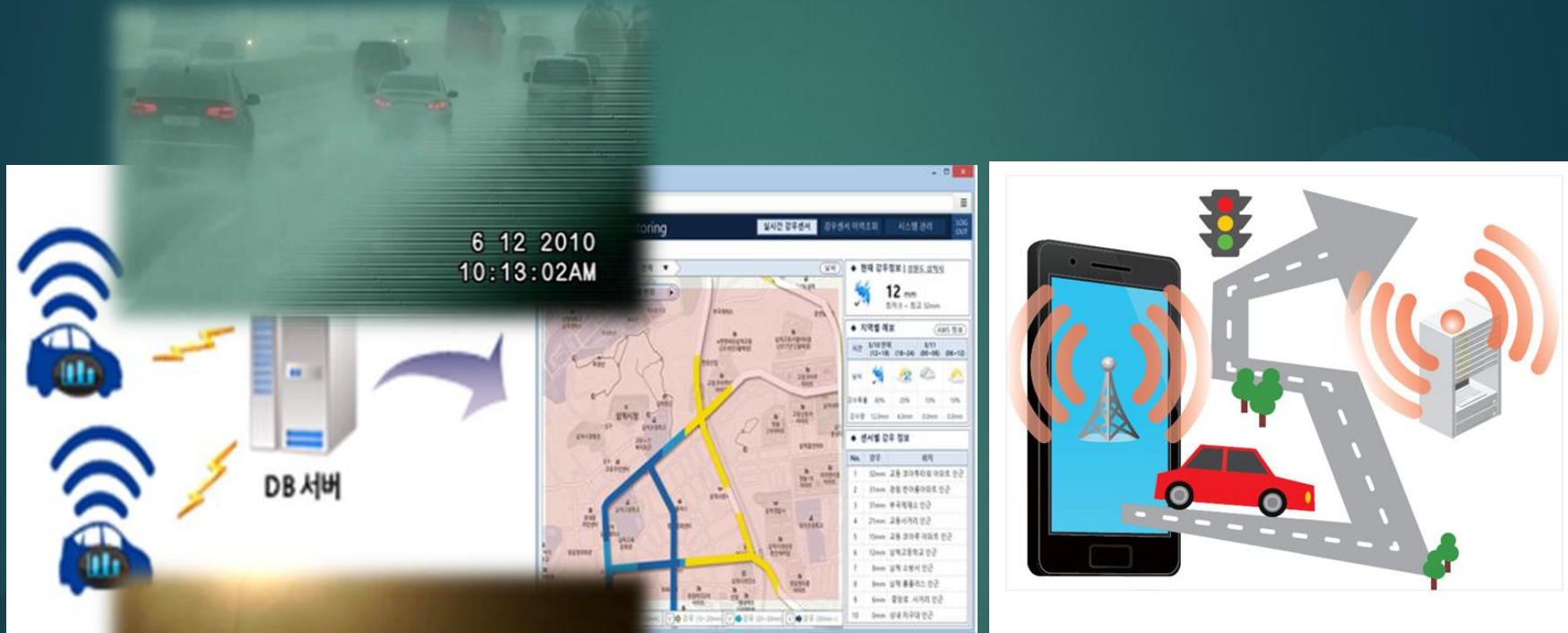


<Extreme Weather>

Dense fog, Severe rain/snow

# Moving CCTV based: *on vehicle weather impact collection*

## ➤ Extreme Weather detection and alarm for safety



<Extreme Weather Management on the road>



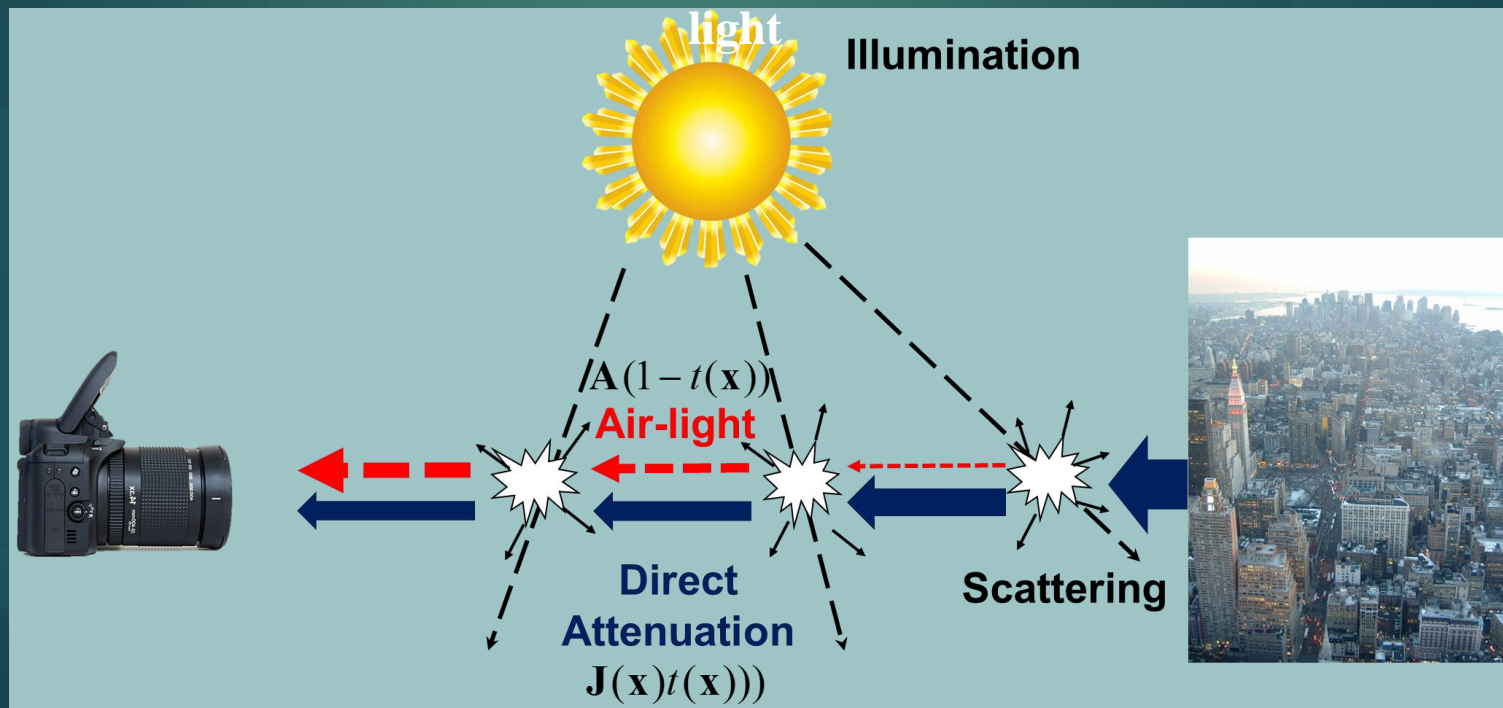
# Proposed Algorithms

# Measuring Fog Density

- Fog Imaging Model
  - Optical Imaging and Image Representation

$$\mathbf{I}(\mathbf{x}) = \mathbf{J}(\mathbf{x})t(\mathbf{x}) + \mathbf{A}(1 - t(\mathbf{x}))$$

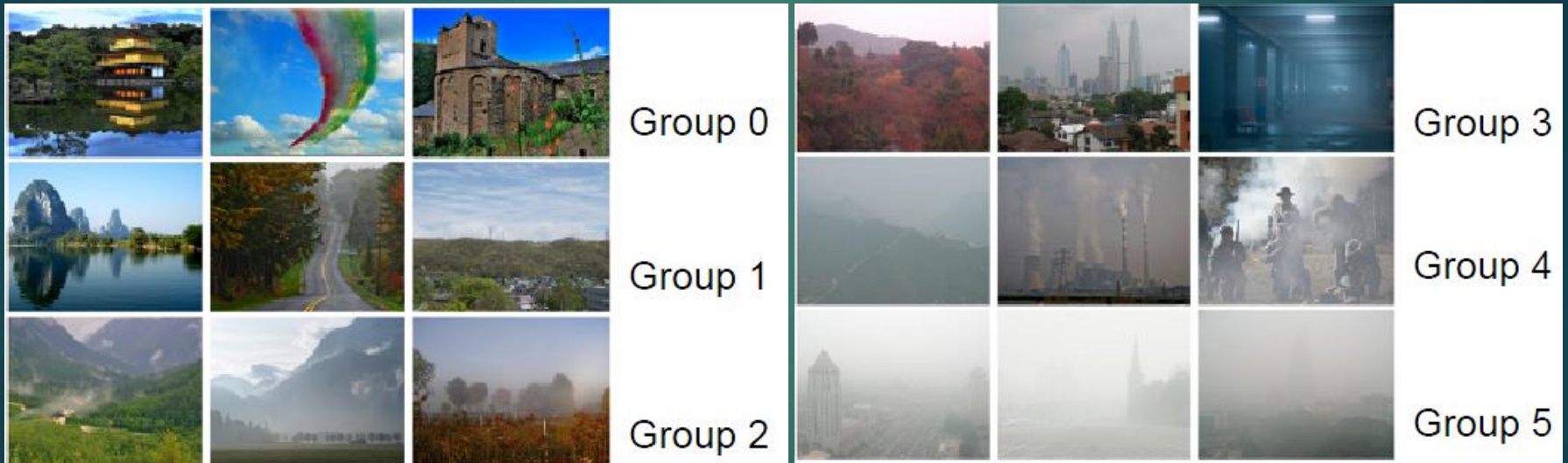
$\mathbf{I}(\mathbf{x})$ : Fog image,  $\mathbf{J}(\mathbf{x})$ : Fog-free image,  $t(\mathbf{x})$ : Transmission,  $\mathbf{A}$ : Atmospheric



# Measuring Fog Density

## ➤ Grouping fog density

- **Group 0:** Clear, **Group 1:** Very Thin, **Group 2:** Thin
- **Group 3:** Normal, **Group 4:** Thick, **Group 5:** Very Thick



<Outdoor Image Database>

# Measuring Fog Density

## ➤ Feature for Measuring Fog Density

- Fog Feature derived from fog imaging model

- Feature 1

$$d^{\mathbf{I}}(x) = \left( \min_{n \in \{r, g, b\}} \mathbf{J}^n(x) \right) t(x) + A_0(1 - t(x)),$$

- Feature 2

$$b^{\mathbf{I}}(x) = \left( \max_{n \in \{r, g, b\}} \mathbf{I}^n(x) \right) t(x) + A_0(1 - t(x)),$$

- Feature 3

$$c^{\mathbf{I}}(x) = \left( \max_{n \in \{r, g, b\}} \mathbf{J}^n(x) - \min_{n \in \{r, g, b\}} \mathbf{J}^n(x) \right) t(x),$$

$$= c^{\mathbf{J}}(x)t(x),$$

# ❖ Measuring Fog Density

## ➤ Global Atmospheric Light

- Global atmospheric light constraint

$$\bar{b} \leq A_0 \leq \max b^I(x),$$

- Initial global atmospheric light

$$A_0 = \lambda \max b^I(x) + (1 - \lambda)\bar{b},$$
$$0 \leq \lambda \leq 1$$

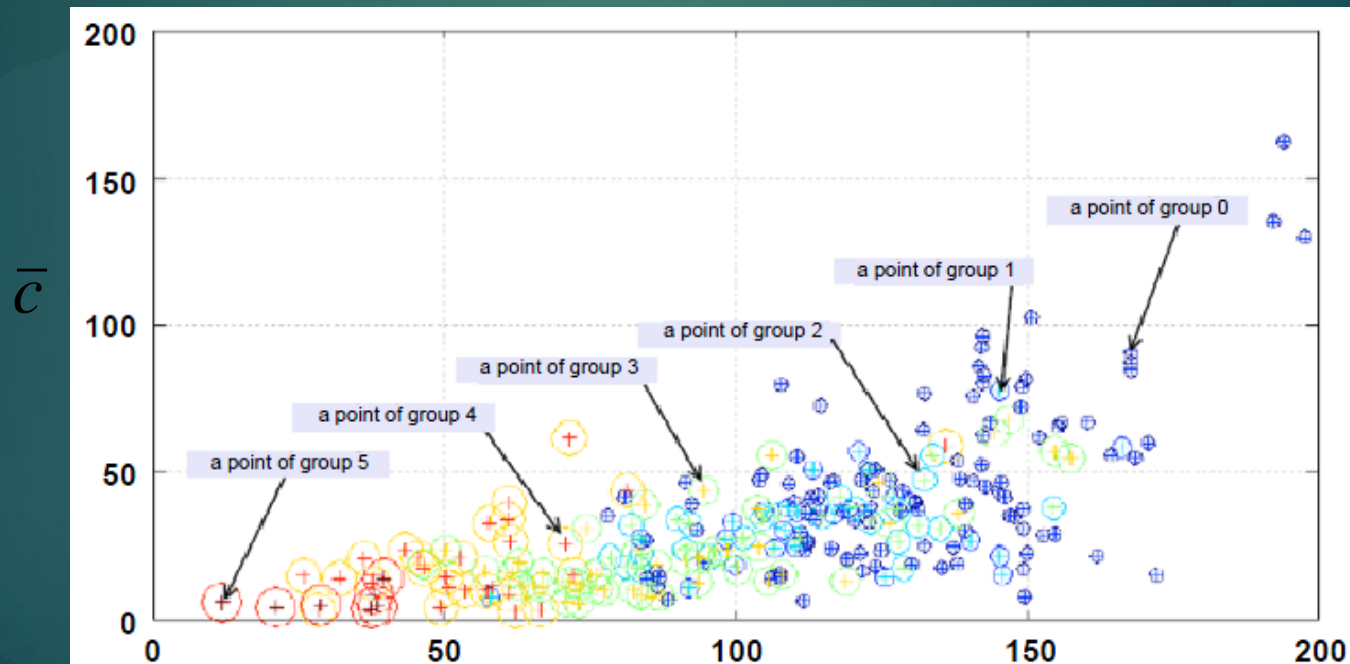
( $\lambda$  : control para. atmospheric light)

# Measuring Fog Density

- Distribution according to the fog density
  - Feature distribution map

$$A_0 - \bar{d}(x) = (A_0 - \bar{d}(x))t(x),$$

$$\bar{c} = \frac{1}{M} \sum d^I(x) - \frac{1}{M} \sum b^I(x),$$



$$A_0 - \bar{d}(x)$$

# Measuring Fog Density

## ➤ Fog density estimation function

$$\omega = \exp\left\{-\frac{1}{2}(5.1\alpha + 2.9\beta) + 0.2461\sigma\right\},$$

$$\alpha = \frac{A_0 - \bar{d}}{A_0}, \beta = \frac{\bar{c}}{A_0}$$

Fog density	$\omega$	Class	
		Ratio of fog	Fog density
0	0.1	0	Clear
1	0.3	30~50%	Low
2	0.5	50~60%	Thin
3	0.7	60%~70%	Normal
4	0.8	70%~80%	High
5	0.9	80%~100%	Denger

# Measuring Fog Density

## ➤ Demo

- Fog density estimation

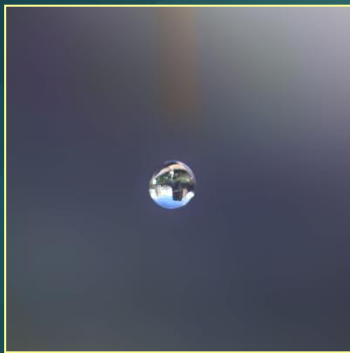




# Measuring Snow/Rain

## ➤ Characteristics of Snow/Rain

- Rain/snow degrade the visibility of the scene and disrupt precise analysis
- Rain/snow have the dynamics and occur sporadically

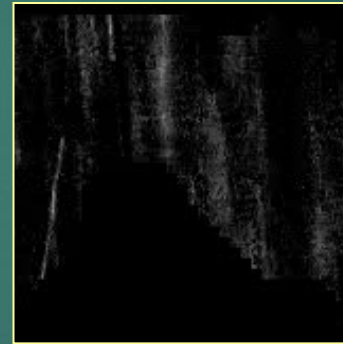


Rain Drop



Rain Streak

+



Dynamics

=

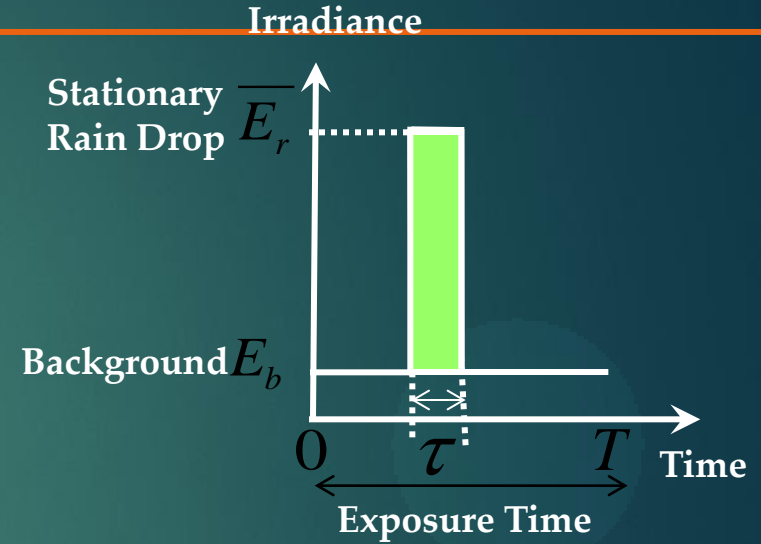
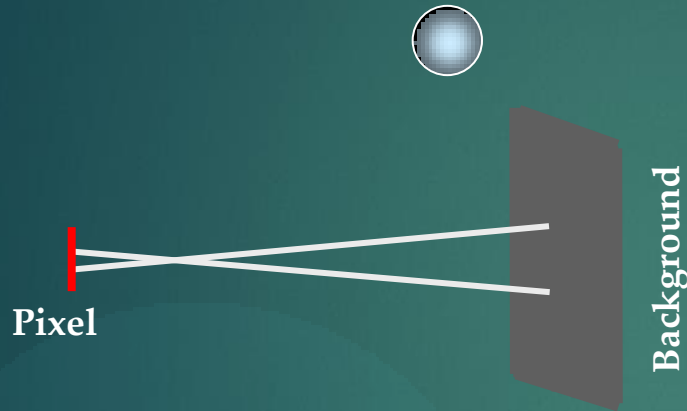


Rain

Photometry

# Measuring Snow/Rain

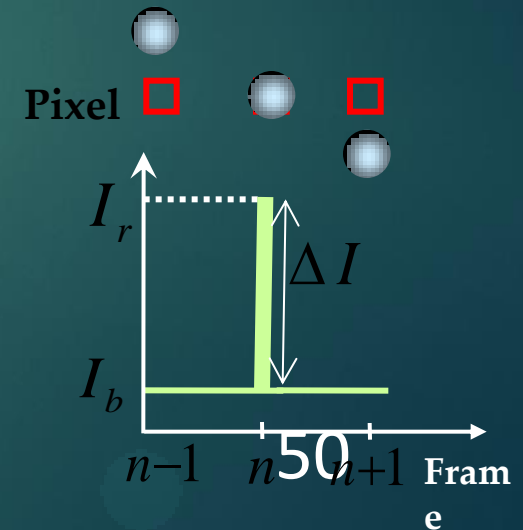
## ➤ Rain/Snow Imaging Model



Time a drop stays over a pixel :  $\tau < 1 \text{ ms} \ll T$

Change in Intensity :  $\Delta I = \tau (\overline{E_r} - E_b) > 0$

Rain produces a "Delta Signal" in Time



# Measuring Snow/Rain

Intensity at a Pixel on a Rain Streak :

$$I_r = E_b(T - \tau) + \tau \overline{E_r}$$

Intensity of the Background :

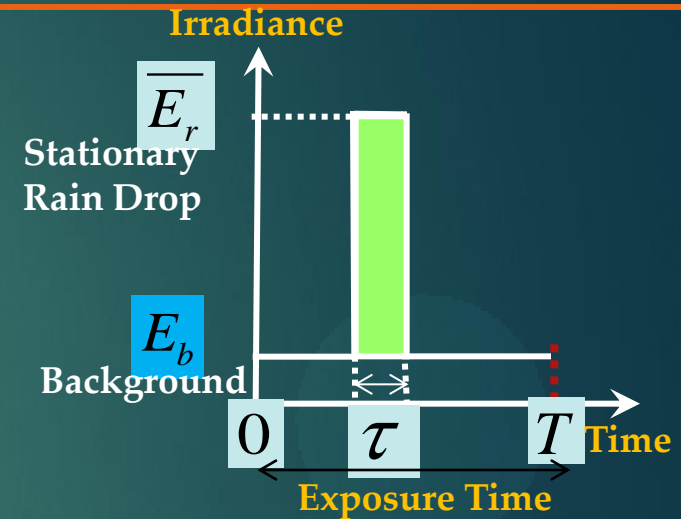
$$I_b = E_b T$$

Change in Intensity due to a Rain Streak :

$$\Delta I = \left( -\frac{\tau}{T} \right) I_b + \left( \tau \overline{E_r} \right)$$

Constants

Constants

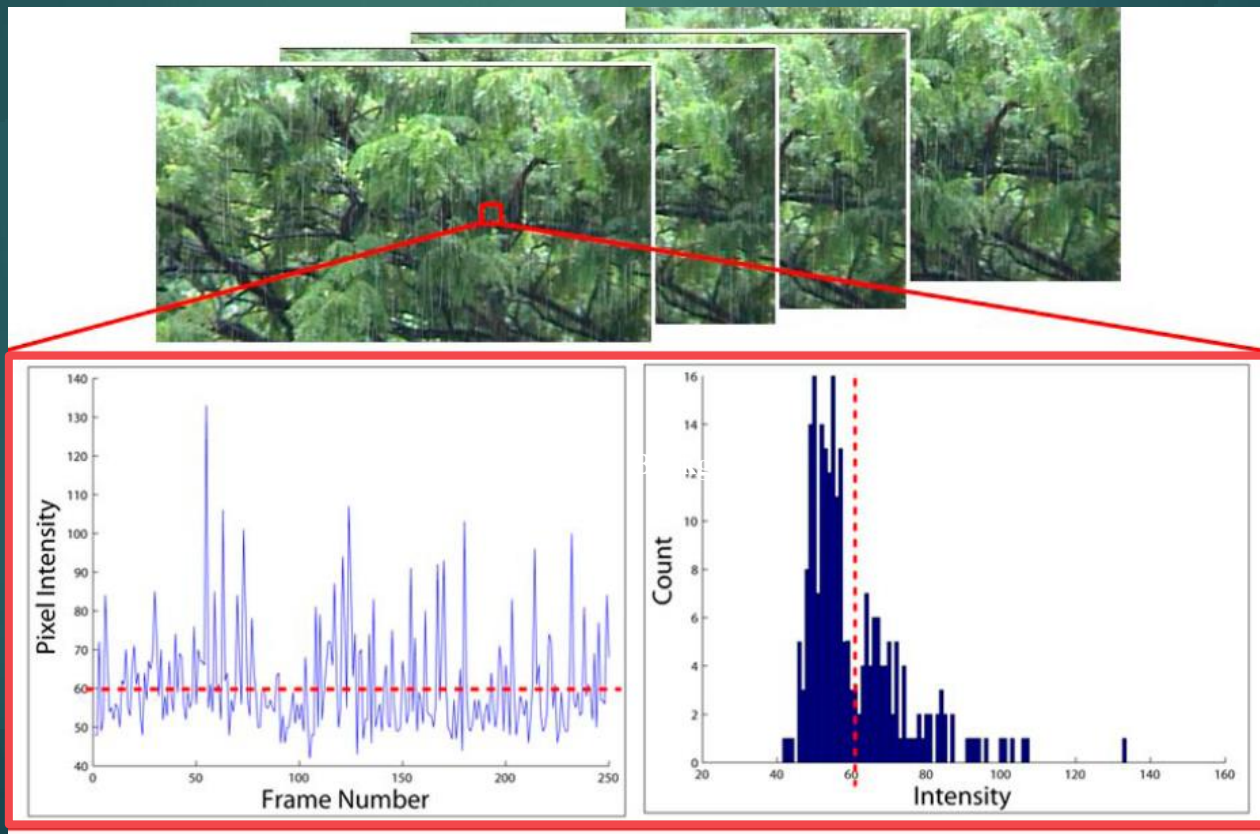


Change in Intensity is Linearly related to Background

# Measuring Snow/Rain

## ➤ Rain/Snow Detection

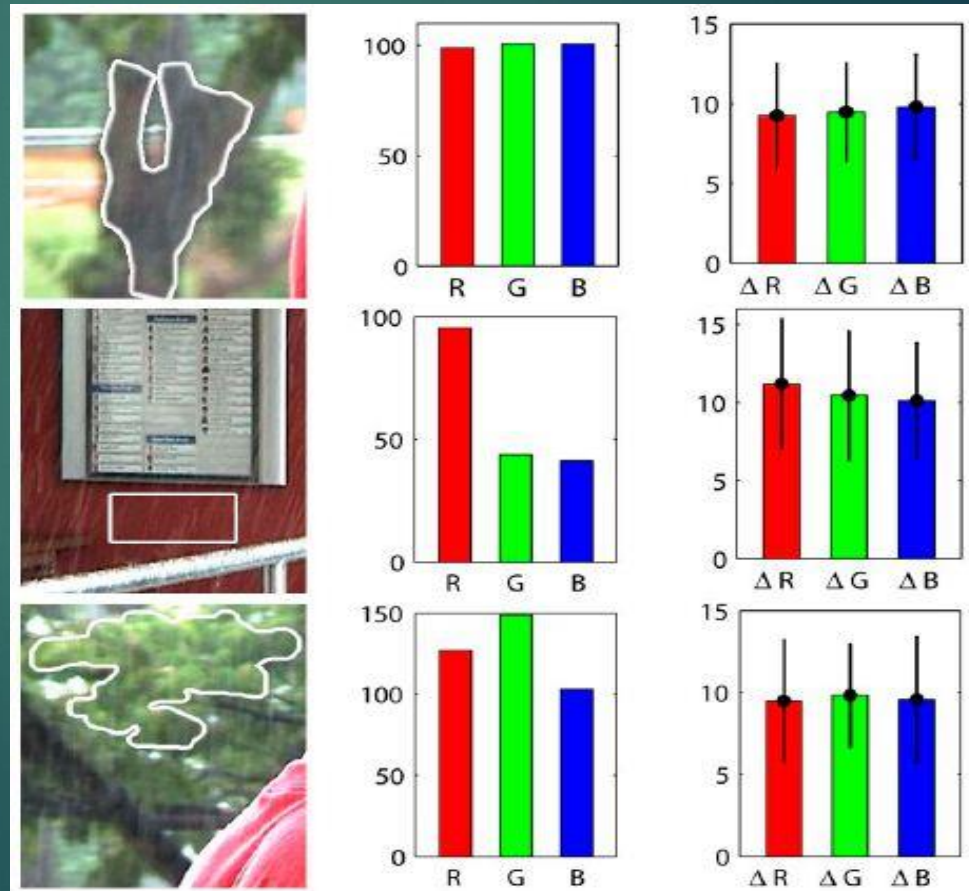
- The pixels including rain drop have the 2-peaks in the temporal histogram
- 2-peaks are computed by K-means clustering
- Classify the pixels based on 2-NN method using 2-peaks



# Measuring Snow/Rain

## ➤ Rain/Snow Detection

- Initially detected pixels are further classified using chromatic constraint which the differential of each R,G,B channels is almost same regardless of background color



# ❖ Measuring Snow/Rain

## ➤ Rain detection

- Initially detected pixels are further classified using chromatic constraint which the difference of each R,G,B channels is almost same regardless of background color



**Rainy image**



**Initial detected rain**



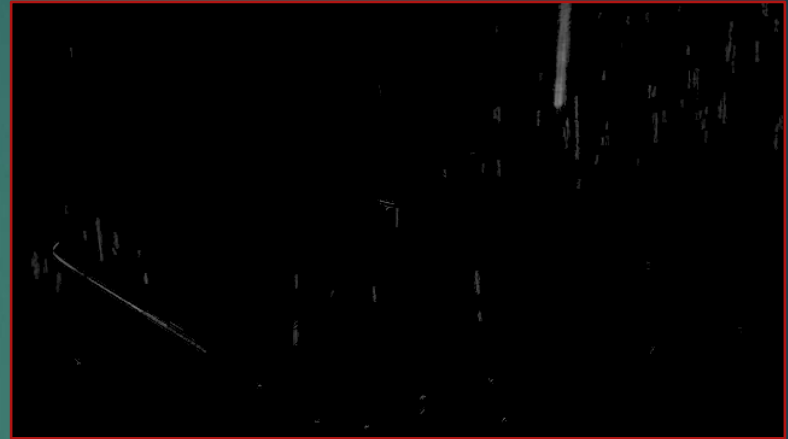
**Detected rain with 54  
chromatic constraint**

# ❖ Measuring Snow/Rain

## ➤ Experimental result



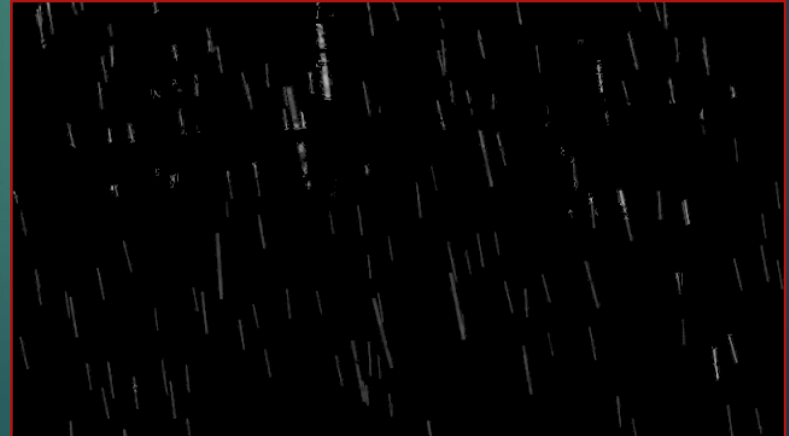
Rain image



Detected rain



Rain image



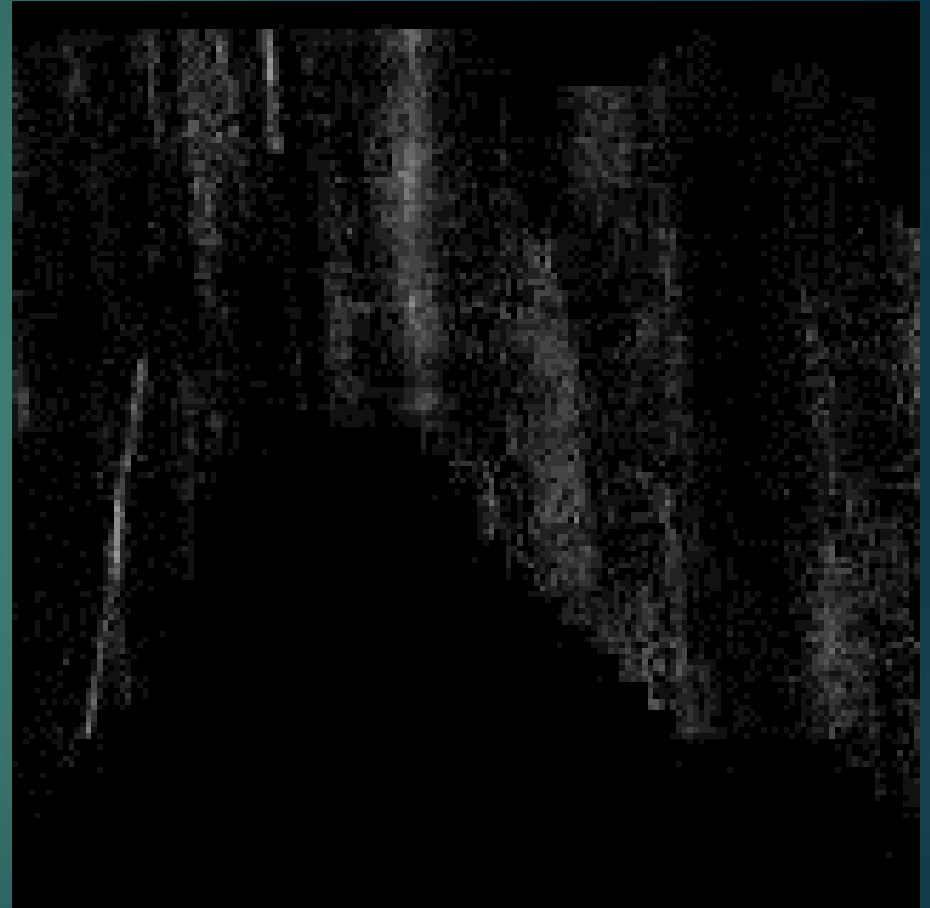
Detected rain

# ❖ Measuring Snow/Rain

## ➤ Demo



**Rain Video**



**Detected rain**

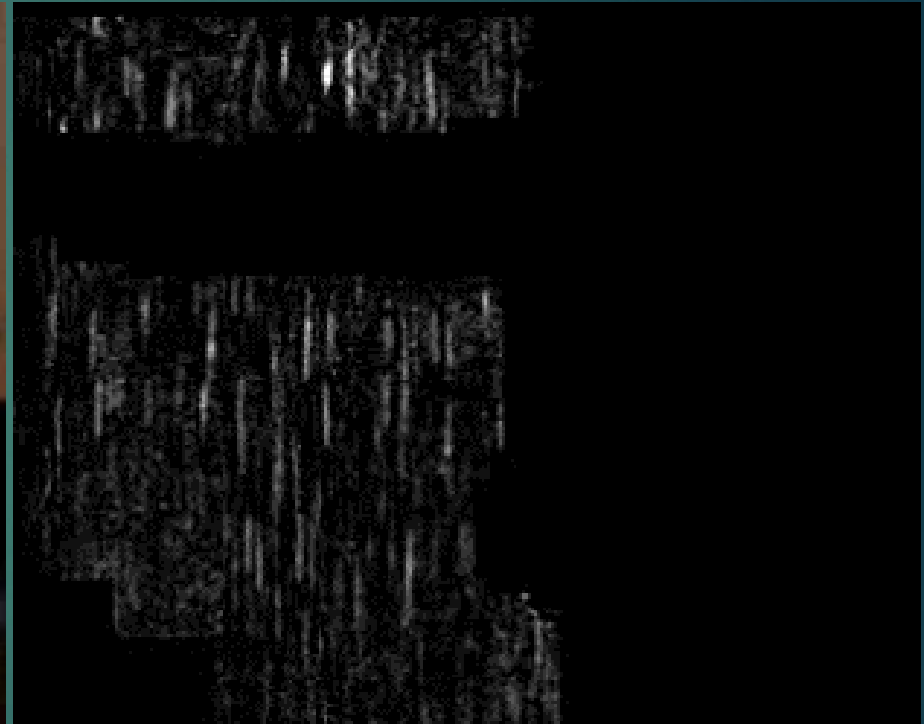


# ❖ Measuring Snow/Rain

## ➤ Demo



**Rain Video**



**Detected rain**

# ❖ Measuring Snow/Rain

## ➤ Demo



**Snow Video**



**Detected Snow**

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# Human activity recognition

- Human activity recognition is an important and challenging task for video analysis and understanding.

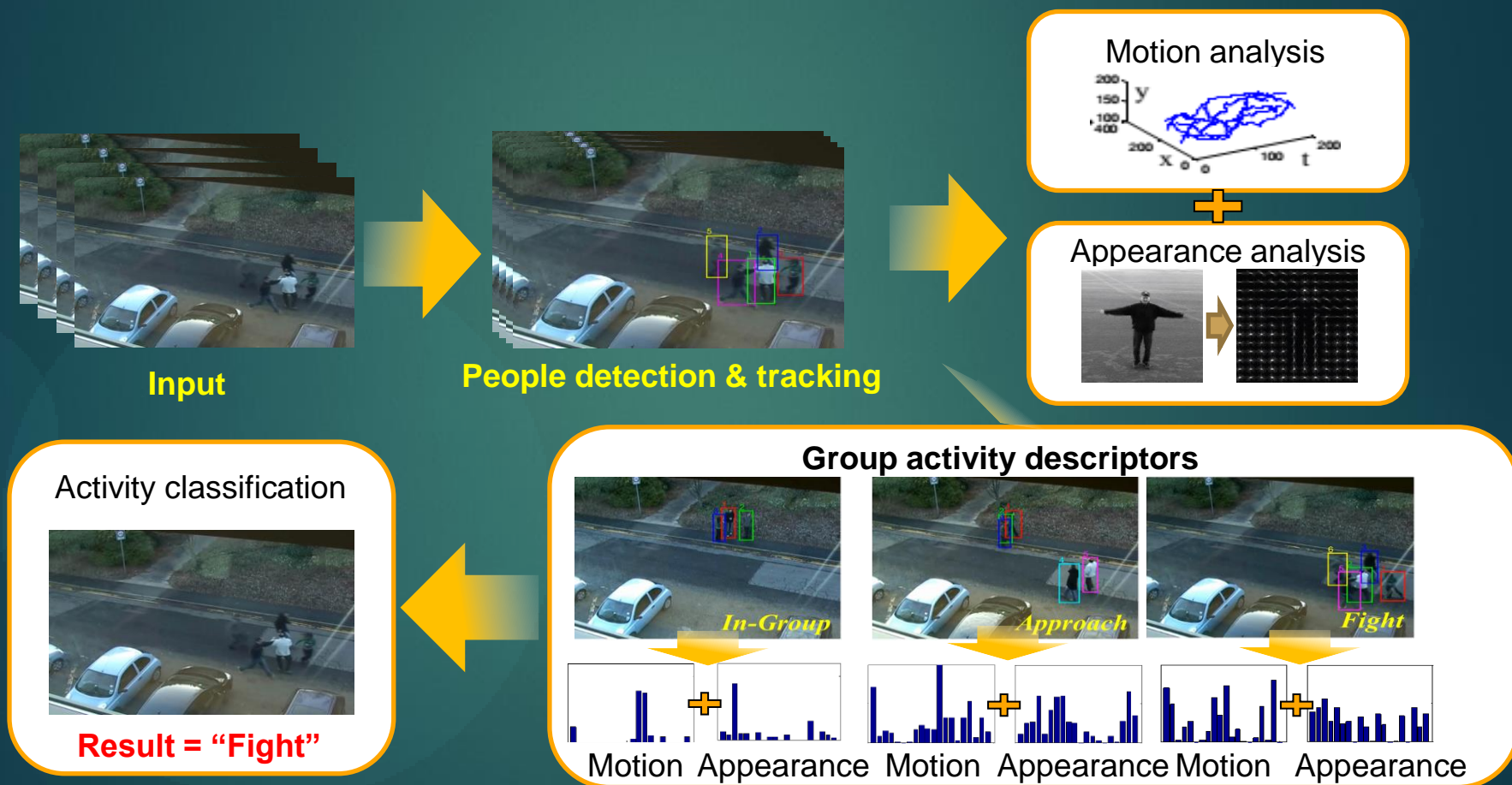


<Example of human activities >

- The analysis of group activity is of great practical importance for many applications.
  - smart video surveillance, semantic video indexing

# Human activity recognition

## ➤ Proposed approach



# Human activity recognition

## ➤ Motion-based Individual activity descriptor

- Average and variance of velocity

$$\bar{v}_i = \frac{1}{t_e - 1} \sum_{\tau=1}^{t_e-1} \|v_i(\tau)\|$$
$$\rho_i = \frac{1}{t_e - 1} \sum_{\tau=1}^{t_e-1} \left| \|v_i(\tau)\| - \bar{v}_i \right|^2$$

- $v_i(\tau) = s_i(\tau + 1) - s_i(\tau)$  : the velocity of  $i$ -th trajectory at frame  $\tau$
- It represents the intensity and variation of the movement

- Feature vector of motion-based Individual activity descriptor

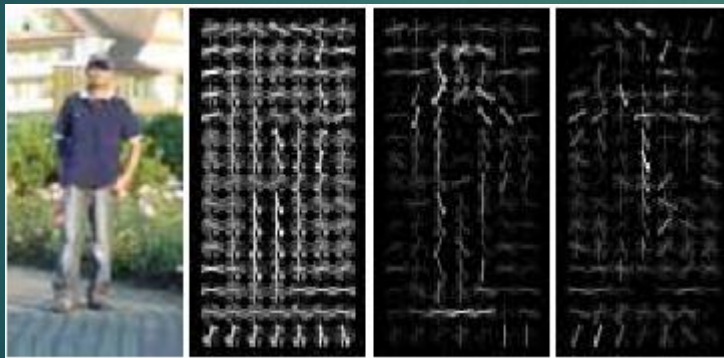
$$[\zeta_i, \bar{v}_i, \rho_i]$$

- $\zeta_i$  : the location change of  $i$ -th person
- $\bar{v}_i$  : the average velocity of  $i$ -th person
- $\rho_i$  : the variance of velocity for  $i$ -th person

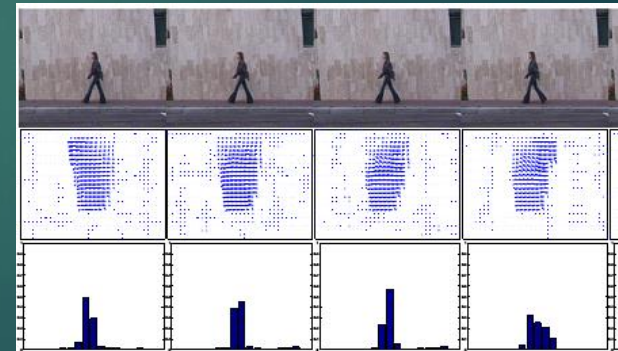
# Human activity recognition

## ➤ Appearance-based Individual activity descriptor

- Appearance information such as shape and local motion is also an important clue for recognizing group activity such as *fight*.
- Histograms of Oriented Gradients (HOG) & Histogram of Oriented Optical Flow (HOOF) has been employed
  - The sequences of HOG and HOOF features within the bounding box of each trajectory are extracted.



<HOG>



<HOOF>

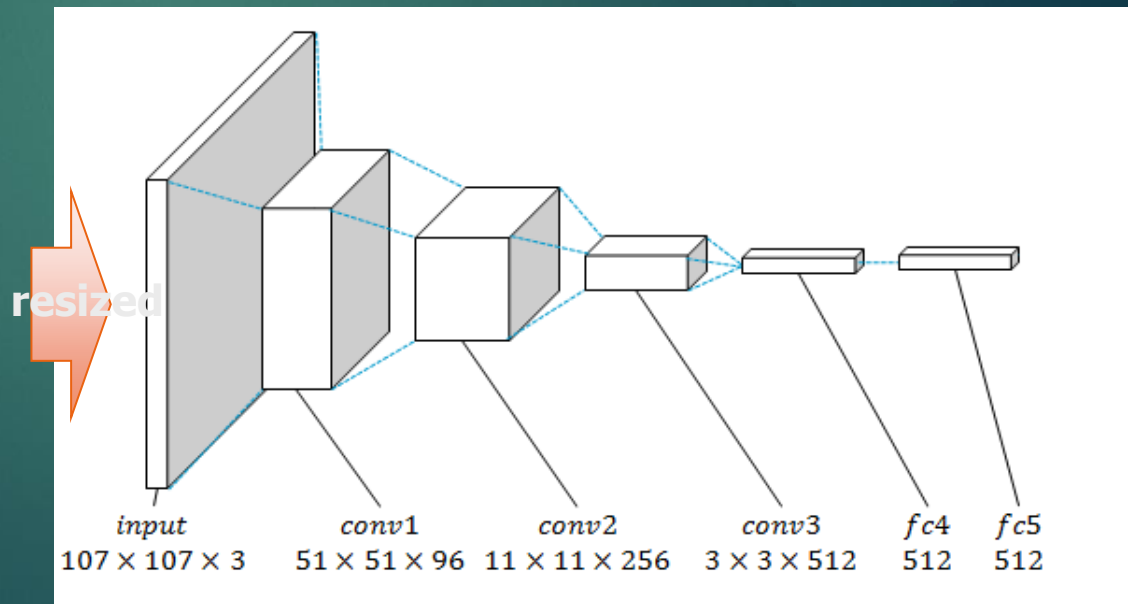
# Human activity recognition

## ➤ Appearance-based Individual activity descriptor

- Recently, deep learning based descriptors for effectively representing target appearance has been presented
- Appearance feature vector is compute by output of the proposed multi target network based on CNN



< Detection Results >

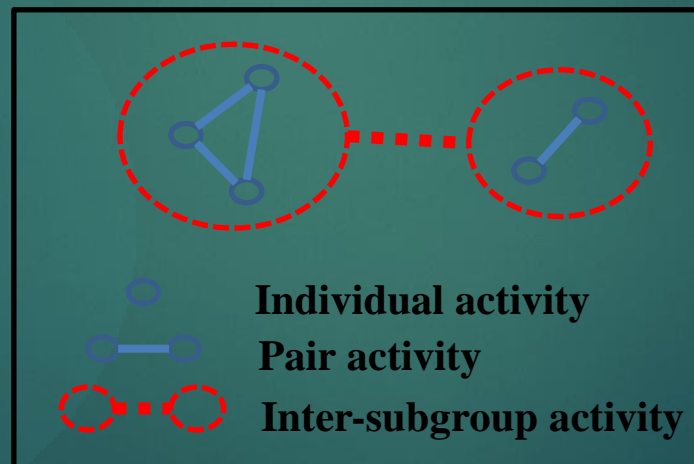


< Proposed multi-target CNN >

# Human activity recognition

## ➤ Group activity descriptor

- Group activity is regarded as a combination of subgroups and characterized by three types of activity descriptors
  - Descriptor type : “individual”, “pair”, “inter-subgroup”
  - These are complementary for analyzing group activity



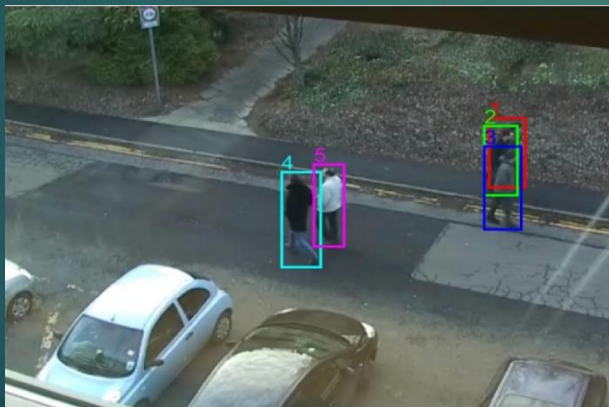
<Three types of group activities>



# Human activity recognition

## ➤ Group activity descriptor

- Consider the interactions between different sub-groups
- It is useful in complex situations with multiple group behavior such as *approach* or *split*.
- Individuals are clustered into non-overlapping sub-groups using the mean-shift clustering algorithm based on their position.
  - No need to determine the number of groups in prior



Sub-group clustering



# Human activity recognition

## ➤ Activity classification with group activity descriptors

- All activity description features are extracted and accumulated from the training video samples.
- For every type of features, the visual words are generated using K-means clustering.
- A multi-class SVM classifier are trained using a MKL method [5] which combines various types of these features and feed the mixture of the kernels to SVM.

[5] P. Gehler, S. Nowozin, “On feature combination for multiclass object classification”, ICCV, pp. 221–228, 2009

# Human activity recognition

## ➤ Demo



# ❖ Conclusions

- **Novel approaches to measure and forecast the impact of weather based on video analytics and image processing from fixed and moving CCTV are presented**
  - Methods to accurately measure the density of fog, rain and snow, respectively
  - Method to recognize the human activity utilizing deep appearance model and group activity descriptor
- **Proposed approaches can be applied to analyzing the impact of adverse weather**
  - Measuring and Forecasting the impact of weather on highway / street / in river / coast
  - Forecasting the impact of weather based on activity analysis of pedestrian

▶ Thanks for your attention!

Q & A