Technical Aspects of the Canadian Wave Measuring Program

JCOMM Technical Workshop on Wave Measurements from Buoys – New York, U.S.A October 2 & 3, 2008

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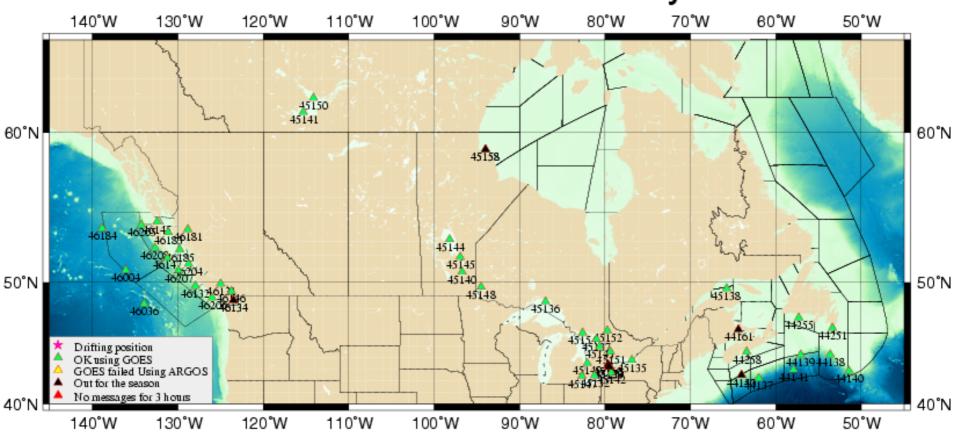


Canadian Buoy Network

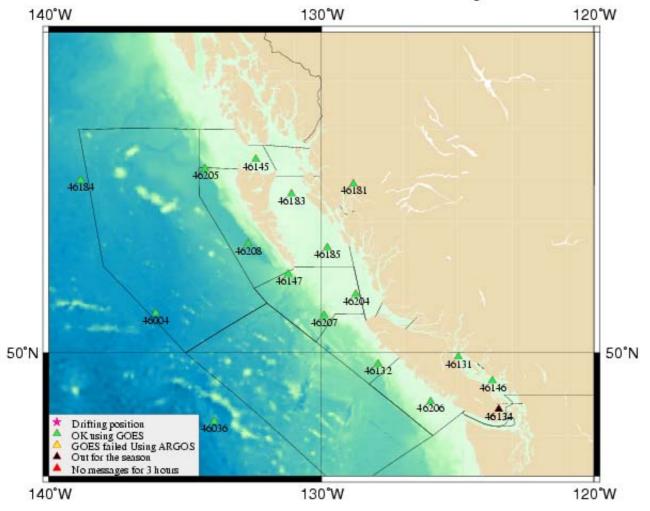
- Locations of Environment Canada Buoys
- Platform Types
- Mooring Types
- Sampling
- Processing

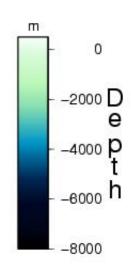


Canadian Moored Buoys

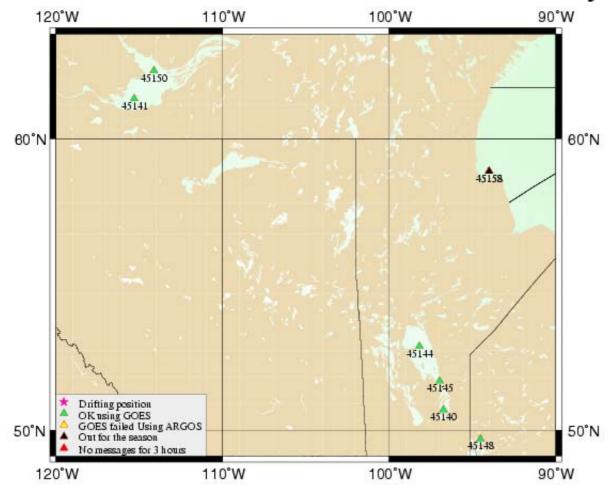


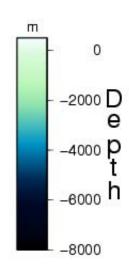
Pacific Moored Buoys

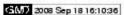




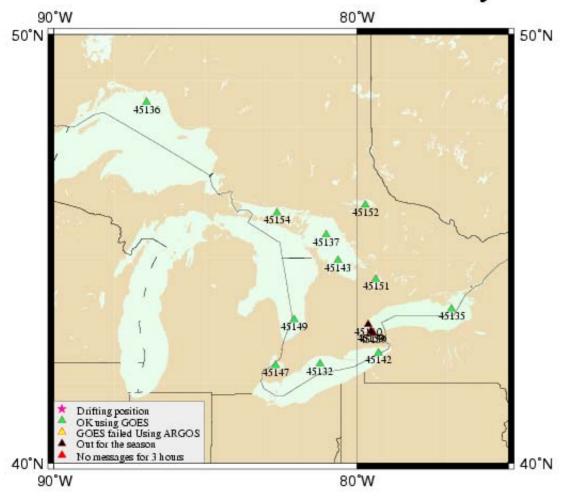
Prairies and the North Moored Buoys

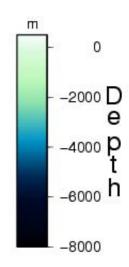


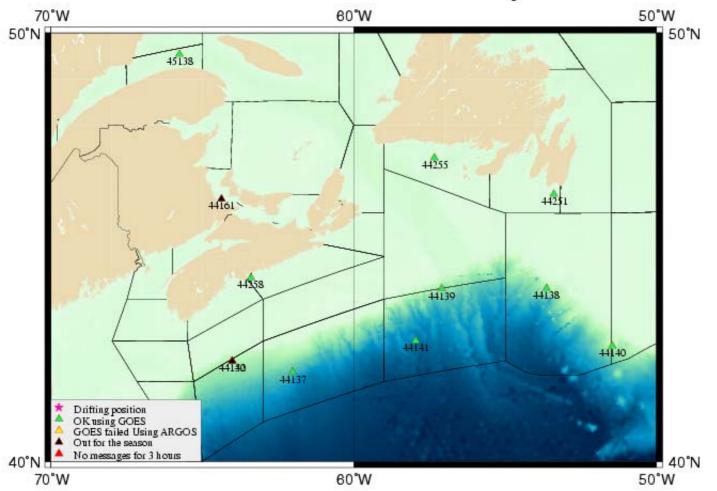


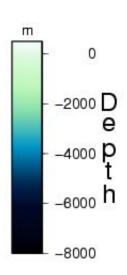


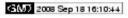
Great Lakes Moored Buoys



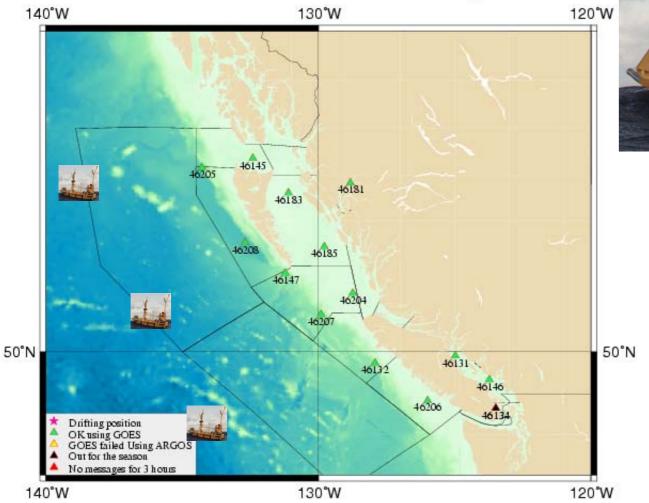




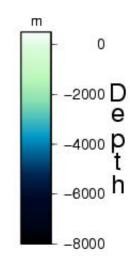




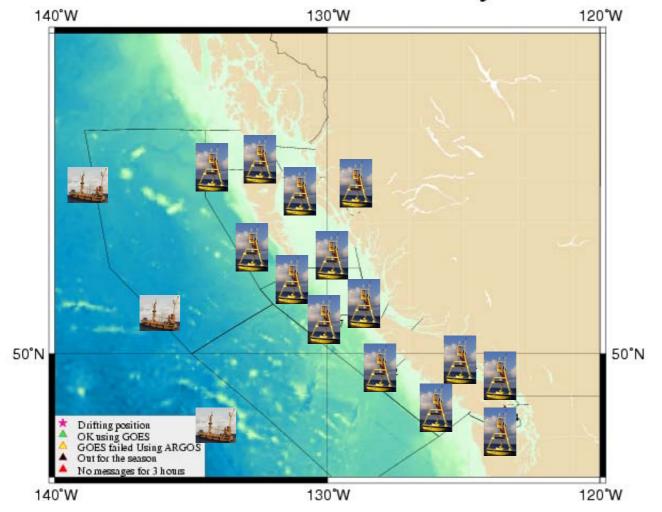
Pacific Moored Buoys



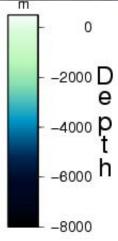




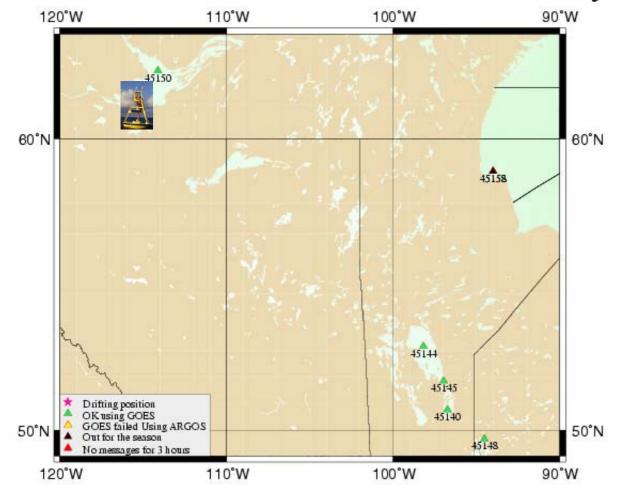
Pacific Moored Buoys

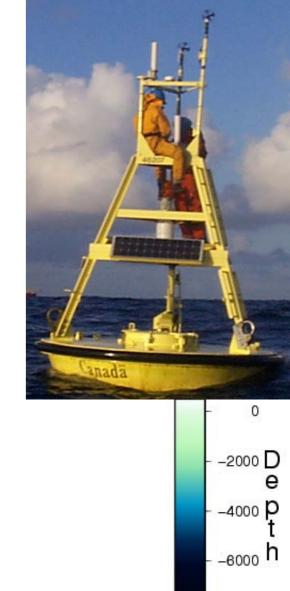




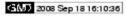


Prairies and the North Moored Buoys

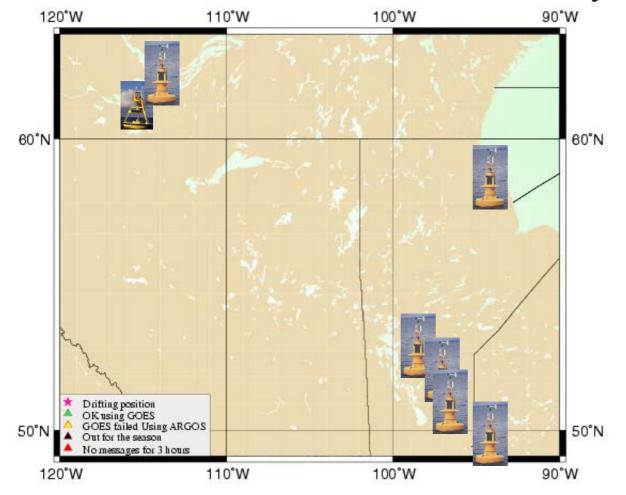




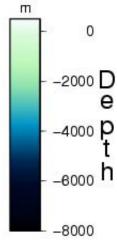
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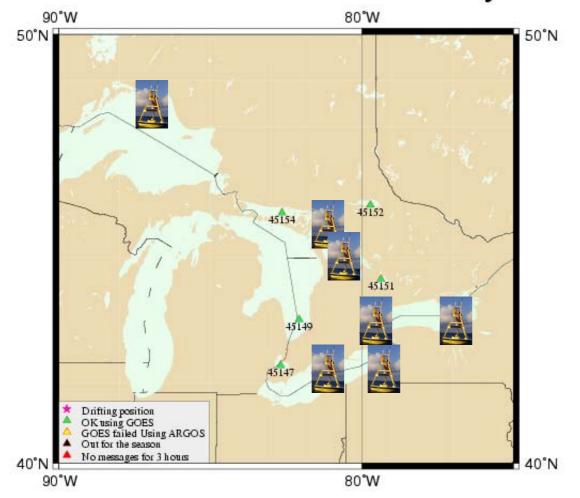
Prairies and the North Moored Buoys



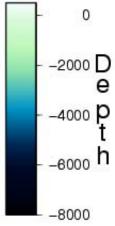




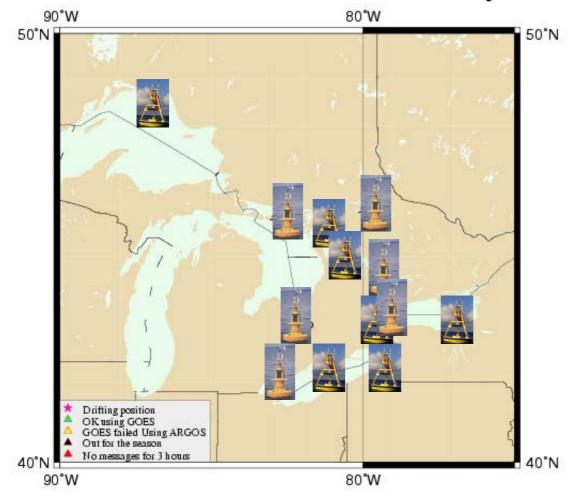
Great Lakes Moored Buoys



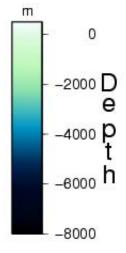


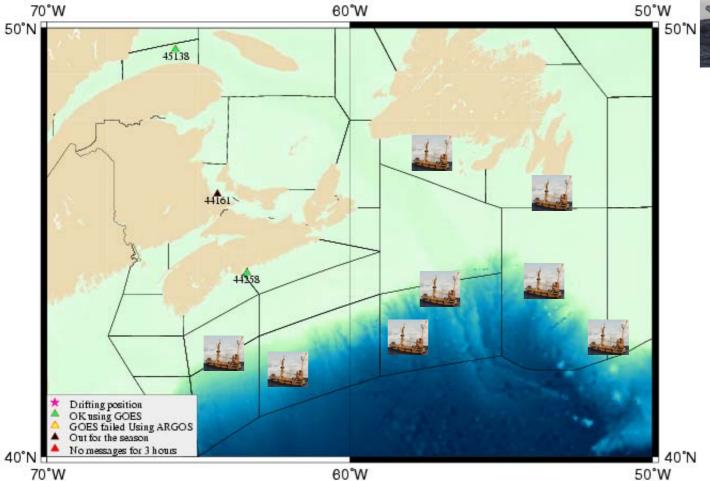


Great Lakes Moored Buoys

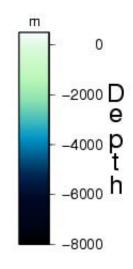


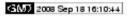


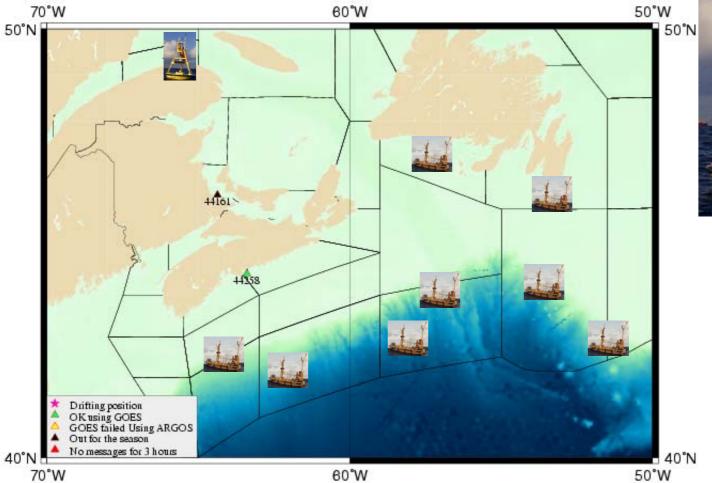




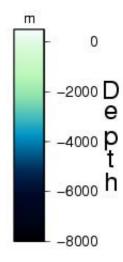


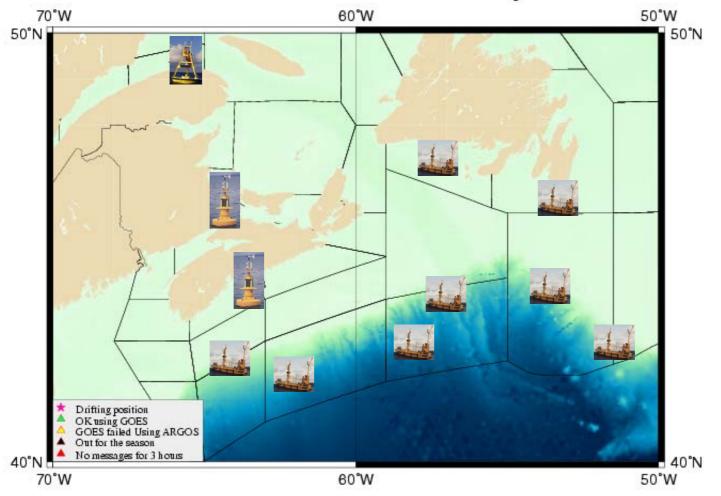




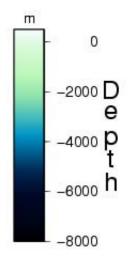












Watchman 100 Payload

- Components are similar on all buoys
- Layout differs with platform





Wave Sensors

- Strapped Down Accelerometer
 - Most Platforms
- TRIAXYS Direction Wave Sensor
 - Currently installed in two systems



Strapped Down Accelerometer



- Jewell LCF-200-2G
- Accelerometer
 Interface PCB
 converts
 acceleration to
 displacement
- ± 15m



TRIAXYS Direction Wave Sensor



- 3 Accelerometers
- 3 Rate Gyros
- Fluxgate Heading Sensor



TRIAXYS Direction Wave Sensor



Heave

Range: $\pm 20 \text{ m}$

Accuracy: better than 2%

Resolution: 1 cm

Period: 1.4 - 33 s

Wave Dir

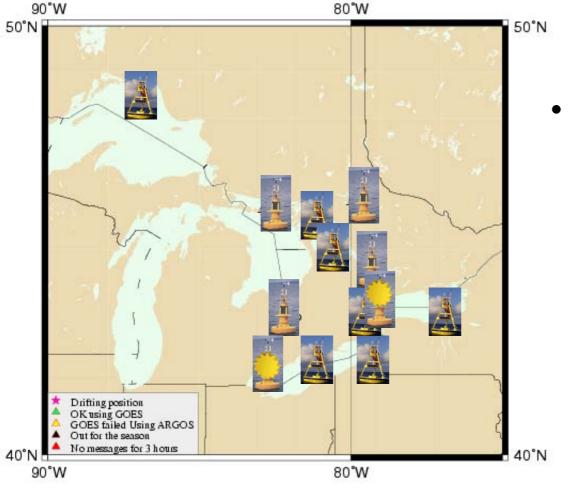
Range: 0 - 3600

Accuracy: ±1°

Period: 1.6 to 30 s



Great Lakes Moored Buoys

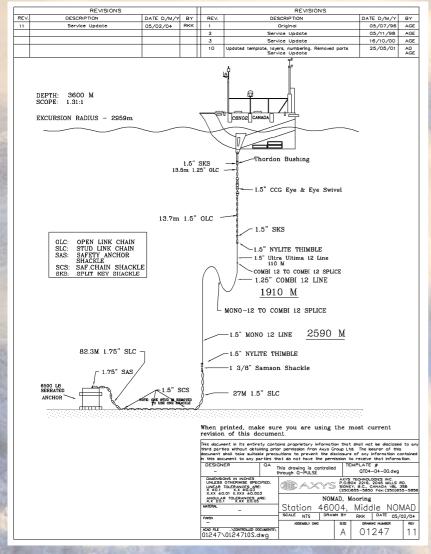


One Operational platform with a TRIAXYS sensor

 One platform with a TRIAXYS sensor logging data in addition to a Strapped Down Sensor

-2000 D

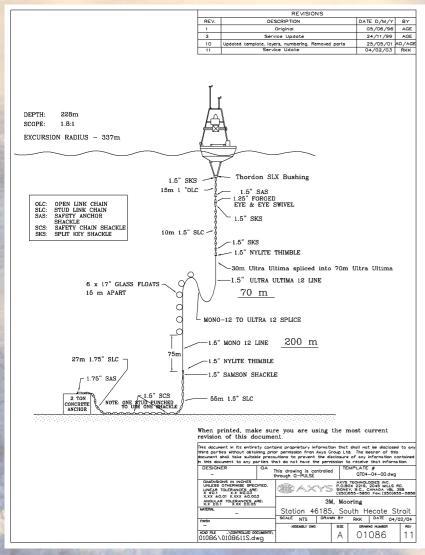
-4000 P



Deep Sea Mooring

- Typically 3500 m
- 2500m floating line
- 2000m sinking line

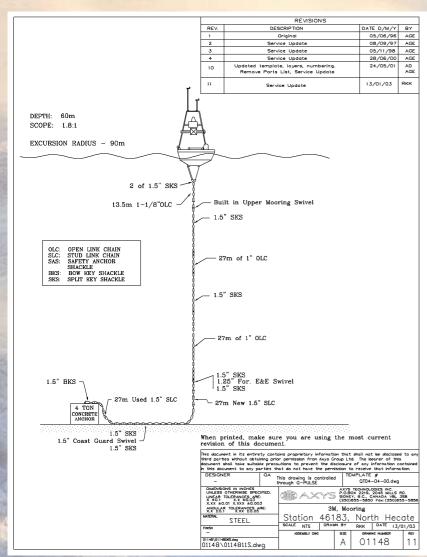




Coastal Deep Mooring

- Typically 200 m
- 200m floating line with extra floatation
- 100m sinking line

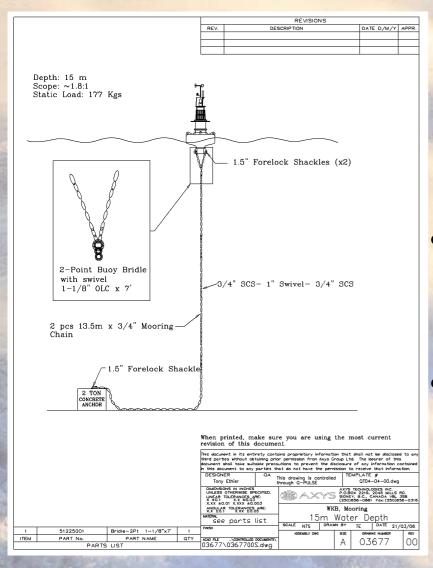




All Chain Mooring

• Less than ~100 m





Shallow WatchKeeper Mooring

- Shallow water presents special problems
- Trade off stability for wave following



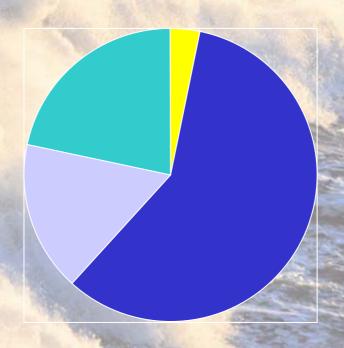
Sampling Scheme

- Different for two Wave Sensors since
 - Watchman samples and processes
 Strapped Down Sensor
 - TRIAXYS is a smart sensor



"Strapped Down" Data Acquisition Cycle

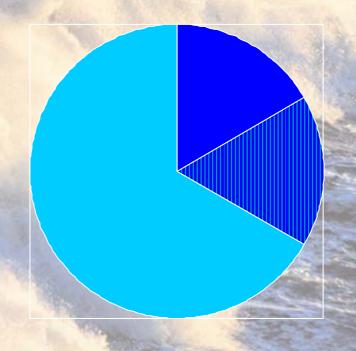
- 2 minute Wave Warm-up
- 35 minute Wave Sampling
- 10 minute Met Sampling
- 13 minute Sleep





"TRIAXYS" Data Acquisition Cycle

- 10 minute Wave
- 10 minute Wave & Met Sampling
- 40 minute Sleep





Watchman Wave Processing

- 8 * 256 one second samples taken
- Mean of the valid raw data is removed
- 10% cosine taper is applied
- FFT Calculated on the block
- Spectrum is Calculated
- Spectrum is corrected for the cosine taper
- Spectrum between 2 and 30 seconds is corrected for the transfer function of the heave sensor
- Band Averaging is done to reduce the number of spectral bands
- Hs and Tp are calculated (LFC is applied to shallow buoys)
- Results of the 8 blocks are averaged



TRIAXYS Wave Processing

- 4 Hz sampling
- 20 minute Sample
- Data processing is performed in the sensor by proprietary software developed by the Canadian Hydraulics Centre (CHC) of the National Research Council of Canada.
- Can be mounted off centre
- Raw data can be logged on board
- Results are read by the Watchman and formatted for GOES transmission





