New BATHY reporting code form

A new form of the BATHY code has been approved and will come into effect on 3 May, 2000. Everyone encoding observations into BATHY and decoding observations from BATHY should make the necessary software changes in time to send and receive this code form.

The new form is a slight modification of the present form. The only change is in the code form identifier and in the way latitudes and longitude are reported. Below is shown the complete code form with the changes highlighted in bold.

SECTION 1	M_iM_iM_jM j (i _u ddff)	YYMMJ (4snTTT)	GGgg/	$Q_cL_aL_aL_aL_aL_a$	LoLoLoLoLoLo
SECTION 2	8888k₁ DD)	$(k_5 D_c D_c V_c V_c))$		
SECTION 4	or 99999	$A_1 b_w n_b n_b n_b$			

Changes

- LaLa Latitude in tenths, hundredths and thousandths of a degree, depending on the capability of the positioning
- LaLa system. When the position is in tenths of a degree, the latitude position group shall be encoded as
- $L_a = Q_cL_aL_aL_a/$. When the position is in hundredths of a degree, the latitude position group shall be encoded as $Q_cL_aL_aL_aL_a/$.
- L_0L_0 Longitude in tenths, hundredths and thousandths of a degree, depending on the capability of the positioning
- L_oL_o system. When the position is in tenths of a degree, the longitude position group shall be encoded as
- $L_{o}L_{o} = L_{o}L_{o}L_{o}L_{o}L_{o}/.$ When the position is in hundredths of a degree, the longitude position group shall be encoded as $L_{o}L_{o}L_{o}L_{o}L_{o}L_{o}/.$
- M_iM_i Identification letters of the report. These remain JJ.
- M_jM_j Identification letters of the part of the report or the version of the code form. These becomes VV.

New TESAC reporting code form

A new form of the TESAC code has been approved and will come into effect on 3 May, 2000. Everyone encoding observations into TESAC and decoding observations from TESAC should make the necessary software changes in time to send and receive this code form.

The new form is a slight modification of the present form. There is a change in the code form identifier, in the way latitude and longitude is reported, and the addition of the instrument and recorder information now found in the current BATHY code form. Below is shown the complete code form with the changes highlighted in bold.

SECTION 1	MiMiMjMj (iuddff)	YYMMJ (4s _n TTT)	GGgg/	$Q_cL_aL_aL_aL_aL_a$	L _o L _o L _o L _o L _o L _o
SECTION 2	888k1k2	$\mathbf{I_{X}I_{X}I_{X}X_{R}X_{R}}$ $2z_{1}z_{1}z_{1}z_{1}$	$2z_0z_0z_0z_0$ $3T_1T_1T_1T_1$	3T₀T₀T₀T₀ 4S₁S₁S₁S₁	$4S_0S_0S_0S_0$
SECTION 4	(55555 DD	 2z _n z _n z _n z _n 1Z _d Z _d Z _d Z _d)	 d _n c _n c _n c _n		
SECTION 5	or 99999	$A_1 b_w n_b n_b n_b$			

Changes:

- I_XI_XI_X Instrument type used to make the observations (See BATHY code form).
- L_aL_a Latitude in tenths, hundredths and thousandths of a degree, depending on the capability of the positioning
- L_aL_a system. When the position is in tenths of a degree, the latitude position group shall be encoded as

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- $L_a \qquad Q_c L_a L_a L_a / . \label{eq:La} When the position is in hundredths of a degree, the latitude position group shall be encoded as Q_c L_a L_a L_a L_a / .$
- L_oL_o Longitude in tenths, hundredths and thousandths of a degree, depending on the capability of the positioning
- L_oL_o system. When the position is in tenths of a degree, the longitude position group shall be encoded as
- L_oL_o $L_oL_oL_oL_oL_o/$. When the position is in hundredths of a degree, the longitude position group shall be encoded as $L_oL_oL_oL_oL_oL_o/$.
- M_iM_i Identification letters of the report. These remain KK.
- M_jM_j Identification letters of the part of the report or the version of the code form. These becomes YY.
- X_RX_R Recorder type (See BATHY code form).
