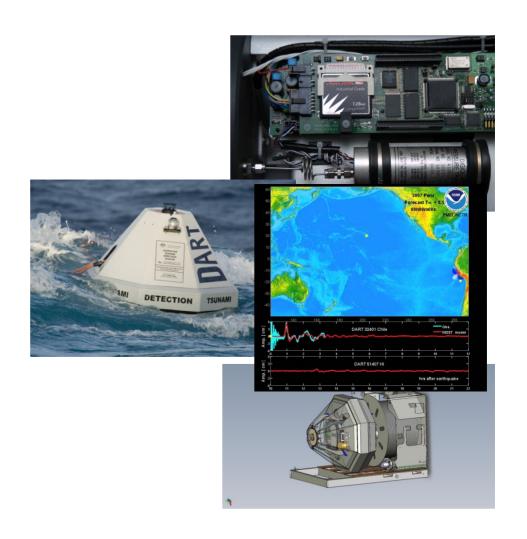
### Recent Tsunami Observations and Forecasts

Christian Meinig
Vasily Titov
Eddie Bernard
Scott Stalin
NOAA/PMEL

Ken Jarrott-AUS BOM

September28, 2008



# **Topics**

- Background
- Technology transfer
- Present state of technology and forecast system
- Future focus

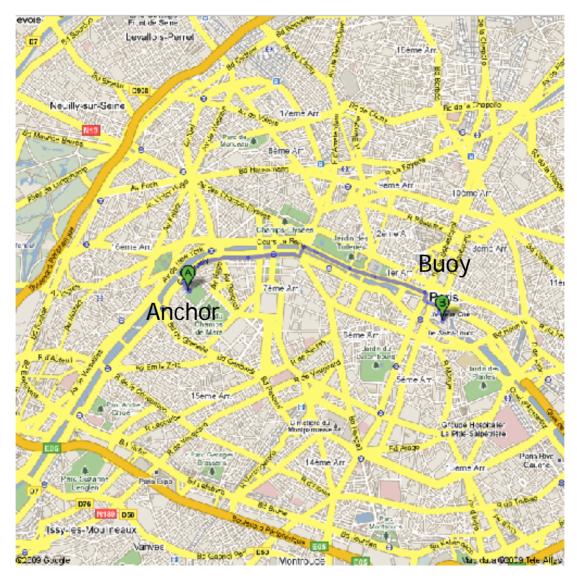
### Recent Technology Developments

- Novel 'self-deploy' mooring; designed for manufacture and safe, efficient operations
- Vandal Resistant, flexible design, low cost of ownership
- Robust acoustic modem integration and coms protocols
- Continuous Composite Mooring Line
  - (patented w/commercial partners)

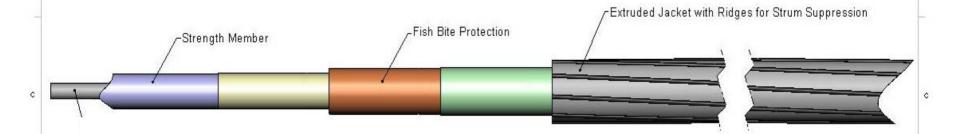
Transitioning to Industry w/commercial partner SAIC







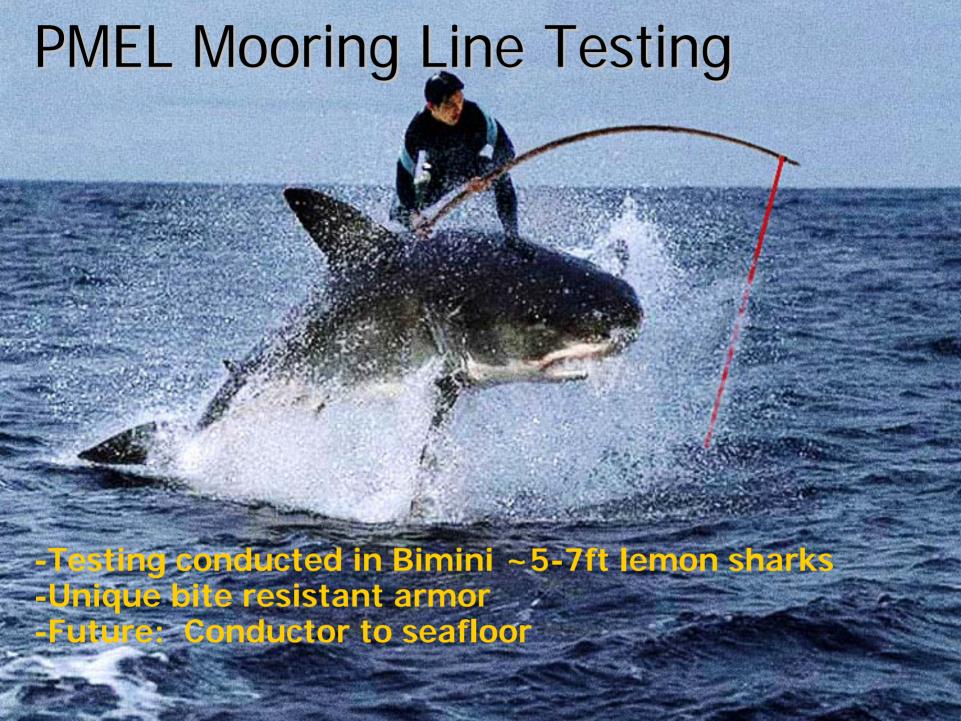
### Composite Mooring: Near Surface Component



#### Most Complicated Mooring Component

- Subjected to intense cyclic loading and bending
- Armored against fish bite

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### DART®-ETD

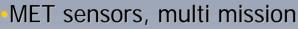
#### Features:

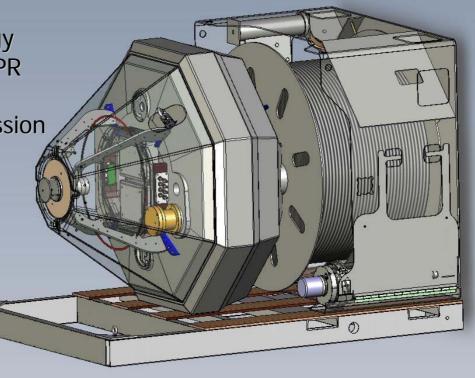
"Factory-built"

Transferable technology

~4 year expendable BPR

Designed for Conex







# Field Deployments

#### **Present Locations:**

North Pacific, Hawaii, New Zealand

Endurance testing: on-going

2.5 years+ Hawaii &

2.0 years+ North Pacific

#### Data Availability:

>92% in N. Pacific (>96% w/xducer mods)

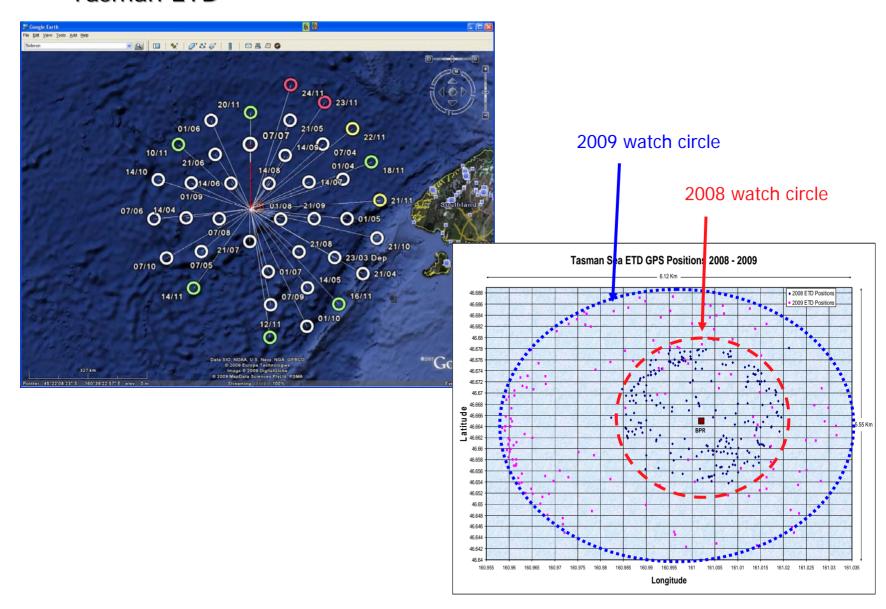
>94% in Hawaii

>74% in Southern Ocean\*\*\*



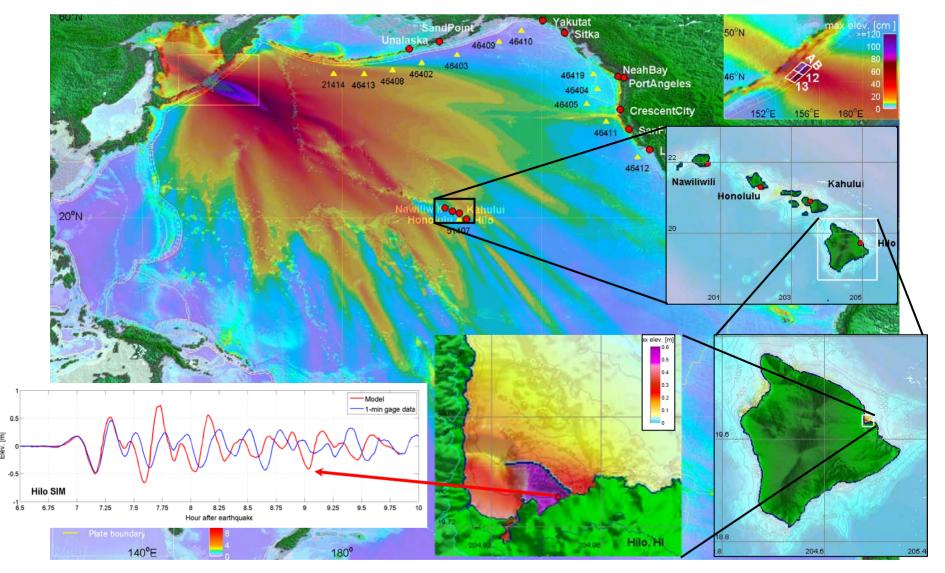
Tasman ETD March '08

# Affect of Watch Circle on Data Delivery Performance – Tasman ETD



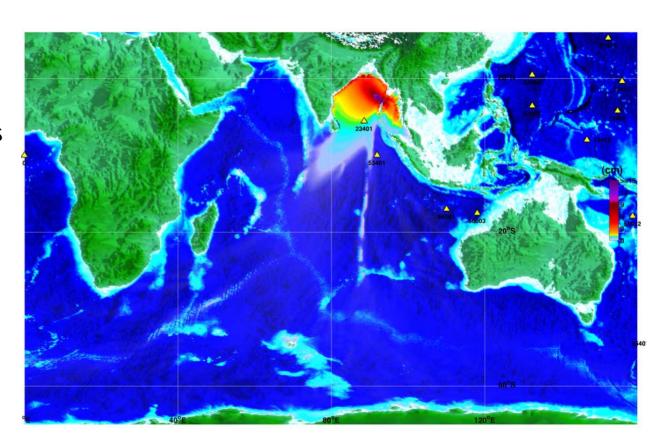
### Realtime Tsunami Forecasts

### November 15, 2006 Kuril Is. Tsunami



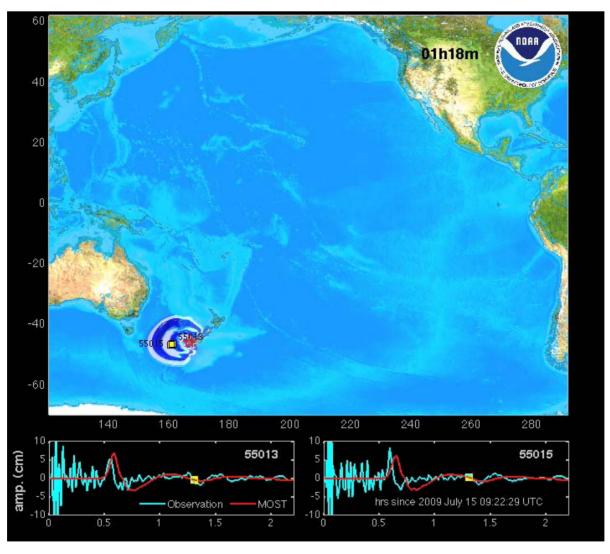
### Tsunami Forecast tests:

9 real-time tests10 data tests19 global test events



Andaman Aug 10, 2009 Tsunami

# Observation & model comparison example: July 15 Tsunami



### **Future Directions**

- Reducing cost of operations
- Continue to reduce size and life-cycle costs
  - -System→Sensor
- Continued mooring line and anchor/spool transition to industry
- Web-based realtime forecasts
- Potential use of mobile platforms such as Liquid Robotics Waveglider



Example: F/V SEA FALCON